

# Timeline of Developments in Algorithms for Finding Correspondences across Sets of Shapes and Images

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This document lists some of the key papers in the developments of methods for finding correspondences across sets of shapes or images.

It concentrates on methods which assume no ordering of the images, and that the images are of different objects (thus we don't include work in the tracking or multi-view reconstruction literature).

We classify the methods into those that work on shapes (curves or surfaces) and those that work on image regions (in 2D or 3D). Typically the shape based methods control points constrained to lie on the shape, whilst the image methods control points moving anywhere, but constrained by the image intensities in some way.

We also highlight *pairwise* methods, in which correspondences across the set are found by performing a sequence of individual pairwise correspondences to optimise a pairwise function, and *groupwise* methods which explicitly aim to optimise a function defined on the whole set of shapes/images.

This distinction is actually somewhat blurred, because some of the explicitly pairwise methods actually end up optimising some (implicit and usually unstated) groupwise objective function. We assign the noble title of groupwise to those explicitly optimising a groupwise function (though it may be done in some pairwise manner).

This is a first draft, so may miss out some relevant work - if you think something significant is missing, please contact the author.

Year	Shape Correspondences	Region Correspondences
1994	Hill corresponds sets of shapes by pairing and merging, then refines each using the resulting shape model [1]	
1995	Baumberg iteratively refines crude correspondences across a set of closed curves modelled with B-splines	
1996	Greedy pairwise scheme [2]	
1997	Groupwise objective function (product of eigenvectors of covar) used for corresponding 2D shapes [3] Use of diffeomorphisms for shape alignment [3] Ramsay and Silverman: Functional Data Analysis book (apply diffeomorphisms to 1D functions to align them) [7]	‘Morphable Models’ use optical flow techniques to correspond 2D regions and build models[4, 5, 6]
1999	Brett <i>et.al.</i> use a pairwise method to correspond 3D surfaces [8]	Transformed Component Analysis allows translation of images before PCA, so as to optimise a suitable function [9] Salient features detected across a sequence used to automatically build appearance models [10]
2000	Shelton corresponds surfaces using an elastic deformation type technique, then refines the model iteratively. Applies to 2D images and 3D surfaces. [11]	
		Miller <i>et.al.</i> [12] introduce ‘congealing’ approach (maximising entropy on a per-pixel basis) and applies it to groupwise affine alignment.
2001	Minimum Description Length objective function for groupwise correspondences of shapes [13, 14] <sup>1</sup> [15].	De la Torre [16] represents a face as a set of fixed shape regions which can move independently. Optimal locations are found by minimising a measure related to the total variance of the eigenmodels.
	Belongie <i>et.al.</i> use ‘shape context’ and thin plate splines to correspond shapes [17]  3D shapes corresponded by using non-rigid registration of sets of binary label images (one for each part) [19, 20]	Rueckert <i>et.al.</i> use non-rigid registration to correspond 3D images and build statistical shape models [18]
2002	MDL applied to 3D shapes [21]	In a technical report Cootes <i>et.al.</i> propose a framework for groupwise diffeomorphic correspondence to build appearance models [22]
2003	Review of some 2D MDL methods [23]. Thodberg and Olafdottir add curvature measures to MDL [24]	In a technical report, Baker and Matthews propose minimising a groupwise measure to build optimal appearance model [25]
	Ericsson and Åström use cunning maths for a steepest descent version of MDL shape matching [26]	Jebara corresponds sets of images by treating pixels as 3D vectors. Optimises a groupwise function using quadratic programming [27]
2004		Cootes <i>et.al.</i> [28] describe an algorithm for groupwise diffeomorphic registration. Joshi <i>et.al.</i> [29] perform groupwise diffeomorphic registration onto an evolving estimate of the mean image.

<sup>1</sup> The details of the MDL theory in these papers is slightly flawed, the interested reader should refer to [21, 15].  
Note: This is incomplete - I need to add more stuff to it!

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