# MAGIC 010: Ergodic Theory

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## Course Outline

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- ► There are 10 lectures.
- Each lecture has:
  - a set of slides,
  - a set of more detailed notes that contain more information about the material, details of arguments that are only sketched in the slides, and the exercises,

- solutions to selected exercises.
- ► These will all be available via the Magic website.
- Assessment: take-home exam at the end of the course.

## MAGIC: Ergodic Theory Lecture 1 - Examples of Dynamical Systems

January 24th 2013

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#### Example

The geodesic flow on the torus

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Let  $\mathbb{T}^2=\mathbb{R}^2/\mathbb{Z}^2$  denote the torus:



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#### Example

The geodesic flow on the torus

Let  $\mathbb{T}^2=\mathbb{R}^2/\mathbb{Z}^2$  denote the torus:



Let X = the unit tangent bundle of  $\mathbb{T}^2$ . Then a point  $x \in X$  is a pair x = (p, v):

 $p = \text{point on } \mathbb{T}^2$ v = unit vector at v.



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Then there is a unique straight line through p in the direction v. We can infinitely extend this line using the identifications. The dynamical system moves the point x = (p, v) along this line at unit speed.



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#### Definition

x is *periodic* if  $T^n x = x$  for some n > 0. We call n the *period* of x.

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#### Definition

x is *periodic* if  $T^n x = x$  for some n > 0. We call n the *period* of x. When projected to  $\mathbb{T}^2$ , some orbits are dense:



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Let  $A \subset X$ .

What is the frequency with which the orbit of x hits A?

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$$\chi_A(T^j x)$$

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$$\frac{1}{n}\sum_{j=0}^{n-1}\chi_A(T^jx)$$

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When is it true that the frequency is equal to the proportion of X occupied by A?

Let  $T : X \to X$  be a discrete dynamical system. Suppose X is equipped with a measure  $\mu$  (eg. X could be the circle,  $\mu =$  Lebesgue measure).

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What is the frequency with which the orbit of x hits A?

$$\lim_{n\to\infty}\frac{1}{n}\sum_{j=0}^{n-1}\chi_A(T^jx)$$

When is it true that the frequency is equal to the proportion of X occupied by A? Is it enough to assume that the orbits are dense in X?

Let  $T : X \to X$  be a discrete dynamical system. Suppose X is equipped with a measure  $\mu$  (eg. X could be the circle,  $\mu =$  Lebesgue measure).

Let  $A \subset X$ .

What is the frequency with which the orbit of x hits A?

$$\lim_{n\to\infty}\frac{1}{n}\sum_{j=0}^{n-1}\chi_A(T^jx)$$

When is it true that the frequency is equal to the proportion of X occupied by A? Is it enough to assume that the orbits are dense in X? No. Proper hypothesis: T is *ergodic* (an indecomposability assumption).

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Birkhoff's Ergodic Theorem



#### Birkhoff's Ergodic Theorem

Let T be an ergodic measure-preserving transformation of a probability space  $(X, \mathcal{B}, \mu)$ . Let  $f \in L^1(X, \mathcal{B}, \mu)$ .



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Let T be an ergodic measure-preserving transformation of a probability space  $(X, \mathcal{B}, \mu)$ . Let  $f \in L^1(X, \mathcal{B}, \mu)$ . Then

$$\lim_{n\to\infty}\frac{1}{n}\sum_{j=0}^{n-1}f(T^jx)\longrightarrow\int f\,d\mu\qquad\qquad\mu\text{-a.e.}$$

## Structure of the Course

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### Structure of the Course

Give examples of dynamical systems


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Uniform distribution mod 1

Give examples of dynamical systems

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- Uniform distribution mod 1
- Invariant and ergodic measures

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- Uniform distribution mod 1
- Invariant and ergodic measures
- Ergodic theorems

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- Uniform distribution mod 1
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## Maps on the Circle and Torus

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Maps on the Circle and Torus

We give some examples of dynamical systems defined on the circle and on the torus.

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We will write the circle as  $\mathbb{R}/\mathbb{Z}$ . We will often abuse notation by identifying a point  $x \in \mathbb{R}$  with the coset  $x + \mathbb{Z}$ , with it being understood that we are working mod 1.

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Similarly, we write the k-dimensional torus as  $\mathbb{R}^k/\mathbb{Z}^k$  with a similar abuse of notation.

Note that both the circle and d-dimensional torus are Abelian groups under addition.

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### Proposition

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## An alternative view

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Write  $\mathbb{R}/\mathbb{Z} = \left[0, \frac{1}{2}\right] \cup \left[\frac{1}{2}, 1\right] = I_0 \cup I_1.$ 



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Every  $x \in (0,1)$  can be expressed as a continued fraction

$$x = \frac{1}{x_0 + \frac{1}{x_1 + \frac{1}{x_2 + \dots}}} = [x_0, x_1, x_2, \dots].$$

where  $x_j \in \mathbb{N}$ .

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If x is irrational then it has a unique continued fraction expansion.

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If x has continued fraction expansion  $[x_0, x_1, x_2, ...]$  then T(x) has continued fraction expansion  $[x_1, x_2, x_3, ...]$ .

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Define

$$\begin{aligned} A_{ij} &= 1 & \text{if symbol } j \text{ can follow symbol } i \\ A_{ij} &= 0 & \text{if symbol } j \text{ cannot follow symbol } i. \end{aligned}$$

$$\begin{split} \Sigma_{A}^{+} &= \{(x_{j})_{j=0}^{\infty} \mid x_{j} \in S, A_{x_{j}x_{j+1}} = 1 \ \forall j \geq 0\} \\ &= \text{ a one-sided shift of finite type} \end{split}$$

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Example

 $A = \left(\begin{array}{cc} 1 & 1 \\ 1 & 0 \end{array}\right) \qquad \qquad \Gamma : \bigcirc 1 \textcircled{2}$ 

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We need hypotheses on A to ensure that  $\Sigma_A$  has sufficient structure to be of interest.

### Definition A $k \times k \ 0 - 1$ matrix A is *irreducible* if: $\forall i, j \exists n > 0$ s.t. $A_{ij}^n > 0$ .

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 $A_{ij}^n :=$  the  $(i, j)^{th}$  entry of  $A^n =$  the number of distinct paths in  $\Gamma$  of length *n* from vertex *i* to vertex *j*.

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#### Hence

A is irreducible  $\iff$  For all vertices i, j, there exists a path in  $\Gamma$  (with length depending on i, j) from i to j.

A  $k \times k \ 0 - 1$  matrix A is irreducible if:  $\forall i, j \exists n > 0$  s.t.  $A_{ij}^n > 0$ . A  $k \times k \ 0 - 1$  matrix A is aperiodic if:  $\exists n > 0$  s.t.  $\forall i, j, A_{ij}^n > 0$ .

#### Fact:

 $A_{ij}^n :=$  the  $(i, j)^{th}$  entry of  $A^n =$  the number of distinct paths in  $\Gamma$  of length *n* from vertex *i* to vertex *j*.

#### Hence

- A is irreducible  $\iff$  For all vertices i, j, there exists a path in  $\Gamma$  (with length depending on i, j) from i to j.
  - A is aperiodic  $\iff$  as above, but the length of the path can be chosen to be independent of i, j.





not irreducible



### Examples



not irreducible

not irreducible



#### Examples



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irreducible but not aperiodic

#### Examples



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Let  $x = (x_j)_{j=0}^{\infty}$ ,  $y = (y_j)_{j=0}^{\infty} \in \Sigma_A^+$ . Fix any  $\theta \in (0, 1)$ .

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$$n(x,y) = \begin{cases} \sup\{n \mid x_j = y_j, \ j = 0, 1, \dots, n-1\} & \text{if } x \neq y; \\ \infty & \text{if } x = y. \end{cases}$$
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Define  $d_{\theta}(x, y) = \theta^{n(x,y)}$ . Then  $d_{\theta}$  is a metric on  $\Sigma_{A}^{+}$ .

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#### Remark

The exact choice of  $\theta$  is, for the moment, unimportant: any  $\theta \in (0, 1)$  gives the same topology.

Suppose A is aperiodic.

- compact
- totally disconnected
- perfect (= equal to its limit points)

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metric space. (Topologically,  $\Sigma_A^+$  is a Cantor set.) The shift map is chaotic:

sensitive dependence on initial conditions

- the periodic points are dense
- there is a dense orbit.

(See exercises.)

Markov partitions and symbolic coding

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Markov partitions and symbolic coding

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# Markov partitions and symbolic coding

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## Markov partitions and symbolic coding

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For example we have already seen that the doubling map can be coded by the full one-sided 2-shift:



 $Tx = 2x \mod 1$   $\pi(x_j) = \sum_{j=0}^{\infty} \frac{x_j}{2^{j+1}}$ 

We will not give a precise definition of what makes a dynamical system 'hyperbolic'.

Heuristically, hyperbolicity means that there is local uniform expansion and (in the case of invertible maps) local uniform contraction in a complementary direction.

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## Definition

A linear toral automorphism  $T = T_A$  is *hyperbolic* if A has no eigenvalues of modulus 1.

The Cat map 
$$A = \begin{pmatrix} 2 & 1 \\ 1 & 1 \end{pmatrix}$$
 is hyperbolic.

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### Remark

It follows that T is chaotic.

One can use symbolic dynamics to prove many other results about hyperbolic dynamical systems.

## Next lecture

Recall that ergodic theory is concerned about the distribution of typical orbits of a dynamical system.

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We will also see some applications to number theory.