

u "contains"

(1)

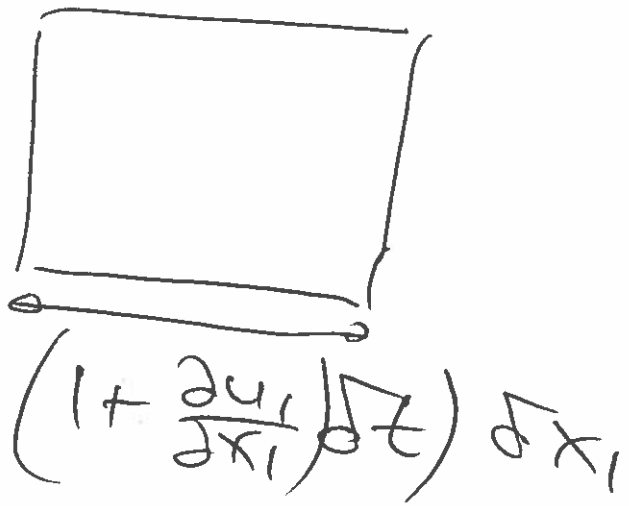
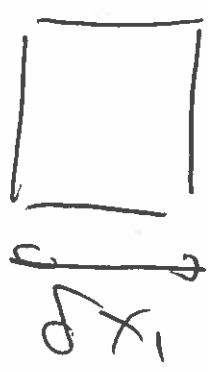
- translation ✓
- rotation ✓
- dilation ✓
- shear

$$\delta u_i = \frac{\partial u_i}{\partial x_j} \delta x_j$$

$$= \left[\frac{1}{2} \left(\frac{\partial u_i}{\partial x_j} + \frac{\partial u_j}{\partial x_i} \right) + \frac{1}{2} \left(\frac{\partial u_i}{\partial x_j} - \frac{\partial u_j}{\partial x_i} \right) \right] \delta x_j$$

$$\epsilon_{ij} = \epsilon_{ji}$$

$$\omega_{ij} = -\omega_{ji}$$



ϵ_{ii} extensional rate of strain of line elements in x_i -direction

$\frac{\Delta e}{e}$

(ii) Shear rate of strain

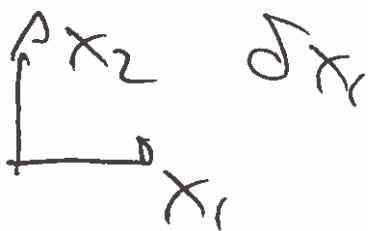
(2)

Illustration in 2D

Shear = change in shape (angles) of a small initially rectangular fluid element



bottom left corner realigned (undo translation & rotation)



$$\frac{\partial u_2}{\partial x_1} \Delta x_1 \delta t$$

$$\left(1 + \frac{\partial u_1}{\partial x_1} \delta t\right) \Delta x_1$$

See last lecture or sheet (1)

$$\underbrace{\tan \delta \alpha}_{\rightarrow \delta \alpha} = \frac{\frac{\partial u_2}{\partial x_1} \Delta x_1 \delta t}{\left(1 + \frac{\partial u_1}{\partial x_1} \delta t\right) \Delta x_1}$$

so $\delta t \rightarrow 0$

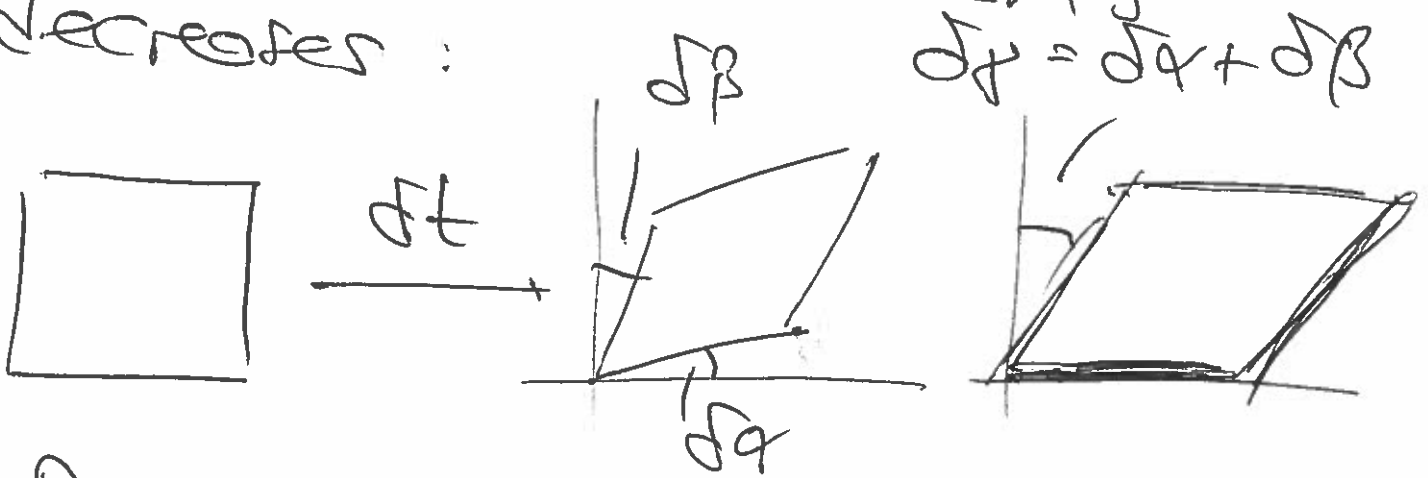
$$\frac{\delta \alpha}{\delta t} = \frac{\partial u_2}{\partial x_1}$$

$$\frac{D\alpha}{Dt} = \frac{\partial u_2}{\partial x_1}$$

Similarly

$$\frac{D\beta}{Dt} = \frac{\partial u_1}{\partial x_2}$$

Now consider the shear rate = the rate at which the initially right angle between two horizontal & vertical line elements decreases:



$$\frac{D\gamma}{Dt} = \frac{D\alpha}{Dt} + \frac{D\beta}{Dt} = \frac{\partial u_2}{\partial x_1} + \frac{\partial u_1}{\partial x_2} = 2\varepsilon_{12}$$

(Similar for other directions) (4)

The off-diagonal entries of ϵ_{ij} represent half the rate of strain in the x_i - x_j -plane.

Summary: rigid body
translation

$$\underline{u}(\underline{x} + \delta \underline{x}) = \underline{u}(\underline{x}) + \underline{\omega} \times \delta \underline{x} +$$

$$+ \underline{\epsilon} \delta \underline{x}$$

shear & dilation.

$$u_i(x_j + \delta x_j) = u_i(x_j) + \omega_{ij} \delta x_j + \epsilon_{ij} \delta x_j$$

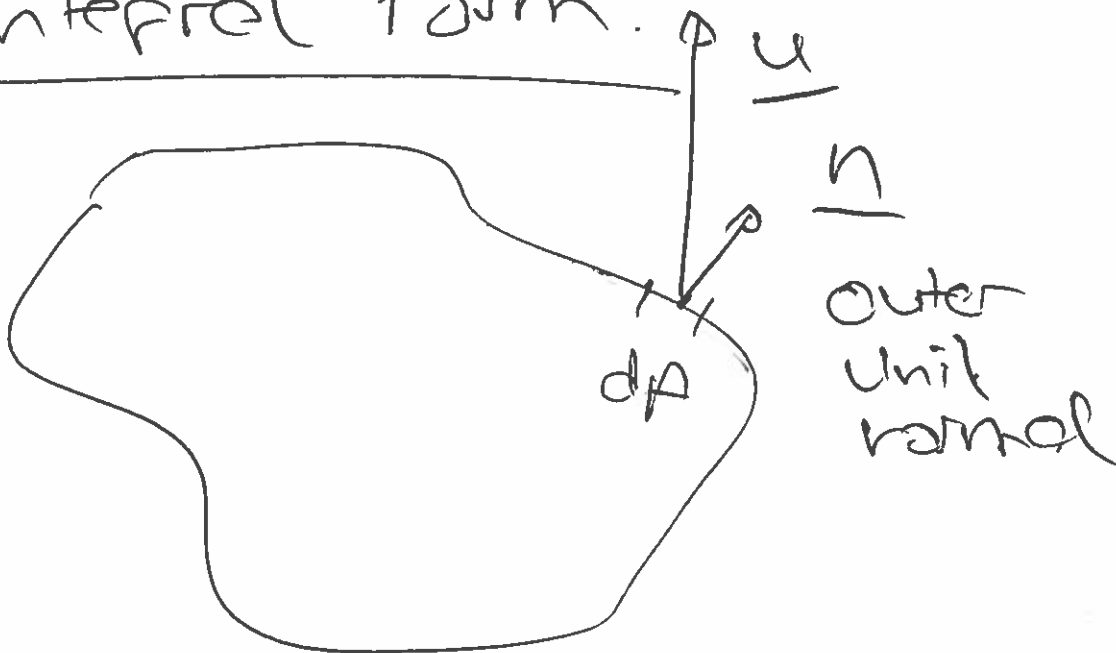
Eqn. of continuity

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Physics: "Mass is conserved"

Mass flux into a spatially fixed volume = rate of change of mass in this volume.

Integral form:



Mass flux:

$$\begin{aligned} & \text{density } \rho \left[\frac{\text{kg}}{\text{m}^3} \right] \times \text{velocity normal} \\ & \text{to face} \left(\frac{\text{m}}{\text{sec}} \right) \times \text{area} \left(\text{m}^2 \right) \\ & = \text{rate of change of mass} \left(\frac{\text{kg}}{\text{sec}} \right) \end{aligned}$$

$$\boxed{-\oint (\rho \underline{u}) \cdot \underline{n} dA = \int \frac{d\rho}{dt} dV} \quad \text{Le}$$

Divergence theorem:

$$\int \operatorname{div} \underline{v} dV = \oint \underline{v} \cdot \underline{n} dA$$

use $\underline{v} = \rho \underline{u}$

$$\int \left[\frac{d\rho}{dt} + \operatorname{div}(\rho \underline{u}) \right] dV = 0$$

This is ~~an~~ an integral over a fixed but arbitrary volume. If the integrand is zero for any volume then

$$\frac{d\rho}{dt} + \operatorname{div}(\rho \underline{u}) = 0$$

pointwise.