

Fluid mechanics

(1)

3 steps: (I) Describe mathematically the flow field / motion of fluid particles:

Kinematics

(II) Formulate the eqns. of motion: Balance of forces acting on fluid particles: stresses

(III) Constitutive eqns: relate the kinematics to stresses

} The Navier-Stokes eqns.
Then: lots of examples!

§ 2 Kinematics

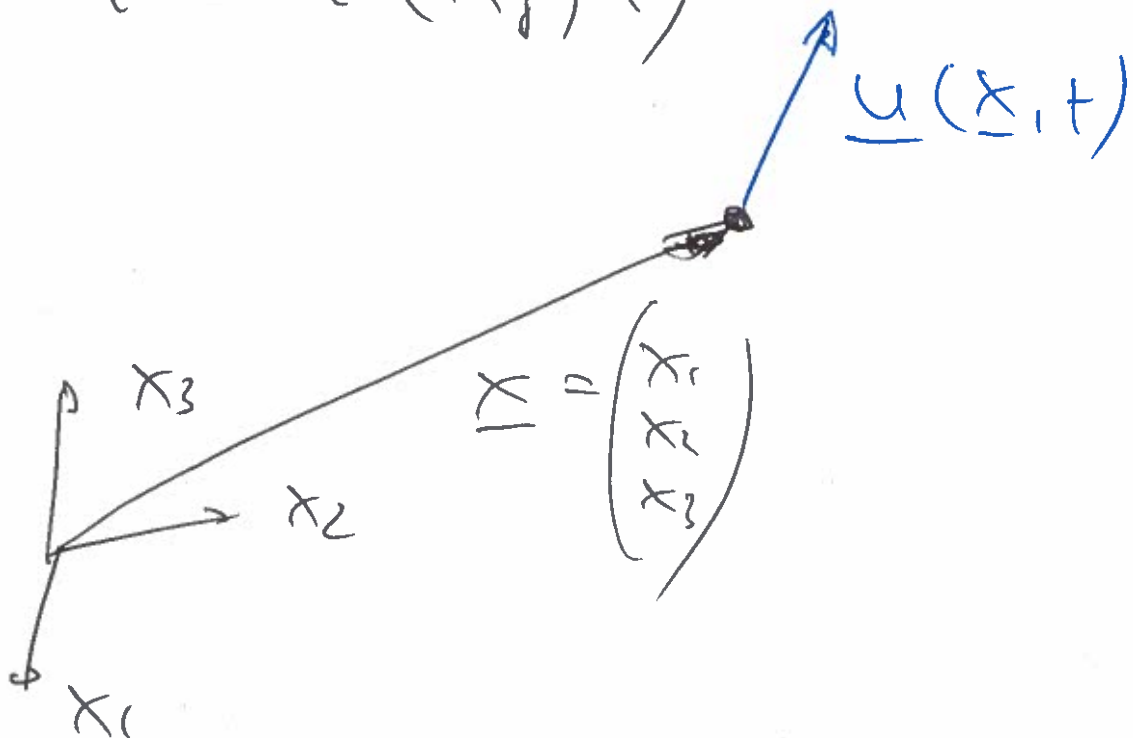
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The Eulerian flow field

Assume we know the velocity \underline{u} as a fct. of the three cartesian coordinates (x_1, x_2, x_3) & time t .

$$\underline{u} = \underline{u}(x_1, x_2, x_3, t) = \underline{u}(\underline{x}, t)$$

$$u_i = u_i(x_j, t)$$



At time t the fluid (3) particle at this position (\underline{x}) has velocity $\underline{u}(\underline{x}, t)$

Note: At different times, different material particles occupy position \underline{x} !

(Eulerian vs. Lagrangian viewpoint):

This has important implications

Example: Acceleration of fluid particles.

The material derivative

The position \underline{x} of a fluid particle is given by

$$\underline{x} = \underline{x}^p(t) = \begin{pmatrix} x_1^p(t) \\ x_2^p(t) \\ x_3^p(t) \end{pmatrix}$$

(Trajectory)

velocity of the particle is ⁽⁴⁾

$$\underline{u} = \underline{u}(x_1^p(t), x_2^p(t), x_3^p(t), t)$$

So, to get the acceleration of that particle:

$$\frac{d\underline{u}}{dt} = \frac{\partial \underline{u}}{\partial t} + \frac{\partial \underline{u}}{\partial x_1^p} \frac{dx_1^p}{dt} +$$

$$+ \frac{\partial \underline{u}}{\partial x_2^p} \frac{dx_2^p}{dt} +$$

$$+ \frac{\partial \underline{u}}{\partial x_3^p} \frac{dx_3^p}{dt}$$

$$\frac{du_i}{dt} = \frac{\partial u_i}{\partial t} + \frac{\partial u_i}{\partial x_j^p} \frac{dx_j^p}{dt}$$

u_j

$$\boxed{\frac{du_i}{dt} = \frac{\partial u_i}{\partial t} + u_j \frac{\partial u_i}{\partial x_j^p}}$$

Symbolically:

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$$\frac{du}{dt} = \frac{\partial u}{\partial t} + \underline{u} \cdot \nabla \underline{u}$$

This expression is often denoted by

$$\frac{D\underline{u}}{Dt}$$

to distinguish derivs.
assoc. with an individual
material particle from the
deriv. at a fixed spatial
point.

The rate of strain tensor & the vorticity (6)

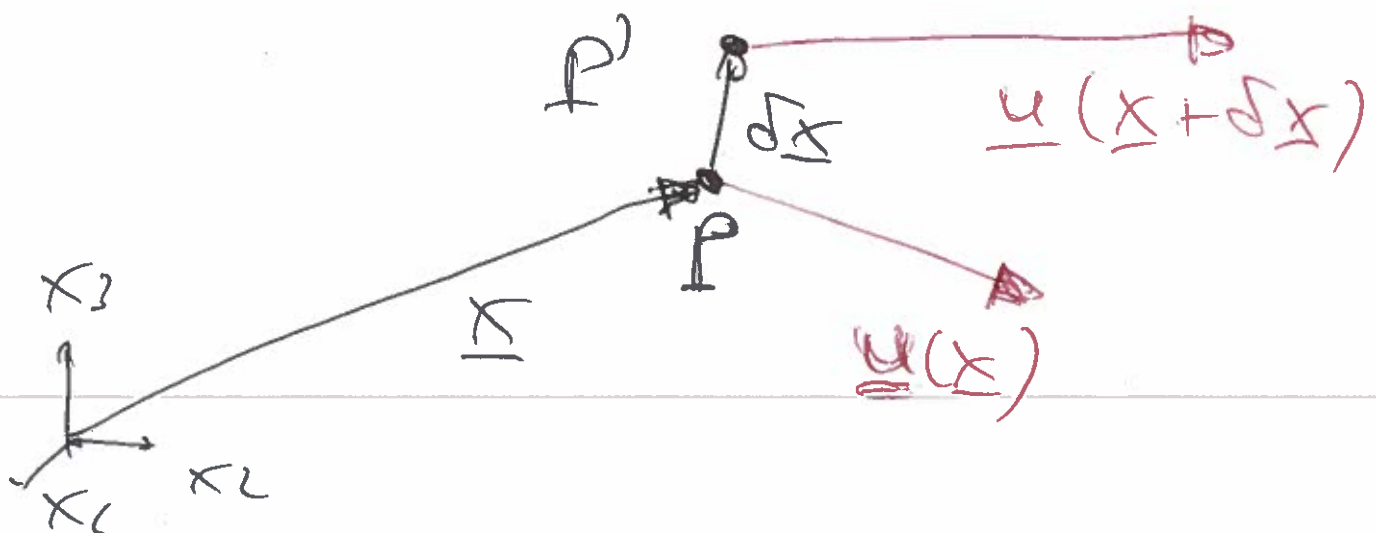
Velocity field in itself is not very interesting.

It contains:

- translations
 - rotations
 - shearing
 - dilation
- } motions

How do we identify these?

Examine the veloc. field in vicinity of point P .



Taylor expand:

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$$\underline{u}(\underline{x} + \underline{\delta x}) = \underline{u}(x_1 + \delta x_1, x_2 + \delta x_2, x_3 + \delta x_3)$$

$$= \underline{u}(x_1, x_2, x_3) + \frac{\partial \underline{u}}{\partial x_1} \delta x_1 + \frac{\partial \underline{u}}{\partial x_2} \delta x_2 + \frac{\partial \underline{u}}{\partial x_3} \delta x_3 + O(\delta x_i^2)$$

$$\delta \underline{u} = \underline{u}(\underline{x} + \underline{\delta x}) - \underline{u}(\underline{x})$$

$$\delta u_i = \frac{\partial u_i}{\partial x_j} \delta x_j + O(\delta x_k^2)$$

Now $\delta x_j \rightarrow dx_j$

$$du_i = \frac{\partial u_i}{\partial x_j} dx_j$$

"velocity gradient tensor" 3×3 matrix