MAGIC: Ergodic Theory Lecture 3 - Invariant Measures

Charles Walkden

February 6th 2013

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In this lecture:

- we give some basics about measure theory
- define and study invariant measures and measure-preserving transformations.

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Examples

- 1. The trivial σ -algebra: $\mathcal{B} = \{\emptyset, X\}$.
- 2. The full σ -algebra: $\mathcal{B} = \mathcal{P}(X) = \{ \text{all subsets of } X \}.$
- 3. Let X be a compact metric space. The Borel σ -algebra is the smallest σ -algebra that contains every open set.

A measure is a function $\mu: \mathcal{B} \to \mathbb{R}^+ \cup \{\infty\}$ such that

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(Example: a.e. real number is irrational w.r.t. Lebesgue measure the rationals have measure zero.)

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Let $f = \sum_{j=1}^{r} c_j \chi_{B_j}$, $c_j \ge 0$, $B_j \in \mathcal{B}$, be a simple function.



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Define $\int f d\mu = \sum_{j=1}^{r} c_j \mu(B_j)$.

A function $f : X \longrightarrow \mathbb{R}$ is *measurable* if $f^{-1}(-\infty, c) = \{x \in X \mid f(x) < c\} \in \mathcal{B} \ \forall c \in \mathbb{R}.$

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$$\begin{array}{rcl} f_+ &=& \max\{f,0\} \geq 0, \\ f_- &=& \max\{-f,0\} \geq 0. \end{array}$$

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We can also work with complex functions by taking real and imaginary parts.
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A is an algebra of subsets of X.
μ: A → ℝ⁺ ∪ {∞} is a function such that

μ(∅) = 0,
if A_n ∈ A, pairwise disjoint, U[∞]_{n=1} A_n ∈ A, then μ(U[∞]_{n=1} A_n) = ∑[∞]_{n=1} μ(A_n),
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Then: there exists a *unique* measure $\mu : \mathcal{B}(\mathcal{A}) \longrightarrow \mathbb{R}^+ \cup \{\infty\}$ that extends $\mu : \mathcal{A} \longrightarrow \mathbb{R}^+ \cup \{\infty\}$.

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Lebesgue Measure X = [0, 1] or \mathbb{R}/\mathbb{Z} $\mathcal{A} = \{\text{finite unions of intervals}\}$ $\mu[a, b] = b - a$

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Higher dimensional Lebesgue Measure $X = \mathbb{R}^k / \mathbb{Z}^k$ $\mathcal{A} = \{\text{finite unions of } k\text{-dimensional cubes}\}$ $\mu([a_1, b_1] \times \cdots \times [a_k, b_k]) = (b_1 - a_1) \times \cdots \times (b_k - a_k)$

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The Kolmogorov Extension Theorem gives k-dimensional Lebesgue measure on the k-dimensional torus.

$$\mu(ext{rectangle}) = (b_1 - a_1) imes (b_2 - a_2)$$

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We illustrate that Stieltjes measures can be surprisingly complicated.

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Fact: If $\rho'(x)$ is continuous then $\mu_{\rho} \ll$ Lebesgue. If in addition, $\rho'(x) > 0$, then μ_{ρ} and Lebesgue measure are equivalent.

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Fact: If $\rho'(x)$ is continuous then $\mu_{\rho} \ll$ Lebesgue. If in addition, $\rho'(x) > 0$, then μ_{ρ} and Lebesgue measure are equivalent. Gauss' measure and Lebesgue measure are equivalent $(\rho'(x) = \frac{1}{\log 2} \frac{1}{1+x})$.

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Note that $\delta_x(X \setminus \{x\}) = 0$. Hence δ_x -a.e. point of X is equal to x. For this reason δ_x is sometimes called a *point mass* at x. Easy check: $\int f \, d\delta_x = f(x)$.

Invariant Measures

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T is measurable if $T^{-1}B = \{x \in X \mid T(x) \in B\} \in \mathcal{B} \forall B \in \mathcal{B}.$

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Lemma

T is a mpt
$$\Longleftrightarrow \int f \circ T \, d\mu = \int f \, d\mu \; \forall f \in L^1(X, \mathcal{B}, \mu)$$

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Lemma

T is a mpt
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Remark: We can replace L^1 by L^2 .

$$T \text{ mpt } \iff \mu(T^{-1}B) = \mu(B) \ \forall B \in \mathcal{B}$$

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We describe three methods for proving a given measure is invariant for a given dynamical system.

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- Using periodic points.
- Using the Kolmogorov Extension Theorem.
- (When X is a group) using Haar measure.

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$$\int f \circ T \, d\mu = \frac{1}{n} (f(Tx) + \dots + f(T^{n-1}x) + f(T^nx))$$

= $\frac{1}{n} (f(x) + f(Tx) + \dots + f(T^{n-1}x))$
= $\int f \, d\mu.$

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Then μ is *T*-invariant $\iff T_*\mu(B) = \mu(B) \ \forall B \in \mathcal{B}$. To show $T_*\mu(B) = \mu(B) \ \forall B \in \mathcal{B}$, it is sufficient to prove that $T_*\mu(B) = \mu(B) \ \forall B \in \mathcal{A}$, where \mathcal{A} is an algebra that generates \mathcal{B} . (This is because the Kolmogorov Extension Theorem tells us that a "measure" on \mathcal{A} extends *uniquely* to a measure on \mathcal{B} .)

Let $Tx = 2x \mod 1$ be the doubling map on [0, 1]. Then T preserves Lebesgue measure μ .

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Proof.

It is sufficient to prove that $\mu T^{-1}[a, b] = \mu[a, b]$ for any interval [a, b].

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$$T^{-1}[a, b] = [\frac{a}{2}, \frac{b}{2}] \cup [\frac{a+1}{2}, \frac{b+1}{2}]$$

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$$\mu T^{-1}[a, b] = \frac{b}{2} - \frac{a}{2} + \frac{b+1}{2} - \frac{a+1}{2} = b - a = \mu[a, b] \square$$

$$\mu(B) = \frac{1}{\log 2} \int_B \frac{1}{1+x} \, dx$$

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Definition

Define Gauss' measure μ on [0,1] by

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Proposition

Let $Tx = \frac{1}{x} \mod 1$ be the continued fraction map. Then T preserves Gauss' measure.

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Proposition

Let $Tx = \frac{1}{x} \mod 1$ be the continued fraction map. Then T preserves Gauss' measure.

Proof:

Again, it is sufficient to prove that $\mu T^{-1}[a, b] = \mu[a, b]$ for every interval [a, b].
$$T^{-1}[a,b] = \bigcup_{n=1}^{\infty} \left[\frac{1}{b+n}, \frac{1}{a+n}\right]$$

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$$\mu(T^{-1}[a,b]) = \sum_{n=1}^{\infty} \mu\left(\left[\frac{1}{b+n}, \frac{1}{a+n}\right]\right) = \mu([a,b]).$$

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Let $X = \{1, \ldots, k\}^{\mathbb{N}} = \{(x_j)_{j=0}^{\infty} \mid x_j \in \{1, \ldots, k\}\}$ be the full one-sided *k*-shift.

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$$[i_0, i_1, \ldots, i_{n-1}, i_n] = \{x = (i_0, i_1, \ldots, i_{n-1}, i_n, *, *, *, \cdots)\}$$

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If $P_{i,j} = P_j$ then

$$\mu[i_0,\ldots,i_n]=p_{i_0}p_{i_1}\cdots p_{i_n}.$$

We call μ a *Bernoulli measure*.

Let $\sigma: \Sigma_k \to \Sigma_k$, $(\sigma x)_j = x_{j+1}$, be the full one-sided *k*-shift, *P* be a stochastic matrix, and let *p* be a left probability eigenvector. Then the Markov measure $\mu = \mu_P$ is σ -invariant.

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Proof.

It is sufficient to prove that $\mu(\sigma^{-1}C) = \mu(C)$ for all cylinders C.

Note:

$$\sigma^{-1}([i_0, i_1, \ldots, i_n]) = \bigcup_{i=1}^k [i, i_0, i_1, \ldots, i_{n-1}].$$

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Proposition

Define $T : \mathbb{R}^k / \mathbb{Z}^k$ by $Tx = x + a \mod 1$. Then Lebesgue measure is *T*-invariant.

Let X be a compact group. Let α a group automorphism of X. Define $T(x) = \alpha(x)$.

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Lebesgue measure is an invariant measure for linear toral automorphisms (eg the Cat map).

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Proof.

Let $g \in X$. Note that $T^{-1}(g(B)) = \alpha^{-1}(g)(T^{-1}(B))$.

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Lebesgue measure is an invariant measure for linear toral automorphisms (eg the Cat map).

Proof.

Let $g \in X$. Note that $T^{-1}(g(B)) = \alpha^{-1}(g)(T^{-1}(B))$. Hence

$$T_*\mu(gB) = \mu(T^{-1}g(B)) = \mu(\alpha^{-1}(g)(T^{-1}B)) = \mu(T^{-1}B)$$

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Hence $T_*\mu$ is invariant under any group rotation. By uniqueness of Haar measure, $T_*\mu$ is Haar measure, i.e. $T_*\mu = \mu$.

In the next lecture we define ergodic measures. We will give examples of ergodic measure-preserving transformations.

We will also see how mixing properties of the dynamics imply ergodicity.

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