Corrigendum to "a new strain energy function for the hyperelastic modelling of ligaments and tendons based on fascicle microstructure" [J. Biomech. 48: 290–297]

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$$\frac{\tau_1}{E} = \frac{1}{\theta_o^2} \left(\frac{2\sqrt{\epsilon(\epsilon+2)}}{\cos^{-1}(\epsilon+1)} - \frac{1}{(\cos^{-1}(\epsilon+1))^2} - 2\epsilon \right)$$
(30)

$$\frac{\hat{\tau}_2}{E} = \frac{1}{2\sin\theta_o} \left(\frac{\epsilon+1}{\sin^{-1}((\epsilon+1)/\sqrt{\epsilon(\epsilon+2)})} - \frac{\sqrt{\epsilon(\epsilon+2)}}{\epsilon+1} \right)$$
(34)

$$\frac{\hat{\tau}_1}{E} = 2 \int_0^1 ((\epsilon + 1)\cos(\hat{\theta}_1(\rho)) - 1)\rho \ d\rho, \quad \beta = \frac{2(1 - \cos^3 \theta_o)}{3\sin^2 \theta_o}$$
(35)

None of the following results were affected by these errors.