

$$y' - xy = x$$

$$y' + p(x)y = q(x)$$

Gen. soln:

$$y(x) = \underbrace{-1}_{y_p} + \underbrace{C \exp\left(\frac{1}{2}x^2\right)}_{y_H}$$

Observation:

The general soln has two parts:

$$y = y_p + y_H$$

$y_p = a(ny)$ particular soln of the full ODE

$y_H =$ general soln of the homogeneous ODE, i.e. the ODE for $q(x) = 0$.

In our example:

$y_p = -1$ into ODE:
 $y_p' = 0$
 $(-x)/(-1) \stackrel{?}{=} x \quad \checkmark$
 $y' - xy = x$

$$y_H: \\ y_H' - x y_H = 0$$

$$\frac{dy_H}{dx} = x y_H$$

$$\int \frac{1}{y_H} dy_H = \int x dx$$

$$\ln|y_H| = \frac{1}{2} x^2 + A$$

$$y_H = \exp\left(A + \frac{1}{2} x^2\right)$$

$$= \underbrace{\exp(A)}_C \exp\left(\frac{1}{2} x^2\right)$$

$$\underline{y_H = C \exp\left(\frac{1}{2} x^2\right)}$$

This structure is general for all linear ODEs.



Some theory for *linear* 2nd order ODEs

Existence and Uniqueness

Consider the *linear* second-order ODE

$$y'' + p(x)y' + q(x)y = r(x), \quad (1)$$

subject to the initial conditions

$$y(X) = Y, \quad y'(X) = Z, \quad (2)$$

where the constants X, Y and Z , and the functions $p(x)$, $q(x)$ and $r(x)$ are given.

Theorem

If the functions $p(x)$, $q(x)$ and $r(x)$ are continuous functions of x in an interval I , and if $X \in I$ then there **exists exactly one** solution to the initial value problem defined by (1) and (2) in the entire interval I .

Notes:

- This is the promised extension of the statement for first-order problems. The extension to even higher-order linear ODEs should be obvious...
- If the functions $p(x)$, $q(x)$ and $r(x)$ are “well-behaved” (no jumps, singularities, etc.), the theorem guarantees the existence of a unique solution for $x \in \mathbb{R}$.
- However, the statement still only applies to initial value problems!



The homogeneous ODE & superposition of its solutions

If we set $r(x) = 0$ in the *inhomogeneous* ODE

$$y'' + p(x)y' + q(x)y = r(x), \quad (\text{I})$$

we obtain the corresponding *homogeneous* ODE

$$y'' + p(x)y' + q(x)y = 0. \quad (\text{H})$$

A trivial (?) but useful observation

If $y_1(x)$ and $y_2(x)$ are two solutions of (H) then the linear combination

$$y_3(x) = A y_1(x) + B y_2(x)$$

is also a solution, for any values of the constants A and B .

Linear independence

To see why this is a useful observation, we need to define the concept of linear independence: Two nonzero functions $y_1(x)$ and $y_2(x)$ are linearly independent if

$$A y_1(x) + B y_2(x) = 0 \quad \forall x \quad \iff \quad A \equiv B \equiv 0$$

(...just as in linear algebra...).

Examples:

- $y_1(x) = x$ and $y_2(x) = 3x^2$ are linearly independent.
- $y_1(x) = x$ and $y_2(x) = 3x$ are linearly dependent – they're just multiples of each other.

$$y'' + py' + qy = 0$$

(5)

y_1 & y_2 are solns.

Claim: $y = Ay_1 + By_2$ is also a soln.

Proof: Into ODE:

$$y' = Ay_1' + By_2'$$

$$y'' = Ay_1'' + By_2''$$

$$\underbrace{Ay_1'' + By_2''}_{y''} + p \underbrace{(Ay_1' + By_2')}_{y'} + q \underbrace{(Ay_1 + By_2)}_y$$

$\begin{matrix} ? \\ \neq 0 \end{matrix}$

collect A & B:

$$\cancel{A(y_1'' + py_1' + qy_1)} \neq \cancel{B(y_2'' + py_2' + qy_2)}$$

$\begin{matrix} ? \\ \neq 0 \end{matrix}$



$$f_1 = x; \quad f_2 = 3x^2$$

(6)

$$A \underbrace{x}_{f_1} + B \underbrace{3x^2}_{f_2} = 0 \quad \forall x$$

Check for some random points:

$$\underline{x=1}: \quad A + 3B = 0$$

$$\underline{x=-1}: \quad -A + 3B = 0$$

$$6B = 0 \Rightarrow B = 0$$

$$A = 0$$

$\Rightarrow f_1$ & f_2 are lin. indep.

$$f_1 = x; \quad f_2 = 3x$$

$$A f_1 + B f_2 = 0$$

$$A x + B 3x = 0$$

$$x(A + 3B) = 0 \quad \forall x$$

$$\text{e.g. } B=1, A=-3$$

$\Rightarrow y_1$ & y_2 are lin. dep. ! (7)



Fundamental solutions of the homogeneous ODE

Theorem

Any solution of the homogeneous ODE

$$y'' + p(x)y' + q(x)y = 0. \quad (\text{H})$$

can be written as a linear combination of *any* two non-zero, linearly independent solutions, $y_1(x)$ and $y_2(x)$, say:

$$y(x) = A y_1(x) + B y_2(x).$$

The two non-zero, linearly independent solutions $\{y_1(x), y_2(x)\}$ are called “fundamental solutions” of the homogeneous ODE (H).

Notes:

- The set of fundamental solutions is not unique!

The general solution of the inhomogeneous ODE

Theorem

The *general* solution of the inhomogeneous ODE

$$y'' + p(x)y' + q(x)y = r(x) \quad (\text{I})$$

can be written as

$$y(x) = y_p(x) + A y_1(x) + B y_2(x),$$

where:

- A and B are arbitrary constants.
- $y_p(x)$ is any particular solution of the inhomogeneous ODE.
- $y_1(x)$ and $y_2(x)$ are fundamental solutions of the corresponding homogeneous ODE.

Notes:

- Note the similarities between the structure of the solution of the linear ODE and the structure of the solution of the linear (algebraic) equation $\mathbf{Ax} = \mathbf{b}$. This is not accidental! There are deep connections between the two fields – matrices and the homogeneous part of a linear ODE are both “linear operators”.
- The values of the constants A and B are determined by the boundary or initial conditions.

Example:

$$y'' + \underbrace{\frac{1}{x}}_p y' - \underbrace{\frac{1}{x^2}}_q y = \underbrace{-\frac{1}{x^2}}_r$$

IC: $y(1) = 1$

$$y'(1) = 1$$

$$x > 1$$

$$p(x) = \frac{1}{x}$$

$$q(x) = -\frac{1}{x^2}$$

$$r(x) = -\frac{1}{x^2}$$

continuous fcts
of x in

$$I = \mathbb{R}^+$$

\Rightarrow unique soln
exists for

$$x \in \mathbb{R}^+$$

• particular soln:

$$y_p = 1$$