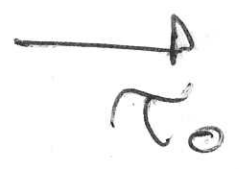




$u(z, t)$



$$\frac{\partial u}{\partial t} = \nu \frac{\partial^2 u}{\partial z^2}$$

$$\underline{u} = -\underline{v} = -\underline{v}$$

$$\underline{u} = n_1 e_1 + n_2 e_2$$

$$n_1 = 0$$

$$n_2 = -1$$

$$t_i = \tau_{ij} n_j$$

$$t_1 = \tau_0$$

$$t_2 = 0$$

⋮

BC

$$\tau_0 = -\mu \frac{\partial u}{\partial z}$$

at $z = 0$

$$u \rightarrow 0 \text{ as } z \rightarrow \infty$$

IC: $u(z, t=0) = 0$

(2)

$$\frac{\partial u}{\partial t} = \nu \frac{\partial^2 u}{\partial z^2}$$

$$\tau_0 = -\mu \frac{\partial u}{\partial z} \quad \text{at } z=0$$

$$u \rightarrow 0 \quad \text{as } z \rightarrow \infty$$

$$u(t=0) = 0$$

\Rightarrow u must be linear in τ_0

$$u(z, t; \nu, \tau_0, \mu)$$

$$\Rightarrow u = \tau_0 F(z, t; \nu, \mu)$$

$$[u] = \frac{m}{sec} \quad [\nu] = \frac{m^2}{sec} \quad [z] = m$$

$$[\tau_0] = \frac{kg}{m sec^2} \quad [\mu] = \frac{m^2}{sec} \quad [z] = m$$

$$[t] = sec$$

$$u = \kappa_0 F(\gamma, t; \nu, g)$$

(3)

kill the κ_0 in κ_0

$$u = \frac{\kappa_0}{g} G(\gamma, t; \nu, g)$$

$$\left[\frac{\kappa_0}{g} \right] = \frac{m^2}{\text{sec}^2}$$

must
retain g
here!

[cannot take sqrt
because we want soln
to be linear in κ_0 !]

Need to form a combin.
of parameters with dim $\frac{m}{\text{sec}}$
from γ, t, ν, g

Option 1: $\frac{\gamma}{t}$ but this
would ruin the sim.
soln form.

Option 2: $\sqrt{\frac{P}{\rho}}$

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$$u = \frac{\sqrt{2} c_0}{5} \sqrt{\frac{t}{\rho}} f(\zeta, t; \rho, S)$$

dim: $\frac{m}{sec}$

$\zeta = \frac{z}{\sqrt{t}}$

f must be a nondim
 fct. of its arguments

\Rightarrow f cannot depend
 on S.

$$\zeta = \frac{z}{\sqrt{t}}$$

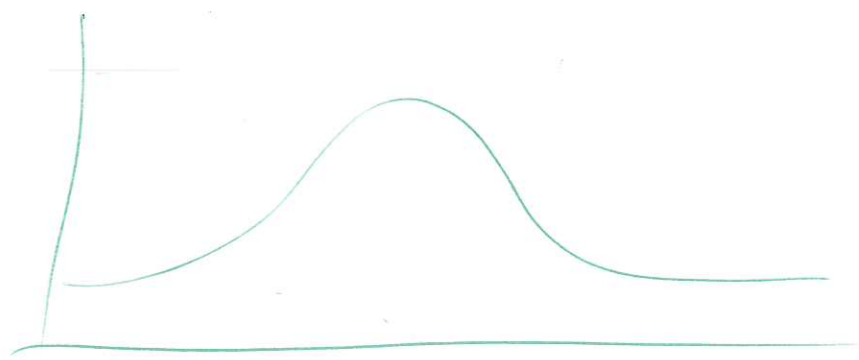
$$u = \frac{\sqrt{2} c_0}{5} \sqrt{\frac{t}{\rho}} f\left(\frac{z}{\sqrt{t}}\right)$$

$$\alpha \frac{dy}{dt} = \alpha \frac{dy}{dy}$$

$$\alpha \hat{u} \rightarrow 0 \quad \alpha, \gamma \rightarrow \infty$$

$$\alpha \hat{u} \rightarrow \infty \quad \alpha \text{ of } t \rightarrow 0$$

$$u(y,t) = a(t) f\left(\frac{y}{b(t)}\right)$$



$$\frac{t_0}{\delta} \frac{t}{\gamma} \hat{f}(y, t, y, \delta)$$

$\underbrace{\hspace{10em}}_{a(t)}$