

Recall streamfunction $\psi = \int \underline{u} \cdot \underline{e}_2 ds$

$$\text{and } \frac{\partial \psi}{\partial x} = -v, \quad \frac{\partial \psi}{\partial y} = u$$

and $\nabla \cdot \underline{u} = 0$ identically.

How is the streamfunction related to vorticity?

$$\text{Vorticity } \underline{\omega} = \nabla \times \underline{u} = \omega_3 \underline{e}_2 \equiv \underline{\omega e}_2$$

and

$$\omega = \frac{\partial v}{\partial x} - \frac{\partial u}{\partial y}$$

(vorticity is out-of-plane for 2D flow)

$$= \frac{\partial}{\partial x} \left(-\frac{\partial \psi}{\partial x} \right) - \frac{\partial}{\partial y} \left(\frac{\partial \psi}{\partial y} \right) = -\nabla^2 \psi$$

In 2D

$$\boxed{\omega = -\nabla^2 \psi}$$

By using ψ , we don't have to solve continuity. What happens to Navier-Stokes?

In general we can formulate the vorticity transport equation by taking $\nabla \times$ (Navier-Stokes)

this is easiest if we use

$$\underline{u} \times \underline{\omega} = \underline{u} \times (\nabla \times \underline{u}) = \frac{1}{2} \nabla (\underline{u} \cdot \underline{u}) - \underline{u} \cdot \nabla \underline{u}$$

to write Navier-Stokes as

$$\frac{\partial \underline{u}}{\partial t} = \frac{\partial \underline{u}}{\partial t} + \overbrace{\frac{1}{2} \nabla (\underline{u} \cdot \underline{u}) - \underline{u} \times \underline{\omega}}^{\underline{u} \cdot \nabla \underline{u}} = -\frac{1}{\rho} \nabla p + \nu \nabla^2 \underline{u}$$

Now we take the curl and recall that

$$\nabla \times \nabla \phi = \underline{0}$$

and so

$$\underline{\nabla} \times \frac{\partial \underline{u}}{\partial t} - \underline{\nabla} \times \underline{u} \times \underline{\omega} = \underline{\nabla} \times \nu \nabla^2 \underline{u}$$

$$\Rightarrow \frac{\partial}{\partial t} (\underline{\nabla} \times \underline{u}) - (\underline{\omega} \cdot \underline{\nabla}) \underline{u} + (\underline{u} \cdot \underline{\nabla}) \underline{\omega} - \underline{u} \nabla \cdot \underline{\omega} + \underline{\omega} \nabla \cdot \underline{u} = \nu \nabla^2 \underline{\nabla} \times \underline{u}$$

incompressibility

$\nabla \cdot (\underline{\nabla} \times \underline{u}) = 0$

Here,

$$\frac{\partial \underline{\omega}}{\partial t} + \underline{u} \cdot \underline{\nabla} \underline{\omega} = \underline{\omega} \cdot \underline{\nabla} \underline{u} + \nu \nabla^2 \underline{\omega}$$

$$\Rightarrow \frac{D \underline{\omega}}{Dt} = \underline{\omega} \cdot \underline{\nabla} \underline{u} + \nu \nabla^2 \underline{\omega}$$

Vorticity Transport equation.

- Expresses the rate of change of angular velocity of fluid particles (LHS)
- Vorticity diffuses via viscous effects. (Final term on RHS)
- $(\underline{\omega} \cdot \underline{\nabla} \underline{u})$ is the vortex stretching term
Velocity gradients lead to increases in vorticity
- $\underline{\omega} \cdot \underline{\nabla} \underline{u} = 0$ in 2D flow because $\underline{\omega}$ is out-of-plane and $\underline{\nabla} \underline{u}$ is in-plane.
- No vortex stretching in 2D.
 \Rightarrow If there is no viscosity, vorticity is conserved.

For low Re we can factor the equations

$$\underline{y} = U \underline{y}^*, \quad \underline{r} = a \underline{r}^*, \quad t = \frac{a}{U} t^*$$

$$\underline{\omega} = \frac{U}{a} \underline{\omega}^*$$

* indicates dimensionless variable.

In index form, vorticity transport equation is:

$$\frac{\partial \omega_i}{\partial t} + y_j \frac{\partial \omega_i}{\partial y_j} = \omega_j \frac{\partial \omega_i}{\partial y_j} + \nu \frac{\partial^2 \omega_i}{\partial x_j^2}$$

$$\Rightarrow \frac{U}{a} \frac{\partial \omega_i^*}{\partial t^*} + \frac{U^2}{a^2} y_j^* \frac{\partial \omega_i^*}{\partial y_j^*} = \frac{U^2}{a^2} \omega_j^* \frac{\partial \omega_i^*}{\partial y_j^*} + \frac{\nu U^2}{a^3} \frac{\partial^2 \omega_i^*}{\partial y_j^{*2}}$$

$$\Rightarrow \frac{U^2}{a^2} \left[\frac{D \underline{\omega}^*}{Dt^*} = \underline{\omega}^* \cdot \nabla \underline{u}^* \right] + \frac{\nu U^2}{a^3} \nabla^2 \underline{\omega}^*$$

In 2D, we obtain

$$\frac{aU}{\nu} \frac{D \underline{\omega}^*}{Dt^*} = \nabla^2 \underline{\omega}^* \quad \Rightarrow \quad \boxed{\text{Re} \frac{D \underline{\omega}^*}{Dt^*} = \nabla^2 \underline{\omega}^*}$$

Re

If $\text{Re} = 0$ (Stokes flow) then $\nabla^2 \underline{\omega} = \underline{0}$

Γ Obtain directly from Stokes

$$\nabla p = \mu \nabla^2 \underline{u} \quad \Rightarrow \quad \nabla \times \nabla p = \mu \nabla \times \nabla^2 \underline{u}$$

$$\Rightarrow \nabla^2 \underline{\omega} = \underline{0} \quad \square$$

In 2D Stokes flow, $\underline{w} = w \underline{e}_z$

$$\Delta \underline{w} = 0 \quad \text{and} \quad w = -\Delta^2 \psi$$

$$\text{Thus } \Delta^2 w = \Delta^2 (-\Delta^2 \psi) = -\Delta^4 \psi = 0$$

$$\Rightarrow \boxed{\Delta^2 \psi = 0} \quad - \text{biharmonic equation}$$

$$\Delta^2 \psi = \frac{\partial^4 \psi}{\partial x^4} + \frac{2 \partial^4 \psi}{\partial x^2 \partial y^2} + \frac{\partial^4 \psi}{\partial y^4}$$

We must solve 1 scalar equation rather than 3 (vector) equations — but what about the boundary conditions?