# MAGIC 010: Ergodic Theory 

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## Course Outline

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- There are 10 lectures.
- Each lecture has:
- a set of slides,
- a set of more detailed notes that contain more information about the material, details of arguments that are only sketched in the slides, and the exercises,
- solutions to selected exercises.
- These will all be available via the Magic website.
- Assessment: take-home exam at the end of the course.


# MAGIC: Ergodic Theory Lecture 1 - Examples of Dynamical Systems 

January 24th 2013

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Alternatively, time could be continuous - in which case a dynamical system is often given by a first order autonomous differential equation.
We will mostly be concerned with discrete dynamical systems.
Let $T: X \rightarrow X$ be a dynamical system. Let $x \in X$. The orbit of $x$ is the set $\left\{T^{n} x \mid n \geq 0\right\}$.

## Example

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Let $\mathbb{T}^{2}=\mathbb{R}^{2} / \mathbb{Z}^{2}$ denote the torus:


Let $X=$ the unit tangent bundle of $\mathbb{T}^{2}$. Then a point $x \in X$ is a pair $x=(p, v)$ :

$$
\begin{aligned}
& p=\text { point on } \mathbb{T}^{2} \\
& v=\text { unit vector at } v .
\end{aligned}
$$





Then there is a unique straight line through $p$ in the direction $v$. We can infinitely extend this line using the identifications. The dynamical system moves the point $x=(p, v)$ along this line at unit speed.


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$x$ is periodic if $T^{n} x=x$ for some $n>0$. We call $n$ the period of $x$. When projected to $\mathbb{T}^{2}$, some orbits are dense:


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Is it enough to assume that the orbits are dense in $X$ ? No.

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$\lim _{n \rightarrow \infty} \frac{1}{n} \sum_{j=0}^{n-1} \chi_{A}\left(T^{j} \times\right)=\frac{\mu(A)}{\mu(X)}$ for $\mu$-almost every point $X$

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Let $T$ be an ergodic measure-preserving transformation of a probability space $(X, \mathcal{B}, \mu)$. Let $f \in L^{1}(X, \mathcal{B}, \mu)$.

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\lim _{n \rightarrow \infty} \frac{1}{n} \sum_{j=0}^{n-1} f\left(T^{j} x\right) \longrightarrow \int f d \mu \quad \quad \mu \text {-a.e. }
$$

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Maps on the Circle and Torus

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Similarly, we write the $k$-dimensional torus as $\mathbb{R}^{k} / \mathbb{Z}^{k}$ with a similar abuse of notation.
Note that both the circle and d-dimensional torus are Abelian groups under addition.

## Rotations

Fix $\alpha \in \mathbb{R}$. Define the map

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T_{\alpha}: \mathbb{R} / \mathbb{Z} \longrightarrow \mathbb{R} / \mathbb{Z}: x \longmapsto x+\alpha \bmod 1
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1. If $\alpha$ is rational ( $\alpha=\frac{p}{q}, p, q$ coprime) then every orbit is periodic with period $q$.
2. If $\alpha$ is irrational then every orbit is dense.

The doubling map

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Define $\pi: \Sigma \rightarrow \mathbb{R} / \mathbb{Z}$ by

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- $\pi$ is surjective.
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We will return to shift maps and their uses later.

## Endomorphisms and automorphisms of a torus

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Let $A=\left(a_{i j}\right)$ be a $k \times k$ matrix with integer entries, $\operatorname{det} A \neq 0$.

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(CAT $=$ Continuous Automorphism of a Torus)

## The Gauss Map

Every $x \in(0,1)$ can be expressed as a continued fraction

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where $x_{j} \in \mathbb{N}$.

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- $x$ has a finite continued fraction expansion iff $x$ is rational.


## The Gauss Map

Every $x \in(0,1)$ can be expressed as a continued fraction

$$
x=\frac{1}{x_{0}+\frac{1}{x_{1}+\frac{1}{x_{2}+\ldots}}}=\left[x_{0}, x_{1}, x_{2}, \ldots\right] .
$$

where $x_{j} \in \mathbb{N}$.
Facts about continued fractions:

- $x$ has a finite continued fraction expansion iff $x$ is rational.
- If $x$ is irrational then it has a unique continued fraction expansion.

Define $T:[0,1] \rightarrow[0,1]$ by $T(x)=\frac{1}{x} \bmod 1$. (Define $T(0)=0$.)

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If $x$ has continued fraction expansion $\left[x_{0}, x_{1}, x_{2}, \ldots\right]$ then $T(x)$ has continued fraction expansion $\left[x_{1}, x_{2}, x_{3}, \ldots\right]$.

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Define

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\begin{array}{ll}
A_{i j}=1 & \text { if symbol } j \text { can follow symbol } i \\
A_{i j}=0 & \text { if symbol } j \text { cannot follow symbol } i .
\end{array}
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Let

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\Sigma_{A}^{+} & =\left\{\left(x_{j}\right)_{j=0}^{\infty} \mid x_{j} \in S, A_{x_{x^{\prime} x_{j+1}}}=1 \forall j \geq 0\right\} \\
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Shifts of finite type as walks on graphs

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We call this the full $k$-shift.
We need hypotheses on $A$ to ensure that $\Sigma_{A}$ has sufficient structure to be of interest.

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$A$ is aperiodic $\Longleftrightarrow$ as above, but the length of the path can be chosen to be independent of $i, j$.

## Examples


not irreducible

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## A topology on $\Sigma_{A}, \Sigma_{A}^{+}$

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$$
n(x, y)= \begin{cases}\sup \left\{n \mid x_{j}=y_{j}, j=0,1, \ldots, n-1\right\} & \text { if } x \neq y  \tag{*}\\ \infty & \text { if } x=y\end{cases}
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## Remark

The exact choice of $\theta$ is, for the moment, unimportant: any $\theta \in(0,1)$ gives the same topology.

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metric space. (Topologically, $\Sigma_{A}^{+}$is a Cantor set.)
The shift map is chaotic:
- sensitive dependence on initial conditions
- the periodic points are dense
- there is a dense orbit.
(See exercises.)


## Markov partitions and symbolic coding

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For example we have already seen that the doubling map can be coded by the full one-sided 2-shift:


$$
T x=2 x \bmod 1
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$$
\pi\left(x_{j}\right)=\sum_{j=0}^{\infty} \frac{x_{j}}{2^{j+1}}
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We will not give a precise definition of what makes a dynamical system 'hyperbolic'.

Heuristically, hyperbolicity means that there is local uniform expansion and (in the case of invertible maps) local uniform contraction in a complementary direction.

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## Definition

A linear toral automorphism $T=T_{A}$ is hyperbolic if $A$ has no eigenvalues of modulus 1 .

## Example

The Cat map $A=\left(\begin{array}{ll}2 & 1 \\ 1 & 1\end{array}\right)$ is hyperbolic.

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## Remark

It follows that $T$ is chaotic.
One can use symbolic dynamics to prove many other results about hyperbolic dynamical systems.

Next lecture

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We will also see some applications to number theory.

