

1st order linear ODEs

(1)

$$y' + p(x)y = q(x)$$

$$y' + \underbrace{x}_{p(x)} y = \underbrace{x}_{q(x)}$$

$$y(x) = -1 + C e^{\frac{x^2}{2}}$$

Note: Soln. has two parts

$$y = y_p + y_h$$

y_p = a(ny) particular soln of the full ODE

y_h = general soln. of the homogeneous ODE, i.e. the ODE for $q'(x) = 0$

In our example:

(2)

- $y_p = -1$ does it solve the full ODE?

$$y_p' = 0$$

in the ODE:

$$y_p' - x y_p \stackrel{?}{=} x$$

$$(-x)(-1) = x \quad \checkmark$$

- $y_H = c \exp\left(\frac{x^2}{2}\right)$ is this the most general soln. of homog. ODE?

$$y_H' - x y_H \stackrel{?}{=} 0$$

soln. of homog. ODE

$$\frac{dy_H}{dx} - x y_H = 0$$

$$\int \frac{1}{y_H} dy_H = \int x dx$$

$$\ln|y_H| = \frac{1}{2}x^2 + A$$

$$y_H = \exp\left(\frac{1}{2}x^2 + A\right)$$

$$y_H = c \exp\left(\frac{1}{2}x^2\right)$$

This structure of the soln. is always the same for linear ODEs.

§4 2nd order ODEs

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$$F(x, y, y', y'') = 0$$

+ 2 BC or 2 ICs

(slides)

Some theory for *linear* 2nd order ODEs

Existence and Uniqueness

Consider the *linear* second-order ODE

$$y'' + p(x)y' + q(x)y = r(x), \quad (1)$$

subject to the initial conditions

$$y(X) = Y, \quad y'(X) = Z, \quad (2)$$

where the constants X, Y and Z , and the functions $p(x)$, $q(x)$ and $r(x)$ are given.

Theorem

If the functions $p(x)$, $q(x)$ and $r(x)$ are continuous functions of x in an interval I , and if $X \in I$ then there **exists exactly one** solution to the initial value problem defined by (1) and (2) in the entire interval I .

Notes:

- This is the promised extension of the statement for first-order problems. The extension to even higher-order linear ODEs should be obvious...
- If the functions $p(x)$, $q(x)$ and $r(x)$ are “well-behaved” (no jumps, singularities, etc.), the theorem guarantees the existence of a unique solution for $x \in \mathbb{R}$.
- However, the statement still only applies to initial value problems!

The homogeneous ODE & superposition of its solutions

If we set $r(x) = 0$ in the *inhomogeneous* ODE

$$y'' + p(x)y' + q(x)y = r(x), \quad (\text{I})$$

we obtain the corresponding *homogeneous* ODE

$$y'' + p(x)y' + q(x)y = 0. \quad (\text{H})$$

A trivial (?) but useful observation

If $y_1(x)$ and $y_2(x)$ are two solutions of (H) then the linear combination

$$y_3(x) = A y_1(x) + B y_2(x)$$

is also a solution, for any values of the constants A and B .

Linear independence

To see why this is a useful observation, we need to define the concept of linear independence: Two nonzero functions $y_1(x)$ and $y_2(x)$ are linearly independent if

$$A y_1(x) + B y_2(x) = 0 \quad \forall x \quad \iff \quad A \equiv B \equiv 0$$

(...just as in linear algebra...).

Examples:

- $y_1(x) = x$ and $y_2(x) = 3x^2$ are linearly independent.
- $y_1(x) = x$ and $y_2(x) = 3x$ are linearly dependent – they're just multiples of each other.

$$y'' + p y' + q y = \textcircled{0} \quad (H) \quad (4)$$

Claim: if y_1 & y_2 are
sols of (H) then
 $A y_1 + B y_2$ is also a
soln.

Proof:

$$y = A y_1 + B y_2$$

$$y' = A y_1' + B y_2'$$

$$y'' = A y_1'' + B y_2''$$

into ODE:

$$\underbrace{A y_1'' + B y_2''}_{\text{v.2}} + \underbrace{p A y_1' + p B y_2'}_{\text{v.2}} + \underbrace{q A y_1 + q B y_2}_{\text{v.2}} = 0$$

$$A \underbrace{(y_1'' + p y_1' + q y_1)}_0 + B \underbrace{(y_2'' + p y_2' + q y_2)}_0 = 0$$



Lin. indep:

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$$f_1 = x \quad f_2 = 3x^2$$

$$A f_1 + B f_2 = 0 \quad \forall x$$

$$A x + 3B x^2 = 0 \quad \forall x$$

check for

$$x=1: \quad A + 3B = 0$$

$$x=-1: \quad -A + 3B = 0$$

$$6B = 0 \Rightarrow B = 0$$

$$A = 0$$

\Rightarrow lin. indep!

$$f_1 = x \quad f_2 = 3x$$

$$A f_1 + B f_2 = 0 \quad \forall x$$

$$A x + 3B x = 0 \quad \forall x$$

$$x(A + 3B) = 0 \quad \forall x$$

$$A = -3B$$

$$B = 1$$

$$A = -3$$

\Rightarrow lin. dependent!

Fundamental solutions of the homogeneous ODE

Theorem

Any solution of the homogeneous ODE

$$y'' + p(x)y' + q(x)y = 0. \quad (\text{H})$$

can be written as a linear combination of *any* two non-zero, linearly independent solutions, $y_1(x)$ and $y_2(x)$, say:

$$y(x) = A y_1(x) + B y_2(x).$$

The two non-zero, linearly independent solutions $\{y_1(x), y_2(x)\}$ are called “fundamental solutions” of the homogeneous ODE (H).

Notes:

- The set of fundamental solutions is not unique!

The general solution of the inhomogeneous ODE

Theorem

The *general* solution of the inhomogeneous ODE

$$y'' + p(x)y' + q(x)y = r(x) \quad (I)$$

can be written as

$$y(x) = y_p(x) + A y_1(x) + B y_2(x),$$

where:

- A and B are arbitrary constants.
- $y_p(x)$ is any particular solution of the inhomogeneous ODE.
- $y_1(x)$ and $y_2(x)$ are fundamental solutions of the corresponding homogeneous ODE.

Notes:

- Note the similarities between the structure of the solution of the linear ODE and the structure of the solution of the linear (algebraic) equation $\mathbf{Ax} = \mathbf{b}$. This is not accidental! There are deep connections between the two fields – matrices and the homogeneous part of a linear ODE are both “linear operators”.
- The values of the constants A and B are determined by the boundary or initial conditions.

Example:

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$$y'' + \underbrace{\frac{1}{x}}_{p(x)} y' - \underbrace{\frac{1}{x^2}}_{q(x)} y = - \underbrace{\frac{1}{x^2}}_{r(x)}$$

IC:

$$y(x=1) = 1$$

$$y'(x=1) = 1$$

$\bar{x} = 1, \bar{y} = 1, \bar{z} = 1$

$$\left. \begin{aligned} p(x) &= \frac{1}{x} \\ q(x) &= -\frac{1}{x^2} \\ r(x) &= -\frac{1}{x^2} \end{aligned} \right\}$$

p, q, r are
cont. fcts of x
in $I_1 = \mathbb{R}^+$
 $I_2 = \mathbb{R}^-$

$$\bar{x} \in I_1$$

\Rightarrow There exists a unique
soln of IVP in I_1 .

gP:

$$\begin{aligned}
 g_P &= 1 \\
 g_P' &= 0 \\
 g_P'' &= 0
 \end{aligned}$$

$$\frac{g_P''}{x^2} + \frac{g_P'}{x} - \frac{g_P}{x^2} \approx 0 - \frac{1}{x^2}$$



gH:

$$g_1 = x \quad \checkmark$$

$$g_2 = \frac{1}{x} \quad \checkmark \quad \text{EXERCISE}$$

$$\begin{aligned}
 g_1 &= x \\
 g_1' &= 1 \\
 g_1'' &= 0
 \end{aligned}$$

homog.

$$\frac{g_1''}{x^2} + \frac{g_1'}{x} - \frac{g_1}{x^2} \approx 0 + \frac{1}{x} - \frac{x}{x^2}$$

$$\frac{1}{x} - \frac{1}{x} = 0 \quad \checkmark$$

y_1 & y_2

Solve (H)

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& are nonzero

Are they lin. indep.:

$$Ay_1 + By_2 = 0 \quad \forall x$$

$$Ax + B \frac{1}{x} = 0 \quad \forall x$$

$$x=1: \quad A + B = 0$$

$$x=2 \quad 2A + \frac{1}{2}B = 0$$

$$-4A + B = 0$$

$$\Rightarrow -3A = 0 \Rightarrow A = 0$$

$$\Downarrow \\ B = 0$$

y_1 & y_2 are nonzero, lin. indep. solns of (H)

$\{x, \frac{1}{x}\}$ are fundamental solns. of (H)

Gen. soln. is:

$$y(x) = \underbrace{1}_{y_p} + A \underbrace{x}_{y_1} + B \underbrace{\frac{1}{x}}_{y_2}$$

Apply ICs to find the unique soln of IVP

$$\left. \begin{aligned} y(x=1) &= 1 \\ y'(x=1) &= 1 \end{aligned} \right\} \dots \begin{aligned} A &= \frac{1}{2} \\ B &= -\frac{1}{2} \end{aligned} \text{ (exercise)}$$

$$y(x) = 1 + \frac{1}{2}x - \frac{1}{2x}$$

Note: soln does blow up @ $x=0$.

Q: How can we obtain a unique soln even though y_p , y_1 & y_2 were not unique.

Redo with..

$$y_p = 1 + x$$

(check or exercise!)
it solves the full ODE

$$y_1 = x$$

$$y_2 = x + \frac{2}{x}$$

EXERCISE:
 y_1 & y_2 are lin. indep nonzero solns of (H)

Gen. soln is

$$y = \underbrace{1+x}_{y_p} + C \underbrace{x}_{y_1} + D \underbrace{\left(x + \frac{2}{x}\right)}_{y_2}$$

apply ICs to this form 11
of the soln

$$\left. \begin{array}{l} y(x=1) = 1 \\ y'(x=1) = 1 \end{array} \right\} \dots \quad C = 0 = -\frac{1}{4}$$

↑
EXERCISE

$$y(x) = \underbrace{(1+x)}_{f_0} - \underbrace{\frac{1}{4}x}_{f_1} - \frac{1}{4} \underbrace{\left(x + \frac{2}{x}\right)}_{f_2}$$

$$= 1 + \frac{1}{2}x - \frac{1}{2x} \quad \text{as before.}'$$

Note: E & U theorem
guaranteed E & U of
the soln for $x > 0$.
Indeed here soln has
a singularity at $x = 0$

But the EFT theorem (12)
does not say that there
will be a singularity
at $x=0$. Depends on
IC.

For example:

$$\left. \begin{aligned} y(x=1) &= \frac{3}{2} \\ y'(x=1) &= \frac{1}{2} \end{aligned} \right\} \dots \quad \begin{aligned} A &= \frac{1}{2} \\ B &= 0 \end{aligned}$$

$$\hookrightarrow y = 1 + \frac{1}{2}x$$

This actually exists for
all values of $x \in \mathbb{R}$.