

# MT35001: SOLUTION FOR EXAMPLE SHEET<sup>1</sup> I

1.) Which one of these equations in index notation are valid? Remember the summation convention!

- a)  $c = a_i b_i$  (OK, this is the dot product  $c = \mathbf{a} \cdot \mathbf{b}$ )
- b)  $c = a_{ij} b_i$  (Wrong, the free index  $j$  doesn't appear on LHS)
- c)  $c_i = a_{ij} b_i$  (Wrong, the indices on LHS and RHS don't match)
- d)  $c_i = a_{ij} b_j$  (OK, this is the matrix vector product with the matrix  $\mathbf{a}$ :  $\mathbf{c} = \mathbf{a}\mathbf{b}$ )
- e)  $c_i = a_{ij} b_j$  (OK, this is the matrix vector product with the transposed matrix  $\mathbf{a}$ :  $\mathbf{c} = \mathbf{a}^T \mathbf{b}$ )
- f)  $\sigma_{ij} = \alpha_{ij} T + E_{ijkl} e_{kl}$  (Correct – meet your first 4th order tensor. By the way: this is the constitutive equation for a linearly elastic solid incl. temperature variations)
- g)  $\sigma_{ij} = \alpha_{kl} T_i + E_{ijkl} e_{ij}$  (Wrong, the indices of all terms are different)
- h)  $k_{ijkl} = a_i b_{kl} c_{n_j m} d_{mn} + e_{ik} e_{jn} f_{nl}$  (Messy, but correct)

2.) Using a comma to denote partial differentiation (e.g.  $\partial u / \partial x_2 = u_{,2}$ ), transform the following expressions into index notation:

- a)  $\nabla u(x_1, x_2, x_3) \rightarrow u_{,i}$
- b)  $\mathbf{A} = \nabla \mathbf{u}(x_1, x_2, x_3) \rightarrow a_{ij} = u_{,i,j}$
- c)  $\nabla \cdot \mathbf{u}(x_1, x_2, x_3) = f(x_1, x_2, x_3) \rightarrow u_{,i,i} = f$
- d)  $\nabla^2 u(x_1, x_2, x_3) = f(x_1, x_2, x_3) \rightarrow u_{,ii} = f$
- e)  $\nabla^2 \mathbf{u}(x_1, x_2, x_3) = \mathbf{f}(x_1, x_2, x_3) \rightarrow u_{,i,jj} = f_i$

- 3.) a) Show that  $\frac{\partial x_i}{\partial x_j} = \delta_{ij}$ : Cartesian coordinates are independent of each other, so  $\frac{\partial x_i}{\partial x_j} = 1$  if  $i = j$  and 0 if  $i \neq j$ .
- b) Show that  $\delta_{ii} = 3$ : Using the summation convention this expands as  $\delta_{ii} = \delta_{11} + \delta_{22} + \delta_{33}$ , which, given the properties of the Kronecker delta, is equal to three.
- c) For arbitrary vectors  $u_i$  and  $v_i$  show that

$$S_{ij} = u_i v_j + u_j v_i$$

is symmetric (i.e.  $S_{ij} = S_{ji}$ ) and that

$$T_{ij} = u_i v_j - u_j v_i$$

is antisymmetric (i.e.  $T_{ij} = -T_{ji}$ ). Exchange the indices  $i$  and  $j$  and re-arrange the terms.

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