

Syntax and Semantics of Dependent Type Theories

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HTT-UF Summer School
Leeds, 24th June 2019

Overview

1. The syntax of dependent type theories
2. Models of dependent type theories
3. Coherence issues

Part 1:
The syntax of dependent type theories

First-order theories vs dependent type theories (I)

Usual steps to set up a first-order theory:

- (1) fix a language L
- (2) define inductively the set of well-formed terms
- (3) define inductively the set of well-formed formulas
- (4) give the axioms for the theory
- (5) define inductively the set of theorems of the theory.

Note. No vicious circle: each step depends only on the previous ones (e.g. the axioms of a theory do not modify the set of well-formed terms).

First-order theories vs dependent type theories (II)

Problem. This approach does not work for dependent type theories:

- ▶ deduction rules of a dependent type theory specify how the well-formed term expressions are built, e.g.

$$\frac{a : A}{\text{inl}(A, B, a) : A + B}$$

- ▶ the sets of terms and of types cannot be defined independently, e.g.

$$\text{Id}(A, a, b), \quad \text{nil}(A)$$

Setting up a dependent type theory

Solution (Martin-Löf, Aczel, ...)

- (1) fix a signature (*a notion that will be defined in the next slides*),
- (2) define inductively the set of raw expressions,
- (3) give the deduction rules of the dependent type theory,
- (4) define inductively the set of theorems of the theory,
- (5) the theorems isolate the well-formed expressions.

We will illustrate this in general and in one example.

Signatures (I)

Recall that a signature for an algebraic theory (e.g. theory of groups) consists of

- ▶ a set of operations,
- ▶ an assignment of an arity to each operation.

Here, an arity is just a natural number (the number of arguments of the operation).

For dependent type theories, we need more a complex notion of arity, to account for **variable binding** operations, e.g. λ , Π , Σ .

Signatures (II)

Definition. An **arity** is a tuple of the form

$$((n_1, \varepsilon_1), \dots, (n_k, \varepsilon_k), \varepsilon),$$

where $k \in \mathbb{N}$, $n_1, \dots, n_k \in \mathbb{N}$ and $\varepsilon_1, \dots, \varepsilon_k, \varepsilon$ are either 0 or 1.

Notation. When $k = 0$, we will write (ε) .

Idea.

- ▶ An operation of arity as above takes k arguments and binds n_i variables in the i -th argument.
- ▶ The $\varepsilon_1, \dots, \varepsilon_k, \varepsilon$ keep track of the distinction between term expressions (0-expressions) and type expressions (1-expressions).

Definition. A **signature** Σ is a set of pairs (s, α) where α is an arity. If $(s, \alpha) \in \Sigma$, we call s a **symbol of arity** α .

Raw expressions

Fix

- ▶ an infinite set of variables $\{x_0, x_1, \dots\}$,
- ▶ a signature Σ .

Define the sets of 0-expressions and 1-expressions by the rules:

- every variable is a 0-expression,
- if s has arity $((n_1, \varepsilon_1), \dots, (n_k, \varepsilon_k), \varepsilon)$ and M_i is an ε_i -expression and \vec{x}_i is a vector of n_i distinct variables for $i = 1, \dots, k$, then

$$s((\vec{x}_1)M_1, \dots, (\vec{x}_k)M_k)$$

is an ε -expression.

Example

The signature for the type theory \mathbf{ML}_1 includes the symbols

- ▶ Nat of arity (1)
- ▶ succ of arity $((0, 0), 0)$
- ▶ nil of arity $((0, 1), 0)$
- ▶ λ of arity $((0, 1), (1, 1), (1, 0), 0)$

Thus, we have that

- ▶ Nat is a 1-expression
- ▶ $\text{succ}(x)$ is a 0-expression
- ▶ $\text{nil}(\text{Nat})$ is a 0-expression
- ▶ $\lambda(\text{Nat}, (x)\text{Nat}, (x)x)$ is a 0-expression, usually written $(\lambda x : \text{Nat})x$.

Judgements

A **judgement** has one of the following four forms:

- ▶ $A : \text{type}$
- ▶ $A = B : \text{type}$
- ▶ $a : A$
- ▶ $a = b : A$

Here, A, B stand for 1-expressions and a, b for 0-expressions.

Contexts and hypothetical judgements

A **context** Γ is a sequence of the form

$$\Gamma = (x_0 : A_0, x_1 : A_1, \dots, x_n : A_n)$$

where

- ▶ x_0, \dots, x_n are distinct variables
- ▶ A_1, \dots, A_n are 1-expressions.

A **hypothetical judgement** has the form

$$\Gamma \vdash J$$

where Γ is a context and J is a judgement.

Deduction rules

A **deduction rule** has the form

$$\frac{\Gamma_1 \vdash J_1 \quad \dots \quad \Gamma_n \vdash J_n}{\Gamma \vdash J}$$

where $\Gamma_1 \vdash J_1, \dots, \Gamma_n \vdash J_n, \Gamma \vdash J$ are hypothetical judgements.

A **dependent type theory** is given by specifying

- ▶ a signature,
- ▶ a set of deduction rules.

Derivability is defined in the standard way.

Well-formed expressions

Definition. Let T be a dependent type theory over a signature Σ .

- ▶ If $\Gamma \vdash A : \text{type}$ is derivable, then we say that A is a **well-formed type** in context Γ .
- ▶ If $\Gamma \vdash a : A$ is derivable, then we say that a is a **well-formed element** of type A in context Γ .
- ▶ If $\Gamma \vdash A = B : \text{type}$, then we say that A and B are **judgementally equal well-formed types** in context Γ .
- ▶ If $\Gamma \vdash a = b : A$, then we say that a and b are **judgementally equal well-formed elements** of type A in context Γ .

The dependent type theory \mathbf{ML}_1

\mathbf{ML}_1 has the following forms of type:

$0, 1, \text{Bool}, \text{Nat}$

$\text{List}(A), A + B$

$\text{Id}(A, a, b)$

$(\Sigma x : A)B, (\Pi x : A)B$

\cup

The signature of \mathbf{ML}_1 (I)

<i>Symbol</i>	<i>Arity</i>
0, 1, Bool, Nat, U	(1)
List	$((0, 1), 1)$
+	$((0, 1), (0, 1), 1)$
Id	$((0, 1), (0, 0), (0, 0), 1)$
Π	$((0, 1), (1, 1), 1)$
Σ	$((0, 1), (1, 1), 1)$
T	$((0, 0), 1)$

Notation. We write

- ▶ $A + B$ for $+(A, B)$
- ▶ $(\Pi x : A)B$ for $\Pi(A, (x)B)$
- ▶ $(\Sigma x : A)B$ for $\Sigma(A, (x)B)$.

The signature of \mathbf{ML}_1 (II)

The other symbols of the signature:

*	refl
unitrec	J
true	λ
false	app
boolrec	pair
0	split
succ	Bool^U
natrec	Nat^U
nil	0^U
cons	List^U
listrec	$+^U$
inl	Id^U
inr	Π^U
case	Σ^U

The deduction rules of \mathbf{ML}_1

- (1) General rules
- (2) Rules for the forms of type of \mathbf{ML}_1 . For each one, we have
 - ▶ formation rules
 - ▶ introduction rules
 - ▶ elimination rules
 - ▶ computation rules

General deduction rules

Standard rules regarding context formation, substitution, equality.

Examples.

$$\frac{\Gamma, \Delta \vdash J \quad \Gamma \vdash A : \text{type}}{\Gamma, x : A, \Delta \vdash J} \quad x \notin \text{FV}(\Gamma) \cup \text{FV}(\Delta)$$

$$\frac{x : A, \Gamma \vdash J \quad a : A}{\Gamma[a/x] \vdash J[a/x]}$$

$$\frac{a : A \quad A = B : \text{type}}{a : B}$$

Notation. $\Gamma[a/x]$ and $J[a/x]$ denote the substitution of a for x in Γ and J , respectively.

The empty type

Formation rule.

$$0 : \text{type}$$

No introduction rules.

Elimination rule.

$$\frac{c : 0 \quad u : 0 \vdash E : \text{type}}{\text{emptyrec}(c, (u)E) : E[c/u]}$$

No computation rules.

The unit type (I)

Formation rule.

$1 : \text{type}$

Introduction rules.

$* : 1$

The unit type (II)

Elimination rules.

$$\frac{c : 1 \quad u : \text{Bool} \vdash E : \text{type} \quad d : E[* / u]}{\text{unitrec}(c, (u)E, d) : E[c / u]}$$

Computation rule.

$$\frac{u : \text{Bool} \vdash E : \text{type} \quad d : E[* / u]}{\text{unitrec}(*, (u)E, d) = d : E[* / u]}$$

The type of Boolean truth values (I)

Formation rule.

`Bool : type`

Introduction rules.

`true : Bool`

`false : Bool`

The type of Boolean truth values (II)

Elimination rules.

$$\frac{c : \text{Bool} \quad u : \text{Bool} \vdash E : \text{type} \quad d : E[\text{true}/u] \quad e : E[\text{false}/u]}{\text{boolrec}(c, (u)E, d, e) : E[c/u]}$$

Computation rules.

$$\frac{u : \text{Bool} \vdash E : \text{type} \quad d : E[\text{true}/u] \quad e : E[\text{false}/u]}{\text{boolrec}(\text{true}, (u)E, d, e) = d : E[\text{true}/u]}$$

$$\frac{u : \text{Bool} \vdash E : \text{type} \quad d : E[\text{true}/u] \quad e : E[\text{false}/u]}{\text{boolrec}(\text{false}, (u)E, d, e) = e : E[\text{false}/u]}$$

The type of natural numbers (I)

Formation rule.

$\text{Nat} : \text{type}$

Introduction rules.

$0 : \text{Nat}$

$$\frac{n : \text{Nat}}{\text{succ}(n) : \text{Nat}}$$

The type of natural numbers (II)

Elimination rule.

$$\frac{c : \text{Nat} \quad u : \text{Nat} \vdash E : \text{type} \quad d : E[0/u] \quad x : \text{Nat}, y : E[x/u] \vdash e : E[\text{succ}(x)/u]}{\text{natrec}(c, (u)E, d, (x, y)e) : E[c/u]}$$

Computation rules.

$$\frac{u : \text{Nat} \vdash E : \text{type} \quad d : E[0/u] \quad x : \text{Nat}, y : E[x/u] \vdash e : E[\text{succ}(x)/u]}{\text{natrec}(0, (u)E, d, (x, y)e) = d : E[0/u]}$$

$$\frac{c : \text{Nat} \quad u : \text{Nat} \vdash E : \text{type} \quad d : E[0/u] \quad x : \text{Nat}, y : E[x/u] \vdash e : E[\text{succ}(x)/u]}{\text{natrec}(\text{succ}(c), (u)E, d, (x, y)e) = e[c/x, \text{natrec}(c, (u)E, d, (x, y)e)/y] : E[\text{succ}(c)/u]}$$

List types (I)

Formation rule.

$$\frac{A : \text{type}}{\text{List}(A) : \text{type}}$$

Introduction rules.

$$\frac{A : \text{type}}{\text{nil}(A) : \text{List}(A)} \qquad \frac{a : A \quad \ell : \text{List}(A)}{\text{cons}(A, a, \ell) : \text{List}(A)}$$

Notation. We will write nil and $\text{cons}(a, \ell)$ for $\text{nil}(A)$ and $\text{cons}(A, a, \ell)$.

List types (II)

Elimination rule.

$$\frac{\begin{array}{l} \ell : \text{List}(A) \\ u : \text{List}(A) \vdash E : \text{type} \\ d : E[\text{nil}/u] \\ x : A, y : \text{List}(A), z : E[y/u] \vdash e : E[\text{cons}(x, y)/u] \end{array}}{\text{listrec}(\ell, (u)E, d, (x, y, z)e) : E[\ell/u]}$$

Computation rules.

$$\frac{\begin{array}{l} u : \text{List}(A) \vdash E : \text{type} \\ d : E[\text{nil}/u] \\ x : \text{List}(A), y : A, z : E[y/u] \vdash e : E[\text{cons}(x, y)/u] \end{array}}{\text{listrec}(\text{nil}, (u)E, d, (x, y, z)e) = d : E[\text{nil}/u]}$$

$$\frac{\begin{array}{l} \ell : \text{List}(A) \\ a : A \\ u : \text{List}(A) \vdash E : \text{type} \\ d : E[\text{nil}/u] \\ x : \text{List}(A), y : A, z : E[y/u] \vdash e : E[\text{cons}(x, y)/u] \end{array}}{\text{listrec}(\text{cons}(a, \ell), (u)E, d, (x, y, z)e) = e[\ell/x, a/y, \text{listrec}(\ell, (u)E, d, (x, y, z)e)/u] : E[\text{cons}(a, \ell)/u]}$$

Sum types (I)

Formation rule.

$$\frac{A : \text{type} \quad B : \text{type}}{A + B : \text{type}}$$

Introduction rules.

$$\frac{a : A}{\text{inl}(A, B, a) : A + B} \quad \frac{b : B}{\text{inr}(A, B, b) : A + B}$$

Notation. We write $\text{inl}(a)$, $\text{inr}(b)$ for $\text{inl}(A, B, a)$ and $\text{inr}(A, B, b)$.

Sum types (II)

Elimination rule.

$$\frac{c : A + B \quad u : A + B \vdash E : \text{type} \quad x : A \vdash d : E[\text{inl}(x)/u] \quad y : B \vdash e : E[\text{inr}(y)u]}{\text{case}(c, (u)E, (x)d, (y)e) : E[c/u]}$$

Computation rules.

$$\frac{a : A \quad u : A + B \vdash E : \text{type} \quad x : A \vdash d : E[\text{inl}(x)/u] \quad y : B \vdash e : E[\text{inr}(y)u]}{\text{case}(\text{inl}(a), (u)E, (x)d, (y)e) = d[a/x] : E[\text{inl}(a)/u]}$$

$$\frac{b : B \quad u : A + B \vdash E : \text{type} \quad x : A \vdash d : E[\text{inl}(x)/u] \quad y : B \vdash e : E[\text{inr}(y)u]}{\text{case}(\text{inr}(b), (u)E, (x)d, (y)e) = e[b/y] : E[\text{inr}(b)/u]}$$

Identity types (I)

Formation rule.

$$\frac{A : \text{type} \quad a : A \quad b : A}{\text{Id}(A, a, b) : \text{type}}$$

Introduction rule.

$$\frac{a : A}{\text{refl}(A, a) : \text{Id}(A, a, a)}$$

Notation. We write $\text{Id}_A(a, b)$ for $\text{Id}(A, a, b)$, $\text{refl}(a)$ for $\text{refl}(A, a)$.

Identity types (II)

Elimination rule.

$$\frac{p : \text{Id}_A(a, b) \quad x : A, y : A, u : \text{Id}_A(x, y) \vdash E : \text{type} \quad x : A \vdash e : E[x/y, \text{refl}(x)/u]}{J(a, b, p, (x, y, u)E, (x)e) : E[a/x, b/y, p/u]}$$

Computation rule.

$$\frac{a : A \quad x : A, y : A, u : \text{Id}_A(x, y) \vdash E : \text{type} \quad x : A \vdash e : E[x/y, \text{refl}(x)/u]}{J(a, a, \text{refl}(a), (x, y, u)E, (x)e) = e[a/x] : E[a/x, a/y, \text{refl}(a)/u]}$$

Note. $E[y/x, \text{refl}(x)/u] = E[x/x, y/x, \text{refl}(x)/u]$.

Dependent pair types (I)

Formation rule.

$$\frac{x : A \vdash B : \text{type}}{\Sigma(x : A)B : \text{type}}$$

Introduction rule.

$$\frac{a : A \quad b : B[a/x]}{\text{pair}(A, (x)B, a, b) : \Sigma(x : A)B}$$

Notation. We will write $\text{pair}(a, b)$ for $\text{pair}(A, (x)B, a, b)$.

Special case. If $x \notin \text{FV}(B)$, write $A \times B$ for $\Sigma(x : A)B$.

Dependent pair types (II)

Elimination rule.

$$\frac{c : (\Sigma x : A)B(x) \quad u : (\Sigma x : A)B(x) \vdash E : \text{type} \quad x : A, y : B \vdash d : E[\text{pair}(x, y)/u]}{\text{split}(c, (u)E, (x, y)d) : E[c/u]}$$

Computation rule.

$$\frac{a : A \quad b : B[a/x] \quad u : (\Sigma x : A)B(x) \vdash E : \text{type} \quad x : A, y : B \vdash d : E[\text{pair}(x, y)/u]}{\text{split}(\text{pair}(a, b), (u)E, (x, y)d) = d[a/x, b/y] : E[\text{pair}(a, b)/u]}$$

Dependent function types (I)

Formation rule.

$$\frac{x : A \vdash B : \text{type}}{\Pi(x : A)B : \text{type}}$$

Introduction rule.

$$\frac{x : A \vdash b : B}{\lambda(A, (x)B, (x)b) : \Pi(x : A)B}$$

Notation. We write $\lambda x.b$ for $\lambda(A, (x)B, (x)b)$.

Special case. If $x \notin \text{FV}(B)$, write $A \rightarrow B$ for $\Pi(x : A)B$.

Dependent function types (II)

Elimination rule.

$$\frac{f : \Pi(x : A)B \quad a : A}{\text{app}(f, a) : B[a/x]}$$

Computation rule.

$$\frac{x : A \vdash b : B \quad a : A}{\text{app}(\lambda x. b, a) = b[a/x] : B[a/x]}$$

A type universe

Formation rule.

$$U : \text{type}$$

Elimination rule.

$$\frac{A : U}{T(A) : \text{type}}$$

This is the so-called formulation à la Tarski.

A type universe (II)

Introduction and computation rules.

$0^U : U$ $T(0^U) = 0 : \text{type}$

$1^U : U$ $T(1^U) = 1 : \text{type}$

$\text{Bool}^U : U$ $T(\text{Bool}^U) = \text{Bool} : \text{type}$

$\text{Nat}^U : U$ $T(\text{Nat}^U) = \text{Nat} : \text{type}$

A type universe (III)

Introduction and computation rules.

$$\frac{A : U \quad B : U}{A +^U B : U}$$

$$\frac{A : U \quad B : U}{T(A +^U B) = T(A) + T(B) : \text{type}}$$

$$\frac{A : U}{\text{List}^U(A) : U}$$

$$\frac{A : U}{T(\text{List}^U(A)) = \text{List}(T(A)) : \text{type}}$$

A type universe (IV)

Introduction and computation rules.

$$\frac{A : U \quad a : T(A) \quad b : T(A)}{\text{Id}^U(A, a, b) : U}$$

$$\frac{A : U \quad a : T(A) \quad b : T(A)}{T(\text{Id}^U(A, a, b)) = \text{Id}(T(A), a, b) : \text{type}}$$

$$\frac{A : U \quad x : T(A) \vdash B : U}{\Pi^U(A, (x)B) : U}$$

$$\frac{A : U \quad x : T(A) \vdash B : U}{T(\Pi^U(A, (x)B)) = \Pi(x : T(A))T(B) : \text{type}}$$

$$\frac{A : U \quad x : T(A) \vdash B : U}{\Sigma^U(A, (x)B) : U}$$

$$\frac{A : U \quad x : T(A) \vdash B : U}{T(\Sigma^U(A, (x)B)) = \Sigma(x : T(A))T(B) : \text{type}}$$

Part 2:
Models of dependent type theories

Comprehension categories

Definition. A (split) comprehension category consists of

$$\begin{array}{ccc} \mathbb{T} & \xrightarrow{\chi} & \mathbb{C} \rightarrow \\ & \searrow p & \swarrow \text{cod} \\ & \mathbb{C} & \end{array}$$

where

- ▶ p is a (split) Grothendieck fibration
- ▶ χ sends Cartesian morphisms to pullback squares

Example: the syntactic category (I)

Let **Ctx** be the category of contexts of **ML₁**, *i.e.*

- ▶ objects are contexts, *e.g.*

$$\Gamma = (x_0 : A_0, \dots, x_n : A_n)$$

- ▶ morphisms $\sigma : \Delta \rightarrow \Gamma$ are substitutions, *i.e.* sequences

$$\sigma = (a_0, \dots, a_n)$$

such that

$$\Delta \vdash a_0 : A_0$$

$$\Delta \vdash a_1 : A_1[a_0/x_0]$$

$$\vdots$$

$$\Delta \vdash a_n : A_n[a_0/x_0, \dots, a_{n-1}/x_{n-1}]$$

Example: the syntactic category (II)

Let **Ty** the category of types-in-context, *i.e.*

- ▶ objects are pairs (Γ, A) , where $\Gamma \vdash A$: type
- ▶ morphisms $(\Delta, B) \rightarrow (\Gamma, A)$ are context morphisms

$$(\Delta, y: B) \rightarrow (\Gamma, x: A).$$

Let $p: \mathbf{Ty} \rightarrow \mathbf{Ctx}$ be the first projection, mapping (Γ, A) to Γ .

Fact. The functor p is a split Grothendieck fibration:

$$\begin{array}{ccc} \mathbf{T} & & \sigma^*(\Gamma, A) \longrightarrow (\Gamma, A) \\ \downarrow p & & \vdots \quad \lrcorner \quad \vdots \\ \mathbf{C} & & \Delta \xrightarrow{\sigma} \Gamma \end{array}$$

where $\sigma^*(\Gamma, A) = (\Delta, A[\sigma])$.

Example: the syntactic category (III)

The functor $\chi: \mathbf{Ty} \rightarrow \mathbf{Ctx}^{\rightarrow}$ sends (Γ, A) to the evident map

$$\chi_A: (\Gamma, x: A) \rightarrow (\Gamma)$$

Proposition. The functor χ sends Cartesian arrows to pullbacks

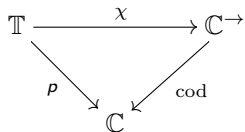
$$\begin{array}{ccc} (\Delta, x: A[\sigma]) & \longrightarrow & (\Gamma, x: A) \\ \chi_{A[\sigma]} \downarrow & \lrcorner & \downarrow \chi_A \\ \Delta & \xrightarrow{\sigma} & \Gamma \end{array}$$

so we have a split comprehension category

$$\begin{array}{ccc} \mathbf{Ty} & \xrightarrow{\chi} & \mathbf{Ctx}^{\rightarrow} \\ & \searrow p & \swarrow \text{cod} \\ & \mathbf{Ctx} & \end{array}$$

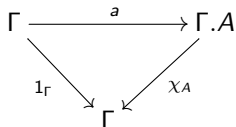
Notation and terminology

Given a general split comprehension category



For $\Gamma \in \mathbb{C}$ and $A \in \mathbb{T}_\Gamma$,

- ▶ we write $\chi_A: \Gamma.A \rightarrow \Gamma$ for $\chi(A)$,
- ▶ we think of a section



as a term $\Gamma \vdash a: A$.

Split comprehension categories model only the core of \mathbf{ML}_1 , *i.e.*

- ▶ structural rules,
- ▶ substitution.

Note. The Grothendieck fibration p being split corresponds to strict associativity and unitality of substitution.

We need additional structure and axioms to model each form of type.

We only discuss the case of Id-types.

Id-types in a comprehension category

For every $\Gamma \in \mathbb{C}$, $A \in \mathbb{T}_\Gamma$, we need

- ▶ an object $\text{Id}_A \in \mathbb{T}_{\Gamma.A.A}$
- ▶ a factorisation of the diagonal

$$\Gamma.A \xrightarrow{r_A} \Gamma.A.A.\text{Id}_A \longrightarrow \Gamma.A.A$$

- ▶ for each $E \in \mathbb{T}_{\Gamma.A.A.\text{Id}_A}$ and e making

$$\begin{array}{ccc} \Gamma.A & \xrightarrow{e} & \Gamma.A.A.\text{Id}_A.E \\ r_A \downarrow & & \downarrow \\ \Gamma.A.A.\text{Id}_A & \longrightarrow & \Gamma.A.A.\text{Id}_A \end{array}$$

commute, a diagonal filler $j_{A,E,e}$.

such that, for all $\sigma: \Delta \rightarrow \Gamma$,

- ▶ $\text{Id}_A[\sigma] = \text{Id}_{A[\sigma]}$, $r_A[\sigma] = r_{A[\sigma]}$, $j_{A,E,e}[\sigma] = j_{A[\sigma],E[\sigma],e[\sigma]}$

Part 3:
How to construct models

Coherence issues

Split comprehension categories modelling \mathbf{ML}_1 occur rarely in practice.

Two issues:

- (1) Grothendieck fibrations need not be split
- (2) Strict stability under reindexing is hard to satisfy

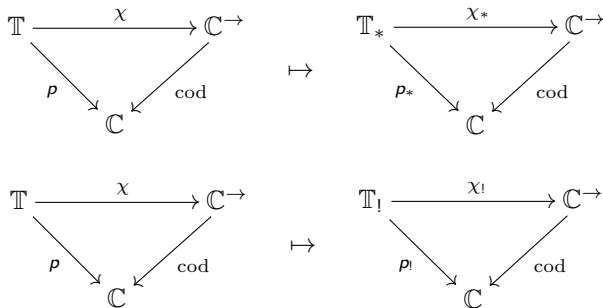
Issue (1) is reminiscent of the distinction between strict monoidal categories and monoidal categories.

Splitting comprehension categories

The inclusion

Split Grothendieck fibrations/ $\mathbb{C} \hookrightarrow$ Grothendieck fibrations/ \mathbb{C}

has both a left and a right adjoint, so we get two splitting methods

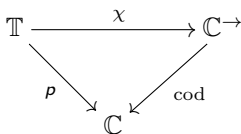


for comprehension categories.

Yet another splitting method is due to Voevodsky.

Strict stability

Fundamental question. What structure on a comprehension category



is sufficient in order for its left (or right, or Voevodsky) splitting to be a model of **ML**₁?

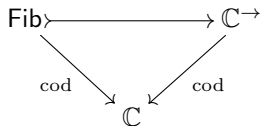
The case of Id-types

- ▶ For the left and Voevodsky splitting, a weak factorisation system of satisfying the Frobenius condition is sufficient.
- ▶ For the right splitting, one needs an algebraic weak factorisation system of satisfying the Frobenius condition.

Example: homotopical models

Consider a category \mathbb{C} with a Quillen model structure $(\text{Weq}, \text{Fib}, \text{Cof})$,

Then



is a comprehension category, but it is not split.

Under some assumptions, we can split it to obtain a model of \mathbf{ML}_1 .

The simplicial model of Univalent Foundations arises in this way from the Kan-Quillen model structure on \mathbf{SSet} .

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