

sea similar

AI  $\pi = 2C_{20} - C_{70} + C_{50} \quad \downarrow$

$$\pi(t=T) = 2 \max(S-20, 0)$$

$$- \max(S-30, 0)$$

$$+ \max(S-50, 0) \quad \textcircled{3}$$

If  $0 < S < 20$

$$\pi = 0$$

$$P_{50} = \text{~~200~~ } 50 - S > \pi \quad \textcircled{3}$$

If  $20 < S < 30$

$$\pi = 2S - 40$$

$$\left( \begin{array}{c} s=20 \\ 0 < \pi < 20 \\ s=30 \end{array} \right)$$

$$P_{50} = 50 - S$$

$$\left( \begin{array}{c} 20 < \pi < 30 \\ s=30 \qquad \qquad s=20 \end{array} \right)$$

$$\Rightarrow P_{50} \geq \pi \quad \textcircled{3}$$

If  $30 < S < 50$

$$P_{50} = 50 - S$$

$$(20 < P_{50} < 0)$$

$$\pi = -S + 50$$

$$(20 > \pi > 0)$$

$$\Rightarrow P_{50} = \pi \quad \textcircled{3}$$

③

$$\text{If } S > 50$$

$$P_{50} = 0$$

$$\pi = 0$$

$$\Rightarrow P_{50} = \pi$$

②

③

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A (i) <sup>no arbitrage</sup>  $F = S e^{rT}$  (semi-class)  $\angle$

$$= 10. e^{+0.75 \times 0.05}$$

$$= \$10.382 \quad (5)$$

(ii) A ft 6 month

$$25 \text{ } \& \text{ } e^{0.5 \times 0.025} = 25.031$$

(5)

Then

$$25.031 \cdot e^{0.5 \times 0.04} = 25.5366$$

- extension of (i) - no arbitrage

(iii)  $F = 31500 \cdot e^{0.5 \times (0.1 + 0.04)}$

$$= 33784$$

storage not seen before  
- unseen (no arbitrage)

(5)

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A7 <sup>see si-ih</sup> (1)  $\pi = 2S - P(S, X)$   $\ll$

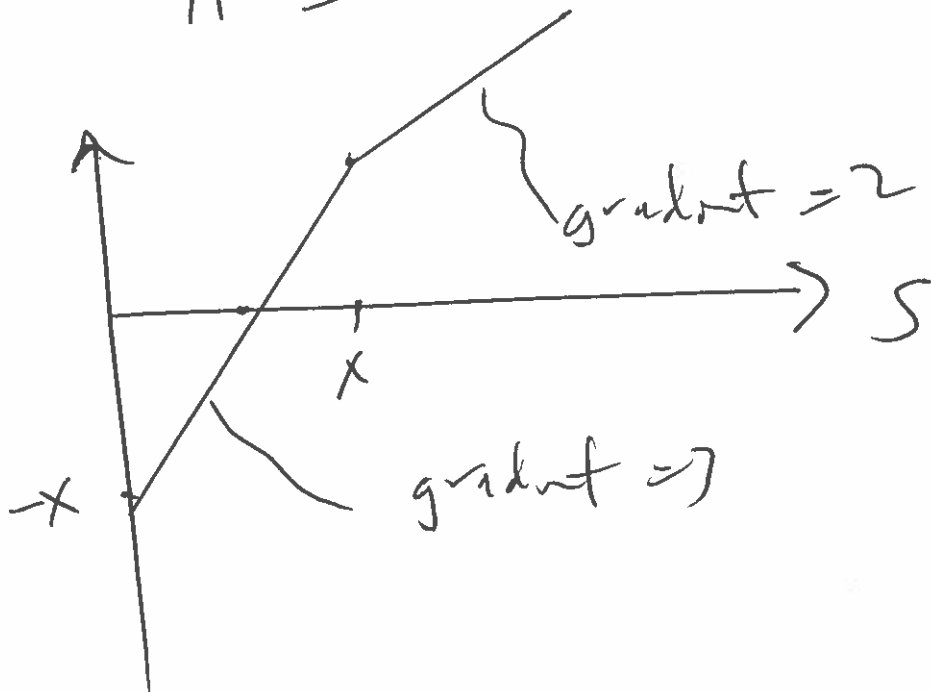
$$\pi(t = \pi) = 2S - \max(X - S, 0)$$

If  $0 < S < X$

$$\pi = 2S - X + S = 3S - X$$

If  $S > X$

$$\pi = 2S$$



I

$$(ii) \quad \pi = 5 - 2p(x_1) + (x_2)^2$$

$$\pi(t=\pi) = 5 - 2 \max(x_1 - s, 0) + \max(s - x_2, 0)$$

$$\text{if } x_1 > x_2$$

$$\text{if } 0 < s < x_2$$

$$\pi = 5 - 2(x_1 - s) = 3s - 2x_1$$

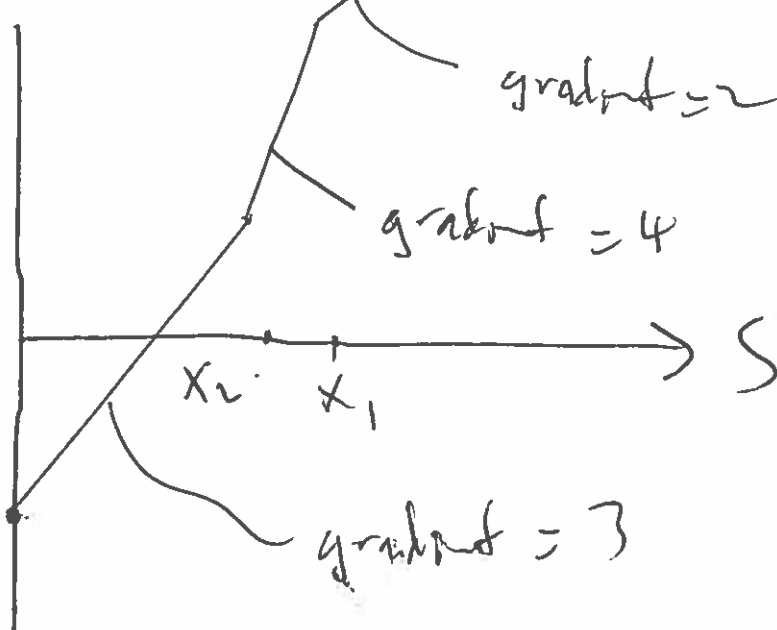
$$\text{if } x_2 < s < x_1$$

$$\pi = 5 - 2(x_1 - s) + (s - x_2)$$

$$= 4s - 2x_1 - x_2$$

$$\text{if } x_1 < s$$

$$\pi = 5 + s - x_2 = 2s - x_2$$



4

$$\text{If } x_1 = x_2 = x$$

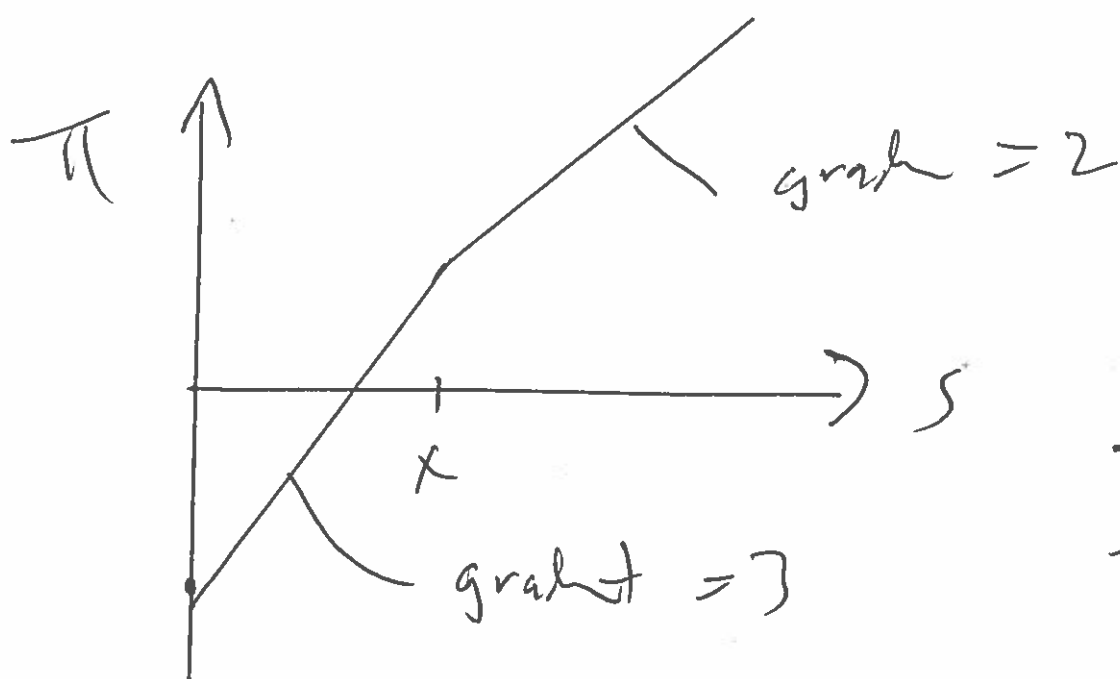
B

$$\text{If } 0 < s < x$$

$$\pi = s - 2(x - s) = 3s - 2x$$

$$\text{If } x < s$$

$$\pi = s + (s - x) = 2s - x$$



4

$$\text{If } x_2 > x_1$$

$$\text{If } 0 < s < x_1$$

$$\pi = s - 2(x_1 - s) = 3s - 2x_1$$

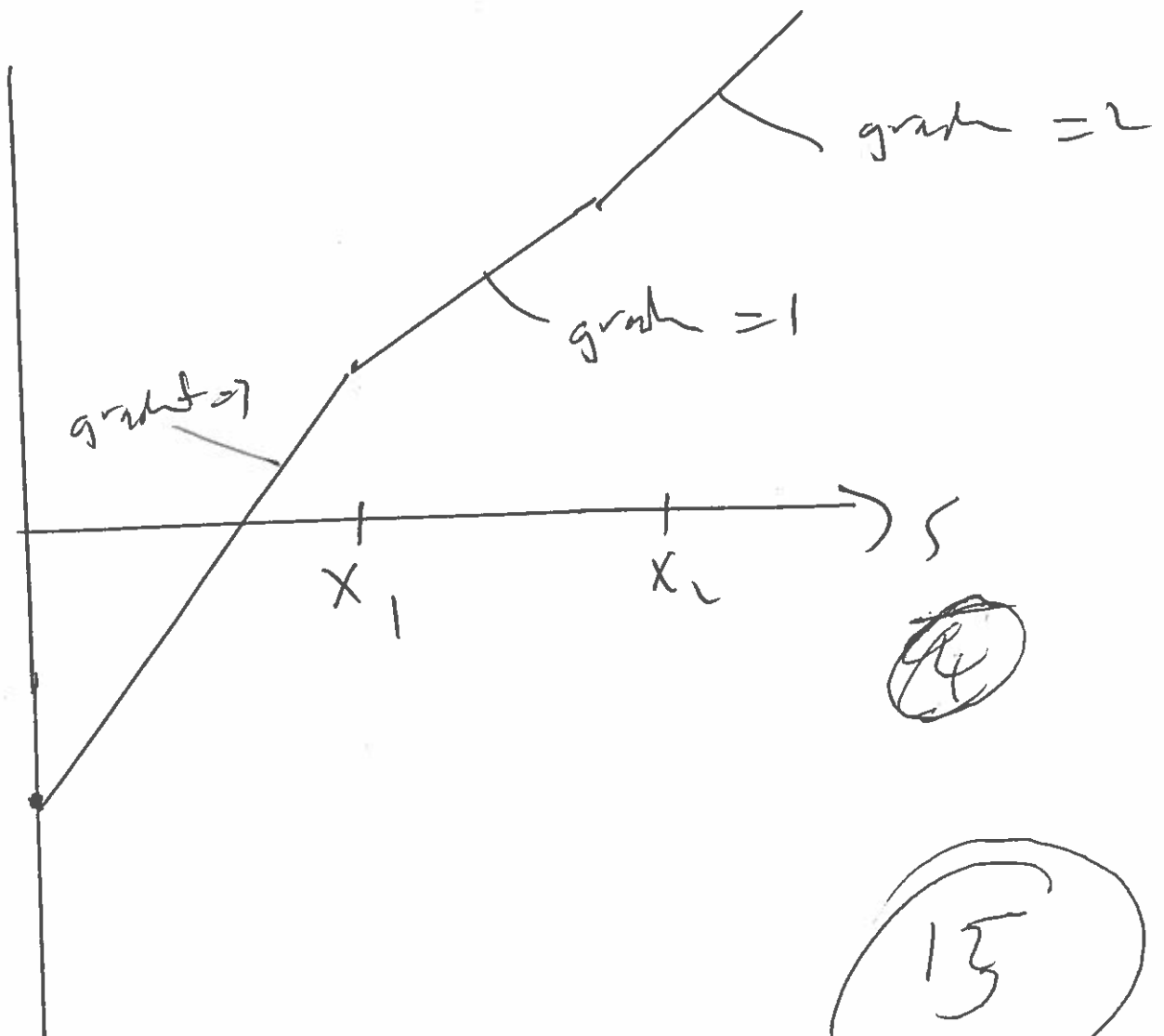
$$\text{If } x_1 < s < x_2$$

(4)

$$\pi = s$$

$$\text{If } s > x_2$$

$$\pi = s + s - x_2 = 2s - x_2$$



~~AY~~ / F  
(i)

$$P = AS^\alpha$$

(i) see similar  
(ii), (iii) use

$$\frac{1}{v} \sigma^2 \alpha (\alpha - 1) + r \alpha - r = 0$$

$$\alpha^2 \left( \frac{1}{v} \sigma^2 \right) + \alpha \left( r - \frac{1}{v} \sigma^2 \right) - r = 0$$

$$\alpha = 1, -2r/\sigma^2$$

(4)

(ii)

On

$$S = S_f$$

$$P(S = S_f) = e^{-\lambda S_f} \quad (2)$$

$$\frac{dP}{dS} (S = S_f) = -\lambda e^{-\lambda S_f} \quad (2)$$

smooth  
past

$$P(S \rightarrow \infty) \rightarrow 0 \quad (2)$$

(iii)

$$A S_f^\alpha = e^{-\lambda S_f}$$

$$\alpha = -\frac{2r}{\sigma^2}$$

$$\alpha A S_f^{\alpha-1} = -\lambda e^{-\lambda S_f}$$

$$\frac{S_f}{\alpha} = -\frac{1}{\lambda} \Rightarrow S_f = -\frac{\alpha}{\lambda}$$

$$S_f = \frac{2r}{\sigma^2 \lambda} \quad (5)$$

KS



BS (i).  $dv = \frac{\partial v}{\partial s} ds + \frac{1}{2} \frac{\partial^2 v}{\partial s^2} ds^2 + \frac{\partial v}{\partial t} dt + \dots$

$E[ds^2] = \sigma^2 dt$  2

$dv = \left( \frac{\partial v}{\partial t} + \frac{1}{2} \sigma^2 \frac{\partial^2 v}{\partial s^2} \right) dt + \frac{\partial v}{\partial s} ds$

see similar

$\pi = v - \Delta S$ ,  $d\pi = dv - \Delta ds$

choose  $\Delta = \frac{\partial v}{\partial s}$  2

$d\pi = \left( \frac{\partial v}{\partial t} + \frac{1}{2} \sigma^2 \frac{\partial^2 v}{\partial s^2} \right) dt$  risk free

If no arbitrage  $d\pi = [r\pi] dt$

$\Rightarrow \frac{\partial v}{\partial t} + \frac{1}{2} \sigma^2 \frac{\partial^2 v}{\partial s^2} + rS \frac{\partial v}{\partial s} - rV = 0$

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(ii) If  $1 = \sigma - S$  (2)

$$\frac{\partial v}{\partial t} + \frac{\sigma^2}{2} S^2 \frac{\partial^2 v}{\partial S^2} + r S \frac{\partial v}{\partial S} - r v = 0$$

If  $v = S^{-1} f(t)$

$$f' + \sigma^2 f + 2r f - r f = 0$$

$$f' + (\sigma^2 + r) f = 0 \quad f(T) = 1$$

$$f = \exp \left[ \int_t^T (\sigma^2 + r) dt \right]$$

$$v = S^{-1} \exp \left[ \int_t^T (\sigma^2 + r) dt \right] \underline{\underline{S}}$$

(iii)  $v = S^{-1} f_1(t) + f_2(t)$

~~mix~~

$$\frac{\partial v}{\partial t} + \frac{\sigma^2}{2} \frac{\partial^2 v}{\partial S^2} + r S \frac{\partial v}{\partial S} - r v = 0$$

$$f_1' + 2r f_1 - r f_1 = 0$$

$$f_1(T) = 1 \Rightarrow f_1 = \exp[r(T-t)]$$

$O(S^4)$

$$O(S^0) \quad f_1' + \sigma_1^2 f_1 - r f_2 = 0 \quad \square$$

$$f_1 = A e^{rt} + \alpha e^{-rt}$$

$$-2r e^{-rt} \alpha = -\sigma_1^2 e^{r(T-t)}$$

$$\alpha = \frac{\sigma_1^2}{2r} e^{rT}$$

$$f_1 = A e^{rt} + \frac{\sigma_1^2}{2r} e^{r(T-t)}$$

unseen

$$\text{But } f_1(T) = 0$$

$$A = -\frac{\sigma_1^2}{2r} e^{-rT}$$

$$\checkmark f_1 = \frac{\sigma_1^2}{2r} \left[ e^{r(T-t)} - e^{-r(T-t)} \right]$$

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(20)

BL (i) If  $v = e^{-D(T-t)} V_1(S, t)$

seen in class

$$D V_1 + \frac{\partial V_1}{\partial t} + \frac{1}{2} \sigma^2 S^2 \frac{\partial^2 V_1}{\partial S^2} + (r - D) \frac{\partial V_1}{\partial S} - r V_1 = 0$$

$$\Rightarrow \frac{\partial V_1}{\partial t} + \frac{1}{2} \sigma^2 S^2 \frac{\partial^2 V_1}{\partial S^2} + (r - D) \frac{\partial V_1}{\partial S} - (r - D) V_1 = 0$$

$$\Rightarrow \text{BSDE, with } r \rightarrow r - D$$

(50)

$$C_d = e^{-D(T-t)} S N(d_{10}) - e^{-r(T-t)} N(d_{20})$$

$$d_{10} = \frac{\log(S/X) + (r - D + \frac{1}{2}\sigma^2)(T-t)}{\sigma \sqrt{T-t}}$$

$$d_{20} = \frac{\log(S/X) + (r - D - \frac{1}{2}\sigma^2)(T-t)}{\sigma \sqrt{T-t}}$$

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(iii) ~~for~~  $T-t = 0.75$

(2)

$$D = 0.05$$

$$\sigma = 0.2$$

$$r = 0.015$$

$$X = 51, S = 50$$

$$d_{10} = -0.17928, d_{20} = -0.752$$

$$N(d_{10}) = 0.42885$$

$$N(d_{20}) = 0.76223$$

~~10~~ 10 minutes

$$C_d = 2.786295$$

~~8~~ 8

↑ see strike  
↓

(iv)  $C_1 = C_1 e^{-D(T-t)}$

$$P_1 = P_1 e^{-D(T-t)}$$

$$C_1 + X e^{-(r-D)(T-t)} - P_1 - S = 0$$

$$e^{D(T-t)} C_d + X e^{-(r-D)(T-t)} - e^{D(T-t)} P_d - S = 0$$

$$(C_d + X e^{-r(T-t)} - P_d - S e^{-D(T-t)}) = 0$$

↑ see strike  
↓

~~4~~ 4

Pl (i)  $ds_i = \mu_i s_i dt + \sigma_i s_i dw_i$  (1)

→ geometric Brown motion

ser  
sit-1m → changes in  $s_i$  linked to magnitude of  $s_i$   $\frac{dw_i^2}{dt} = 1$

→  $s_i$  cannot go negative  $\frac{dw_i^2}{dt} = 1$

(ii)  $d\pi = dV - \Delta_1 ds_1 - \Delta_2 ds_2$

$$= \left[ \frac{\partial V}{\partial t} dt + \frac{\partial V}{\partial s_1} ds_1 + \frac{\partial V}{\partial s_2} ds_2 \right.$$

$$+ \frac{1}{2} \frac{\partial^2 V}{\partial s_1^2} ds_1^2 + \frac{1}{2} \frac{\partial^2 V}{\partial s_2^2} ds_2^2$$

$$\left. + \frac{\partial^2 V}{\partial s_1 \partial s_2} ds_1 ds_2 \right]$$

$$- \Delta_1 [\mu_1 s_1 dt + \underbrace{\sigma_1 s_1 dw_1}]$$

$$- \Delta_2 [\mu_2 s_2 dt + \underbrace{\sigma_2 s_2 dw_2}]$$

similar on st. sheets

$$= \frac{\partial V}{\partial t} dt + \frac{\partial V}{\partial S_1} [K_1 S_1 dt + \sigma_1 S_1 dW_1] (2)$$

$$+ \frac{\partial V}{\partial S_2} [K_2 S_2 dt + \sigma_2 S_2 dW_2] + \frac{1}{2} \sigma_1^2 S_1^2 \frac{\partial^2 V}{\partial S_1^2} dt$$

$$+ \frac{1}{2} \sigma_2^2 S_2^2 \frac{\partial^2 V}{\partial S_2^2} dt + \sigma_1 \sigma_2 \rho S_1 S_2 \frac{\partial^2 V}{\partial S_1 \partial S_2} dt$$

$$- \Delta_1 [K_1 S_1 dt + \sigma_1 S_1 dW_1]$$

$$- \Delta_2 [K_2 S_2 dt + \sigma_2 S_2 dW_2]$$

$$+ o(dt)$$

~~S~~

$$\Delta_i = \frac{\partial V}{\partial S_i} \quad \text{remember } dW_i$$

$$(iii) d\pi = \left[ \frac{\partial V}{\partial t} + \frac{1}{2} \frac{\partial^2 V}{\partial S_1^2} S_1^2 \sigma_1^2 \right. \\ \left. + \frac{1}{2} \frac{\partial^2 V}{\partial S_2^2} S_2^2 \sigma_2^2 + \frac{\partial^2 V}{\partial S_1 \partial S_2} S_1 S_2 \sigma_1 \sigma_2 \right] dt$$

$$= r\pi dt$$

$$= \text{tr} \left[ rV - S_1 \frac{\partial V}{\partial S_1} - S_2 \frac{\partial V}{\partial S_2} \right]$$

$$\frac{S_1}{r} \frac{\partial V}{\partial t} + \frac{1}{2} \sigma_1^2 \frac{\partial^2 V}{\partial S_1^2} + \frac{1}{2} \sigma_2^2 \frac{\partial^2 V}{\partial S_2^2} + \rho \sigma_1 \sigma_2 \frac{\partial^2 V}{\partial S_1 \partial S_2} \\ + r S_1 \frac{\partial V}{\partial S_1} + r S_2 \frac{\partial V}{\partial S_2} - rV = 0$$

$$(iv) \text{ If } v = a_1 s_1 H(\frac{1}{s_1} +) \quad \square$$

$$\begin{aligned}
 v(t=T) &= \max(a_1 s_1 - a_2 s_2, 0) \\
 &= a_1 s_2 \max(\left\{ -\frac{a_2}{a_1}, 0 \right\}) \\
 \Rightarrow H(t=T) &= \max(\left\{ -K, 0 \right\})
 \end{aligned}$$

$$A \left\{ \rightarrow \infty, H \rightarrow \left\{ \right. \right.$$

$$A \left\{ \rightarrow 0, H \rightarrow 0 \right\}$$

useen  
(v)

$$\frac{\partial v}{\partial s_1} = a_1 s_2 \frac{\partial H}{\partial s_1} \left( \frac{1}{s_1} + \right) = a_1 \frac{\partial H}{\partial s_1}$$

$$\frac{\partial v}{\partial s_2} = a_1 H - a_1 s_1 \frac{\partial H}{\partial s_2}$$

$$\frac{\partial^2 v}{\partial s_1^2} = \frac{a_1}{s_2} \frac{\partial^2 H}{\partial s_1^2}$$

$$\begin{aligned}
 \frac{\partial^2 v}{\partial s_2^2} &= \cancel{a_1 \frac{\partial H}{\partial s_2} \left( -\frac{s_1}{s_2} \right)} + \cancel{\frac{a_1 s_1}{s_2^2} \frac{\partial H}{\partial s_2}} \\
 &\quad - a_1 \frac{s_1}{s_2} \frac{\partial^2 H}{\partial s_2^2} \left( -\frac{s_1}{s_2} \right) = \frac{\partial^2 H}{\partial s_2^2}
 \end{aligned}$$



(4)

$$\frac{1}{v} \sigma_1^c - \frac{q_1 s_1^c}{s_2} \frac{\partial^2 H}{\partial s_2^2} + \frac{1}{v} \frac{q_1 \sigma_2^c s_2^c}{s_2} \frac{\partial^2 H}{\partial s_2^2}$$

$$+ q_1 s_2 \frac{\partial H}{\partial z} + v s_1 q_1 \frac{\partial H}{\partial s_1}$$

$$+ v s_2 \left[ q_1 H - \frac{q_1}{s_2} \frac{\partial H}{\partial s_1} \right] - v q_1 s_2 H = 0$$

$$\frac{\partial H}{\partial z} + \left[ \frac{1}{v} \sigma_1^c + \frac{1}{v} \sigma_2^c \right] s_2 \frac{\partial^2 H}{\partial s_2^2} = 0$$

unseen

(i) - (iii) similar to material on example sheet. Remainder unseen.

5 ~~20~~

20