

# Fluid mechanics

(1)

3 steps: (I) Describe (mathematically) the flow field / motion of fluid particles.

(KINEMATICS)

(II) Formulate the eqns of motion: Newton's law applied to continua. (Stresses)

(III) Constitutive eqns relate kinematics to the stresses.

} The Navier Stokes eqns.

Then: Lots of examples.

## § 2 Kinematics

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### The Eulerian flow field

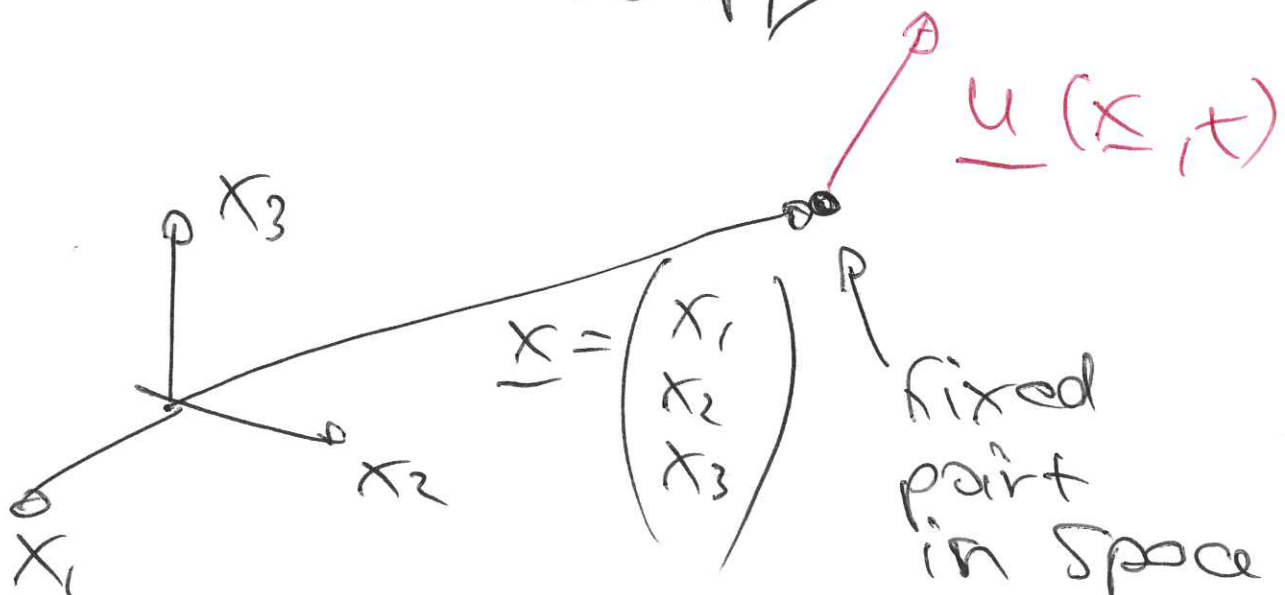
Assume we know the velocity  $\underline{u}$  as a fun of the 3 Cartesian coords  $(x_1, x_2, x_3) = (x, y, z)$  and time  $t$ .

$$\underline{u} = \underline{u}(x_1, x_2, x_3, t) = \underline{u}(\underline{x}, t)$$

or

$$u_i = u_i(x_j, t)$$

↑  
stays



Note: At different times (3) different material particles will be at point x.

This is important!

E.g.: Acceleration of fluid particles.

The material derivative.

Now follow a particle whose instantaneous position is given by the particle path:

$$\underline{x} = \underline{x}^P(t) = \begin{pmatrix} x_1^P(t) \\ x_2^P(t) \\ x_3^P(t) \end{pmatrix}$$

Its velocity is:

$$\underline{u}(x_1, x_2, x_3, t) = \underline{u}(x_1^P(t), x_2^P(t), x_3^P(t), t)$$

Accel. of the particle(!) is  
the rate of change of  $u$

$$\frac{du}{dt} = \frac{du(x_1^p(t), x_2^p(t), x_3^p(t), t)}{dt}$$

$$= \frac{\partial u}{\partial t} + \frac{\partial u}{\partial x_1} \frac{dx_1^p}{dt} + \frac{\partial u}{\partial x_2} \frac{dx_2^p}{dt} + \frac{\partial u}{\partial x_3} \frac{dx_3^p}{dt}$$

$$\frac{du_i}{dt} = \frac{\partial u_i}{\partial t} + \underbrace{\frac{\partial u_i}{\partial x_j} \frac{dx_j^p}{dt}}_{u_j}$$

$$\frac{du_i}{dt} = \frac{\partial u_i}{\partial t} + u_j \frac{\partial u_i}{\partial x_j}$$

Symbolic:

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$$\frac{d\underline{u}}{dt} = \frac{\partial \underline{u}}{\partial t} + \underline{u} \cdot \nabla \underline{u}$$

This is often denoted by

$$\frac{D\underline{u}}{Dt}$$

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The rate of strain tensor & the vorticity

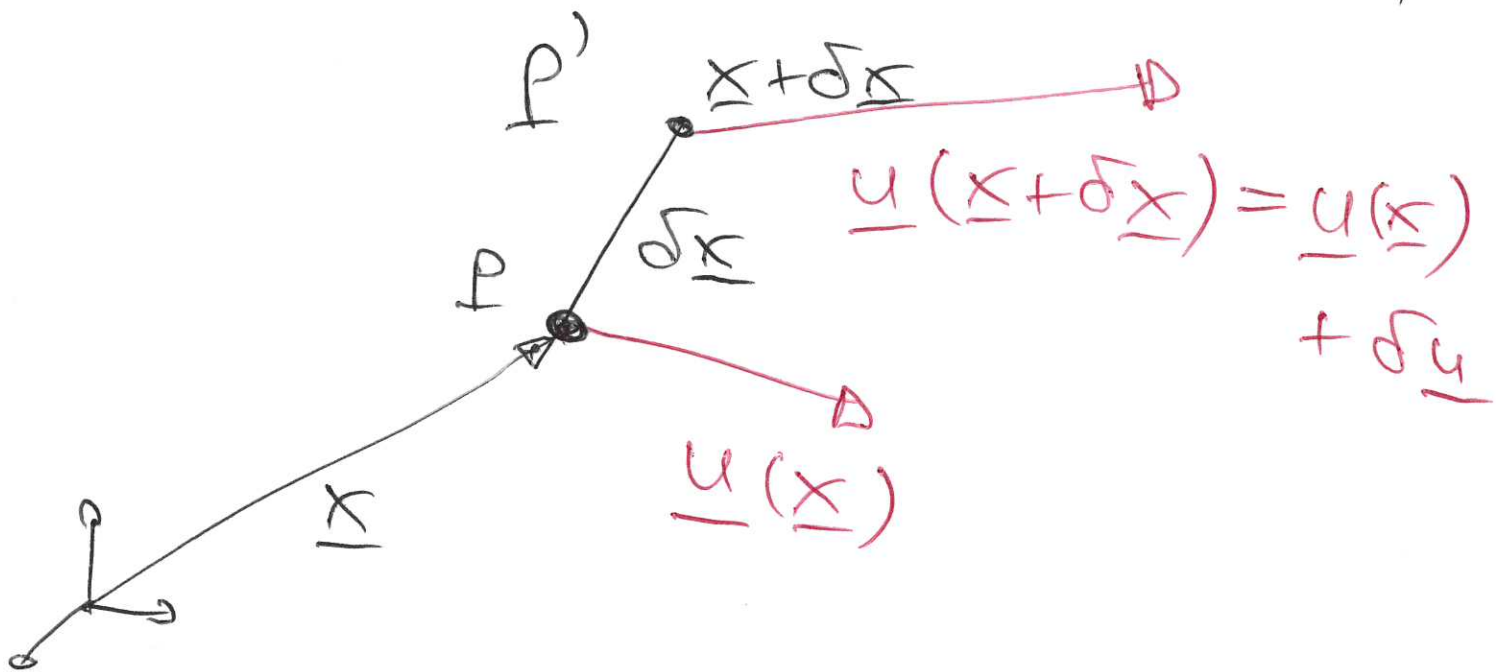
Velocity field in itself is not that interesting. It contains:

- translation
- rotation
- shearing
- dilation

How do we identify these?

Examine veloc. field (6)  
in the vicinity of a given  
point  $P$ :

$$\|\delta \underline{x}\| \ll 1$$



$$\underline{u}(\underline{x} + \delta \underline{x}) = \underline{u}(x_1 + \delta x_1, x_2 + \delta x_2, x_3 + \delta x_3)$$

Taylor expansion

$$= \underline{u}(x_1, x_2, x_3) + \frac{\partial \underline{u}}{\partial x_1} \delta x_1 + \frac{\partial \underline{u}}{\partial x_2} \delta x_2 +$$

$$\frac{\partial \underline{u}}{\partial x_3} \delta x_3 + \dots \quad O(|\delta \underline{x}|^2)$$

$$\underbrace{\underline{u}(\underline{x} + \delta \underline{x}) - \underline{u}(\underline{x})}_{\delta \underline{u}} = \frac{\partial \underline{u}}{\partial x_j} \delta x_j + \dots$$

Now as  $|\delta x| \rightarrow 0$

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$$\delta x \Rightarrow D dx$$

$$du_i = \frac{\partial u_i}{\partial x_j} dx_j$$

velocity  
gradient  
tensor

(3x3 matrix).