

• Steady

• $v = v_\phi(r) e_\phi$

$v_\phi = v$

• $\frac{\partial v}{\partial t} = 0$

• $\frac{\partial v}{\partial \phi} = 0$

• $\nabla p = 0$

• conti ✓

• axial comp. of mom. eqn ✓

• azimuthal:

$$0 = \nu \left(\nabla^2 v - \frac{v}{r^2} \right)$$

$$0 = \underbrace{V \left(\frac{d^2 u}{dr^2} + r \frac{du}{dr} \right)}_{\Delta^2 u(r)} - \frac{u}{r^2} \quad (2)$$

$$\boxed{r^2 \frac{d^2 u}{dr^2} + r \frac{du}{dr} - u = 0}$$

non-const. coeff. 2nd order linear ODE for $u(r)$.

Ansatz:

$$u(r) \sim r^\lambda$$

in ODE:

$$r^2 \lambda(\lambda-1) r^{\lambda-2} + r \lambda r^{\lambda-1} - r^\lambda \stackrel{!}{=} 0$$

$$r^\lambda \underbrace{(\lambda(\lambda-1) + \lambda - 1)}_{=0} \stackrel{!}{=} 0$$

$$\lambda^2 - 1 = 0$$

$$\lambda = \pm 1$$

But: Check δ -mom. (3)

eqn: \circ ($\Delta p = 0$)

$$\dots - \frac{v^2}{r} = - \frac{1}{\rho} \frac{dp}{dr} + \dots$$

Doesn't work because our ansatz that $\Delta p = 0$ was wrong.

Fix: Allow $p = p(r)$

Luckily, this does not affect any of the other eqns. So can simply integrate p from

$$\frac{dp}{dr} = \rho \frac{v^2(r)}{r} \quad \text{known!}$$

(centrifugal effect).

Gen. form:

$$u(r) = A r + B \frac{1}{r}$$

(4)

BE:



$$u(r=a) = a R_1$$

$$u(r=b) = b R_2$$

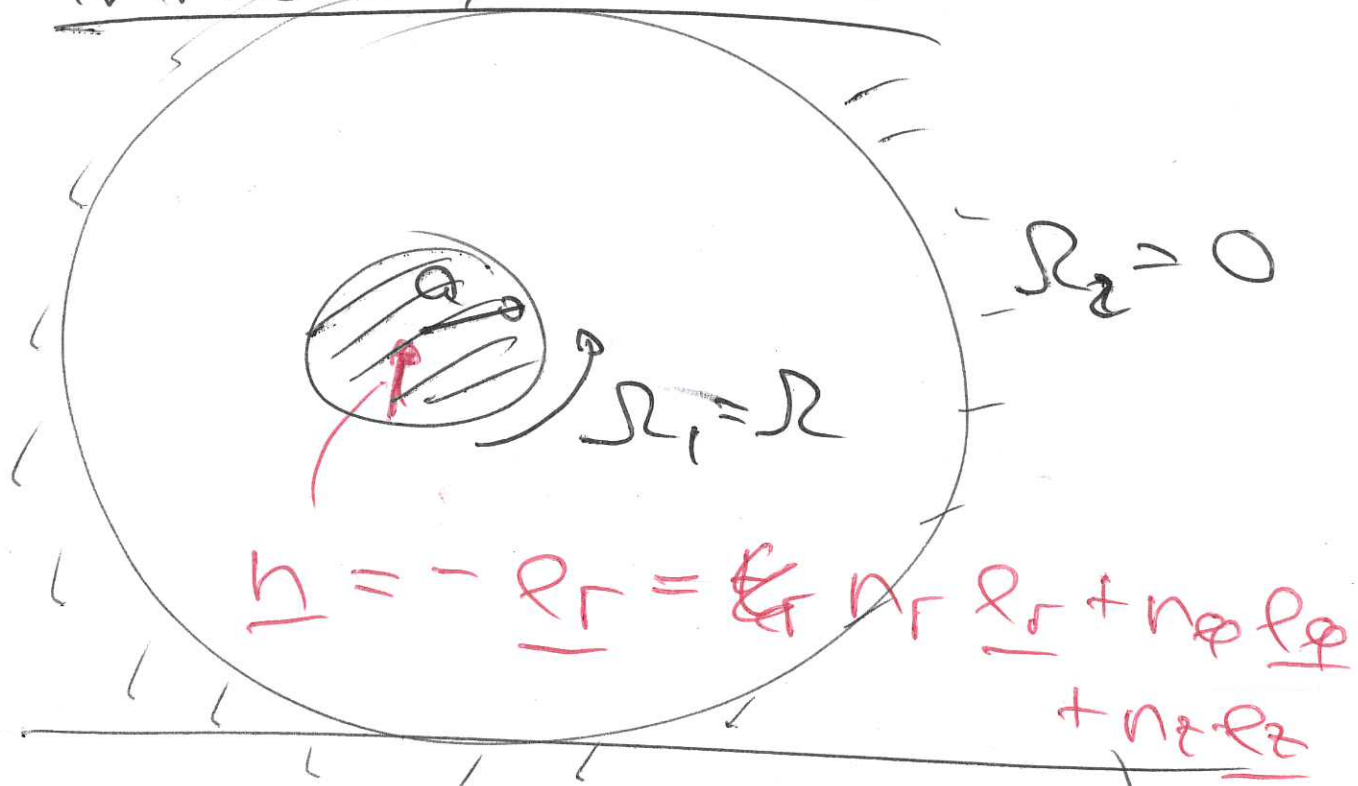
$$u(r) = \frac{1}{b^2 - a^2} \left\{ (b^2 R_2 - a^2 R_1) r - \frac{a^2 b^2 (R_2 - R_1)}{r} \right\}$$

TEST: $R_1 = R_2 = R$

$u(r) = R r$



Traction acting on inner cylinder.



$$\underline{n} = -\underline{e}_r = n_r \underline{e}_r + n_\phi \underline{e}_\phi + n_z \underline{e}_z$$

$$v(r) = \frac{a^2 \Omega}{b^2 - a^2} \left(\frac{b^2}{r} - r \right)$$

Traction on fluid.

$$t_i = \tau_{ij} n_j \quad i, j = r, \phi, z$$

$$\tau_{ij} = -p \delta_{ij} + 2\mu e_{ij}$$

Hand out.

$$\begin{aligned} n_r &= -1 \\ n_\phi &= 0 \\ n_z &= 0 \end{aligned}$$

$$u = u_r = 0 \quad u_\phi = v = v(r)$$

$$w = u_z = 0$$

~~$$\epsilon_{rr} = \frac{\partial u}{\partial r} \quad \epsilon_{\phi\phi} = \frac{1}{r} \frac{\partial v}{\partial \phi} + \frac{v}{r}$$~~

~~$$\epsilon_{zz} = \frac{\partial w}{\partial z} \quad \epsilon_{r\phi} = \frac{1}{2} \left[r \frac{\partial}{\partial r} \left(\frac{v}{r} \right) + \frac{1}{r} \frac{\partial u}{\partial \phi} \right]$$~~

~~$$\epsilon_{\phi z} = \frac{1}{2} \left[\frac{1}{r} \frac{\partial w}{\partial \phi} + \frac{\partial v}{\partial z} \right] \quad \epsilon_{rz} = \frac{1}{2} \left[\frac{\partial u}{\partial z} + \frac{\partial w}{\partial r} \right]$$~~

From handbook:

(2)

Only $e_{r\phi} = \frac{1}{2} r \frac{d}{dr} \left(\frac{u(r)}{r} \right)$
is nonzero.

$$e_{r\phi} = - \frac{a^2 b^2 \Omega}{b^2 - a^2} \frac{1}{r^2}$$

at $r = a$:

$$e_{r\phi} = - \frac{b^2 \Omega}{b^2 - a^2}$$

$$t_i = -p n_i + 2\mu e_{ij} n_j$$

$i = \begin{matrix} r \\ \phi \end{matrix}$

$$t_r = -p n_r + 2\mu (e_{rr} n_r + e_{r\phi} n_\phi + e_{\phi r} n_r + e_{\phi\phi} n_\phi)$$

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$$\underline{\underline{t_r = p(r=a)}}$$

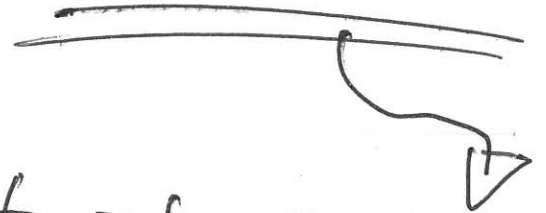
$$i = \varphi$$

(P)

$$t_{\varphi} = -\cancel{pr_{\varphi}} + 2\mu \left(\cancel{e_{\varphi} r_{\varphi}} + \cancel{e_{\varphi} r_{\varphi}} + \cancel{e_{\varphi} r_{\varphi}} \right)$$

$$\underline{t_{\varphi}} = -2\mu e_{\varphi} r \Big|_{r=a} = 2\mu \frac{b^2 \Omega}{b^2 - a^2}$$

$$i = z$$



$$\underline{t_z = 0}$$

$$\underline{t} = \underline{t_r} e_r + \underline{t_{\varphi}} e_{\varphi}$$

$p(r=a)$

