



# Numerical and laboratory prediction of smoke lofting in the atmosphere over large area fires

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## ABSTRACT

We analyze the lofting of aerosol in the atmosphere over a large scale fire. According to the well-known theory of “nuclear winter”, soot, rising in the atmosphere, may spread in the stratosphere and screen sun rays, which may in turn result in long-term catastrophic consequences for the climate. The height reached by the soot is critical for the climate modeling because long-term global consequences can only be caused by a significant quantity of soot injected into the stratosphere. Most of the studies in the present literature are devoted to long-term modeling. The study of the initial (pyrocumulus) stage of the problem has attracted much less attention with the amount of the soot injected into the mid-latitude stratosphere often being postulated. The amount of smoke that enters the stratosphere is crucial for climate consequences. It is therefore important to predict accurately the active stage of a large-scale fire, which is accompanied by the development of convective columns. The paper is devoted to the analysis of different approaches to the prediction of the altitude of smoke lofting over large scale fires. Some numerical, laboratory and analytical methods are considered. The latter two approaches are based on the theory of similarity. The results obtained by different techniques are compared with each other. Special attention is given to high resolution simulations, which accurately enough resolve gravity waves.

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## 1. Introduction

The theory of “nuclear winter” predicts long-lasting climate consequences of large-scale firestorms. According to this theory, soot rises over the source of fire and is capable of penetrating into the middle and upper atmosphere [1]. Then, the smoke spreads in the stratosphere over the Earth and absorbs solar radiation for a long term. This inevitably leads to significant damages for the Earth climate.

First publications about the damage impact of large area fires on the climate appeared at the beginning of eighties independently by different groups (see [2,1,3]). Although different climate models were used, similar predictions were obtained: the climate consequences of a large area fire would cause a global climate disaster. As is concluded in [1], a significant drop of the average temperature would result in a “nuclear winter” and the climate changes would be severe. They might last about a decade [4].

Those and further studies (see, e.g., recent publications: [4–6] have been based on global and regional climate modeling. There has been the detailed climate simulation of numerous scenarios. It has been shown that in the case of a nuclear explosion, the resulting fire inflicts more damage to the climate (via the lofting smoke) than the explosion itself. The plume, rising

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over a fire, contains fire products such as black soot, smoke, ash and dust. Among the fire products, the soot is especially crucial for the climate consequences because it absorbs solar radiation.

It has been concluded that the plume of soot rises into the upper troposphere or lower stratosphere [4]. Moreover, additional ascent to the upper stratosphere can be caused by solar induced lofting [5,7]. These effects are proved to be highly important for the long-lasting climate consequences. Conversely, if aerosol is dispersed below the tropopause, its quantity rapidly diminishes due to rainfall as soon as its concentration drops to allow precipitation. As the result, the effect of fire on the climate is local and holds for several months [6].

As noted above, the aerosol over a large scale fire can be lofted into the stratosphere due to heat convection and local air circulation. Indeed, some smoke plumes have been observed after large forest fires [8–10]. According to the observation data reported in [11], the aerosol plume lofted to the lower stratosphere over the boreal forest fire in northwest Canada in 1998 contained enough smoke to be visible. In recent numerical simulations of forest fires [12,13], it has been shown that if the fire diameter exceeds the atmospheric scale height,  $H_0$ , estimated as 10 km, then deep penetration into the tropopause and lower stratosphere due to solar heating occurs.

Jost et al. [10] identify three major mechanisms which may be responsible for the aerosol injection into the mid-latitude stratosphere [10]: the overshooting of the original convection over the level of neutral buoyancy due to inertia and mixing at the top, the effect of water vapor, and radiative heating followed by lofting of smoke. Overall, it seems that the driving force of the troposphere-to-stratosphere transport is the extreme pyro-convection [11,14].

Much less study has been devoted to the stage of formation of convective columns over large-scale fires. However, this stage is highly important for the prediction of the soot quantity to be injected into the stratosphere. As is noted in [9], the injection of significant quantity of soot into the mid-latitude stratosphere is often postulated rather than accurately predicted.

In the literature, there are many publications devoted to the simulation of forest fires [8–10,15,12,13]. However, the typical size of the fire in those studies is usually smaller than the height of the tropopause (atmospheric scale height  $H_0$ ). As is shown below, for such fires, the maximum height of the soot rise is well predicted by a self-similar solution. Overall, there are only several publications in which large scale fires are addressed. We restrict our consideration by large scale fires because only they can give the maximum estimate for the height of the soot rise [6]. By a large scale fire we mean a fire with a typical size to be comparable with the height of the tropopause (about 10 km).

Pioneering simulations of large-scale fires [16,17] were quite limited with respect to the typical physical size and numerical resolution. The flow over a fire was described by the compressible Reynolds Averaged Navier–Stokes equations (RANS). Penner et al. [16] simulated the Hamburg fire and predicted the maximum soot rise as high as 12 km and the altitude of neutral buoyancy as high as 8 km. These results were in rough agreement with limited available observations. In [16], relatively small areas of the fire (the radius less than 5 km) were considered. The information on the numerical algorithm was not provided. Meanwhile, according to the pictures, the numerical resolution was quite low.

In [17], the physical time was limited by 1 h, while the fire radius was restricted by 10 km. The turbulent viscosity in the RANS equations was approximated by a piece-wise constant function that was, as shown by Muzafarov and Utyuzhnikov [18], a significant simplification. A first order scheme was used to obtain the numerical solution. Small and Heikes [17] recognized that the area of the smoke was not adequately reproduced by the simulation. Thus, their prediction of the altitude of plume rise (up to 19 km) did not seem very reliable. Meanwhile, Small and Heikes concluded that for large fires the height of the smoke injection mainly depended on the rate of energy release per unit area rather than the area of the fire.

Numerical modeling of an axis-symmetric fire source with the radius of 5 km was also carried out in [19]. Although they used the turbulence model suggested in [16], the coefficient with the mixing length was different. As well as in [17], the first order scheme was exploited on a relatively rough mesh. The predicted maximum altitude of smoke injection was about 14 km.

A detailed three-dimensional analysis of the Chisholm fire, which happened in Canada in 2001, was carried out by Trentmann et al. [13] using a sophisticated multiphase atmospheric model. The fire source was represented by a rectangular domain of 15 km length and 0.5 km width. The length of the fire front was about 25 km. The maximum altitude of the pyro-convective columns reached 13 km.

The sensitivity analysis done by Luderer et al. [12] showed that heat release is the most significant factor affecting convection, while the fuel moisture is much less important. Overall, water vapor emitted from the fire does not significantly affect the evolution of the smoke plume [17,13]. According to Heikes et al. [20], the moisture can lead to the redistribution of soot towards the upper level by a few kilometers.

As noted in [9], one of the key factors for this problem is related to intense gravity waves over a fire. For the first time, the gravity waves were resolved by Muzafarov and Utyuzhnikov [18] due to the use of compact approximations. In that paper, as well as in [25], a wide range of fire areas was considered. It was demonstrated that the gravity waves essentially affect the formation of smoke columns.

In spite of the papers considered above, so far little has been done on comprehensive numerical simulation of large scale fires. As recently noted in [6], “Further numerical simulations of mass fires of a few kilometers radius would be useful to better understand the behavior of pyro-convection for fires of this scale”. In that paper, it is recognized that there are still uncertainties related to smoke plume heights.

It is to be noted that the problem is even more complicated due to lack of observation data and complete impossibility of any full-scale experiment. Despite there are reliable estimates of plume height due to volcanic eruption in the literature (see e.g. [21–24]), these results cannot be applicable for large-scale fires as shown in the current paper.

In this paper, we consider computational, analytical and experimental predictions of the soot lofting in the atmosphere over a large scale fire. The paper is organized as follows.

In Section 2, the key computational results of papers by Muzafarov and Utyuzhnikov [18] and Konyukhou et al. [25] are analyzed. Special attention is given to high resolution simulations of large-scale fires. These results are also considered in detail because they are not well-known in the western literature. It is shown that the average level of neutral buoyancy is approximately half the maximum plume rise altitude. Numerical simulations show that the aerosol cloud oscillates in the atmosphere around its equilibrium level with the Brunt–Väisälä frequency. It is also obtained that, although there is a clear correlation between the area of a fire and the maximum height of the soot column, the maximum height is strictly bounded because the fire breaks into cells once the fire exceeds a radius of about 8 km.

The rest part of the paper is devoted to the analytical and experimental predictions of smoke lofting. Both approaches are based on the theory of similarity. In the case of laboratory conditions, this theory is not applicable to the problem in question straightforward. However, it appears that, as demonstrated in the current paper, it can be used under some reasonable assumptions. In turn, the analytical solution can be obtained from the theory of similarity only for a so-called point source model described in Section 3. It appears to be accurate enough provided that the size of the fire can be neglected while the power retaining. The laboratory modeling does not have such a limitation and can be carried out for a wide range of the input parameters as shown in Section 4.

For the first time, all the three approaches mentioned above are compared with each other as described in Section 5. In particular, this allows us to define the limits of applicability for the point-source model. It is demonstrated that the self-similar analytical solution provides a quite good prediction for the altitude of smoke lofting until the radius of fire does not exceed 8 km. A reasonably good correspondence between the numerical results and laboratory re-scaled data occurs. This brings an additional confirmation to the validity of the approximate similarity theory exploited in the experiments. It allows us to design more comprehensive laboratory experiments which take it into account the effects of moisture and radiation. Overall, the considered results are not only relevant to the “nuclear winter” problem but also applicable to the analysis of very large wildfires such as the Red Lake 7 and Chisholm fires.

## 2. High resolution numerical simulation

Consider the mathematical formulation of the problem and key computational results obtained by Muzafarov and Utyuzhnikov [18] and Konyukhou et al. [25] via the use of compact Padé-type upwind approximations. These results are required for further comparison against analytical and laboratory predictions.

### 2.1. Statement of problem

The Reynolds-averaged Navier–Stokes equations for compressible gas flow are considered in the Cartesian coordinate system  $\{y^i\}$  ( $i = 1, 2, 3$ ), where  $y^3$  is the coordinate in the direction normal to the Earth surface:

$$\frac{\partial q}{\partial t} + \frac{\partial e_{mv}^i}{\partial y^i} + \frac{\partial \mu e_{vis}^i}{\partial y^i} = -gf + Q,$$

where  $q$  is the vector of conserved variables,  $e_{mv}^i$  tensor of physical fluxes,  $f$ ,  $Q$  and  $s_{vis}$  source terms:

$$q = \begin{pmatrix} \rho \\ \rho V^1 \\ \rho V^2 \\ \rho V^3 \\ E \end{pmatrix}, \quad e_{mv}^i = \begin{pmatrix} \rho V^i \\ \rho V^i V^1 + p \delta^{i1} \\ \rho V^i V^2 + p \delta^{i2} \\ \rho V^i V^3 + p \delta^{i3} \\ (E + p) V^i \end{pmatrix}, \quad f = \begin{pmatrix} 0 \\ 0 \\ 0 \\ \rho \\ \rho V^3 \end{pmatrix}, \quad Q = \begin{pmatrix} 0 \\ 0 \\ 0 \\ Q^* \end{pmatrix},$$

$$e_{vis}^i = \begin{pmatrix} 0 \\ \frac{2}{3} \frac{\partial V^k}{\partial y^k} \delta^{i1} - \left( \frac{\partial V^1}{\partial y^i} + \frac{\partial V^i}{\partial y^1} \right) \\ \frac{2}{3} \frac{\partial V^k}{\partial y^k} \delta^{i2} - \left( \frac{\partial V^2}{\partial y^i} + \frac{\partial V^i}{\partial y^2} \right) \\ \frac{2}{3} \frac{\partial V^k}{\partial y^k} \delta^{i3} - \left( \frac{\partial V^3}{\partial y^i} + \frac{\partial V^i}{\partial y^3} \right) \\ \frac{2}{3} \frac{\partial V^k}{\partial y^k} V^i - \left( \frac{\partial V^k}{\partial y^i} + \frac{\partial V^i}{\partial y^k} \right) V^k - \frac{1}{Pr} \frac{\partial h}{\partial y^i} \end{pmatrix}.$$

Here, the summation over repeated indexes  $i, k = 1, 2, 3$  is assumed;  $\delta^{ij}$  is the Kronecker symbol;  $\{V^1, V^2, V^3\}$  are the velocity coordinates,  $\rho$  density,  $E = \rho(\epsilon + \frac{V^k V^k}{2})$  total energy,  $\epsilon$  internal energy,  $p$  pressure,  $h = \epsilon + p/\rho$  enthalpy,  $g$  free fall acceleration,  $\mu$  efficient coefficient of viscosity,  $Q^*$  power of heat release per unit volume,  $Pr$  Prandtl number.

A dry atmosphere is considered in simulations. The parameters of the atmosphere correspond to the International Standard Atmosphere [26].

The efficient coefficient of viscosity is described by the algebraic model used in [27,19] for modeling small- and large-scale fires in the atmosphere. As noted above, the model almost coincides with the model suggested in [28,16]. The only difference is that the turbulent mixing length in the model by Gostintsev et al. [27] is shorter as much as 1.6 times.

The fire source is modeled by a volume source similar to Hiekes et al. [20] and Gostintsev et al. [27,19]. It is considered axis-symmetric with the height,  $h_s$ , equal to 100 m. In the computations, the fire radius varies between 5 km and 33 km. The intensity of the volume source reaches its maximum value in 30 min. After 1 h the fire source is turned off to analyze how this affects the height of the plume. Muzafarov and Utyuzhnikov [18] consider the case of a forest fire with  $Q^* = 0.5 \text{ kW/m}^3$  that corresponds to the maximum energy release from the unit area of the surface equal to  $Q_m = 0.05 \text{ MW/m}^2$  since  $Q_m = Q^*/h_s$ . The aerosol is simulated by a “passive” contaminant permanently injected from the fire area. The passive contaminant consists of transported weightless particles that do not affect the gas flow.

## 2.2. Numerical algorithm

In Muzafarov and Utyuzhnikov [18], a modified version of the upwind compact scheme developed by Tolstykh [29] is used. The original scheme has been modified to maintain the third order of accuracy for smooth solutions and in the same time satisfy the entropy condition [30]. The scheme is strictly conservative, and has low dissipative and dispersive errors. The boundary conditions on the artificial open boundary are non-reflecting in the normal to the boundary direction and no-friction in the tangential direction. The scheme allows one to obtain non-oscillatory solutions without the use of any extra dissipative terms provided that the solution is sufficiently smooth [29]. The outlined properties of the third-order accurate upwind compact scheme are critical for long-term computations and resolution of gravity waves.

The basic scheme for a hyperbolic set of one-dimensional equations can be formulated as follows.

Consider the set of equations:

$$\frac{\partial q}{\partial t} + \frac{\partial e}{\partial x} = g, \quad (1)$$

where  $q \in \mathbb{R}^p$  is the vector of conserved quantities,  $e \in \mathbb{R}^p$  is the physical flux vector,  $g \in \mathbb{R}^p$  is the source term,  $p \geq 1$ .

Since set (1) is hyperbolic, the Jacobian matrix  $E = \frac{\partial e}{\partial q}$  can be decomposed into the product of three matrices  $E = SAS^{-1}$ , where  $S$  and  $A$  are square  $p \times p$  matrices,  $S$  is the matrix with rows identical to the eigenvectors of the matrix  $E$ ,  $A = \text{diag}\{\lambda_1, \lambda_2, \dots, \lambda_p\}$  is a diagonal matrix,  $\lambda_i$ ,  $i = 1, \dots, p$  are the eigenvalues of matrix  $E$ .

Let us introduce a uniform spatial grid  $\{x_i\}$ ,  $i = 0, 1, \dots, N$  with the constant cell size  $h$  and a space of discrete functions  $f_i$ , defined on this grid. Next, we consider basic operators:

$$\begin{aligned} A_0 f_i &= \frac{1}{6} f_{i-1} + \frac{2}{3} f_i + \frac{1}{6} f_{i+1}, \\ A_0 f_i &= f_{i+1} - f_{i-1}, \\ A_2 f_i &= f_{i+1} - 2f_i + f_{i-1}, \quad i = 1, \dots, N-1. \end{aligned}$$

Then, the spatial discretisation of (1) is given by

$$B_x \frac{\partial q}{\partial t_i} + C_x e_i = B_x g_i, \quad (2)$$

where  $B_x$  and  $C_x$  are the following finite-difference operators:

$$\begin{aligned} B_x &= A_0 - \frac{1}{4} M A_0, \quad C_x = \frac{1}{2h} (A_0 - M A_2), \\ M &= \text{diag}\{\text{sign} \lambda_i\}, \quad i = 0, 1, \dots, N. \end{aligned}$$

The spatial discretisation scheme (2) is combined with a second order accurate temporal evolution method [31]. Overall, the scheme is proved to be high-resolution on smooth solutions. In particular, one can show via spectral analysis that, to resolve a harmonic wave, it is enough to have only five nodes per wave length [29].

In calculations, the spatial grid with refinement to the fire source was used. At least 10 nodes appeared in the fire source area in the vertical direction, and 20 nodes, in horizontal coordinate direction. The adaptation in the physical domain was reached via a transform of the coordinate system:  $\xi = \xi(x)$ . Thus, in the computational domain, the grid remained uniform. On average, the space step was about 200 m. Thus, the chosen mesh was sufficient to resolve the internal gravity waves with the wavelength of 2 km. In control accuracy computations, the number of nodes was doubled in each direction to make sure that the numerical resolution was accurate enough. In calculations, the Courant–Friedrichs–Lewy coefficient did not exceed the value of 1. The artificial open boundary was placed far enough from the fire so that the solution was not sensitive to its location.

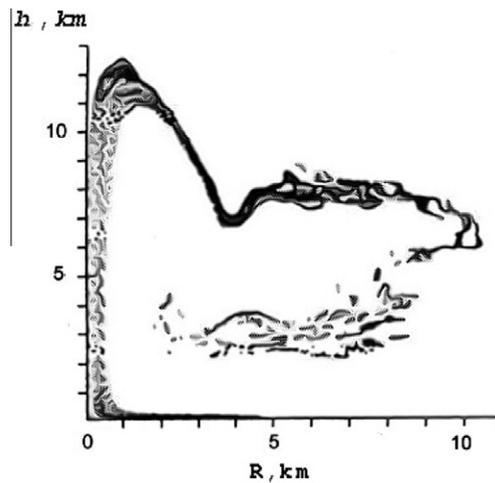


Fig. 1. Distribution of passive contaminant over a fire with  $R = 5$  km after 1 h.

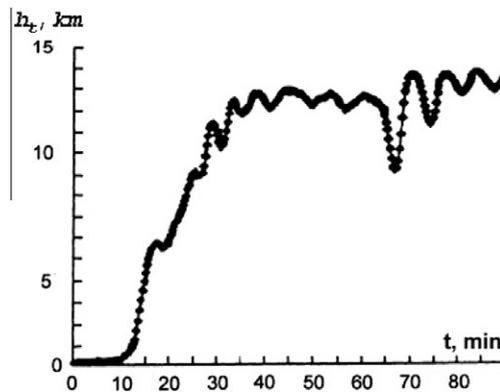


Fig. 2. Maximum plume height over a fire with  $R = 5$  km.

### 2.3. Variation of fire areas

First, we consider a fire with the radius of 5 km. Thereby, the maximum total rate of heat injection  $q_f$  reaches  $3.9 \times 10^6$  MW. It is to be noted that here and in further examples in this section, the contribution of the local wind is not taken into account. The distribution of aerosol for the time 1 h is shown in Fig. 1, where the density of points representing passive contaminant reflects the density of smoke. Similar to the earlier results [16,20], it is clear that the gas over the fire rises due to the buoyancy force. Meanwhile, the hot gas overshoots the equilibrium height of about 8 km due to strong convection. As the gas cools down, it falls to the equilibrium level of neutral buoyancy and spreads along with the aerosol. The described process is characterized by the Rayleigh–Taylor instability with a heavy gas situated above a light one due to overshooting. At the later stage, gas spreading at the altitude of neutral buoyancy,  $h_b$ , is also accompanied by the Kelvin–Helmholtz instability [15]. The predicted maximum height,  $h_t$ , of 12.5 km is in reasonable agreement with the results obtained in [17]. However, the altitude,  $h_b$ , and the area of smoke are significantly smaller than that in [17]. Overall, it appears that the level of neutral buoyancy,  $h_b$ , is approximately half the total column height  $h_t$ .

Fig. 2 shows the dependence of the maximum height on time. In Muzafarov and Utyuzhnikov [18], it was shown for the first time that after reaching the maximum altitude, the plume of aerosol oscillates in time rather than stays on the same level. The period of oscillations around the equilibrium level is approximately equal to 5–7 min that corresponds to the Brunt–Väisälä frequency of free oscillations of the atmosphere [32]. The generation of large-scale vortices is caused by the internal gravity waves. These vortices are mostly formed once the plume reaches the maximum height.

The average altitude of the plume,  $h_t$ , is about 13 km that is quite consistent with the prediction by Gostintsev et al. [19]. The plume altitude sharply changes at the time of about 70 min. This is caused by the deactivating of the fire after 1 h. It is important to note that 10 min after the power of the fire source reaches its maximum the aerosol rises to its maximum height. Meanwhile, the average altitude of the plume rise stays constant as long as the fire source operates. Thus, the operation of the fire source beyond 40 min interval does not alter the maximum height of the convective column  $h_t$ .

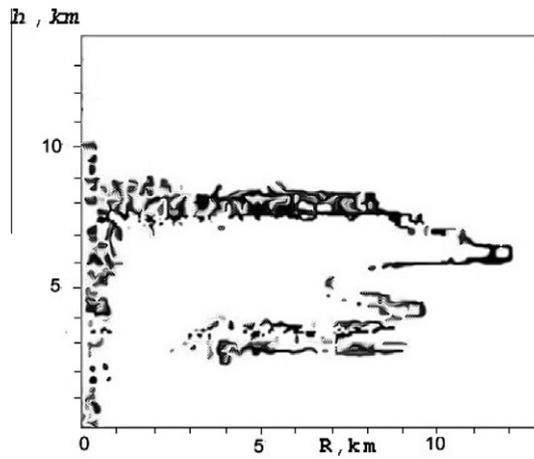


Fig. 3. Distribution of passive contaminant over a fire with  $R = 5$  km after 1, 5 h.

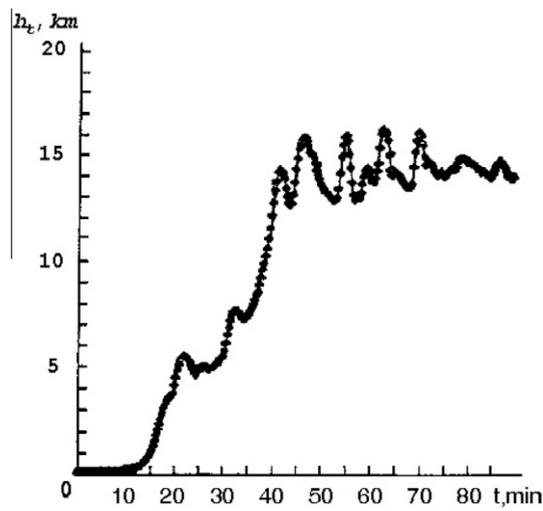


Fig. 4. Maximum plume height over a fire with  $R = 11$  km.

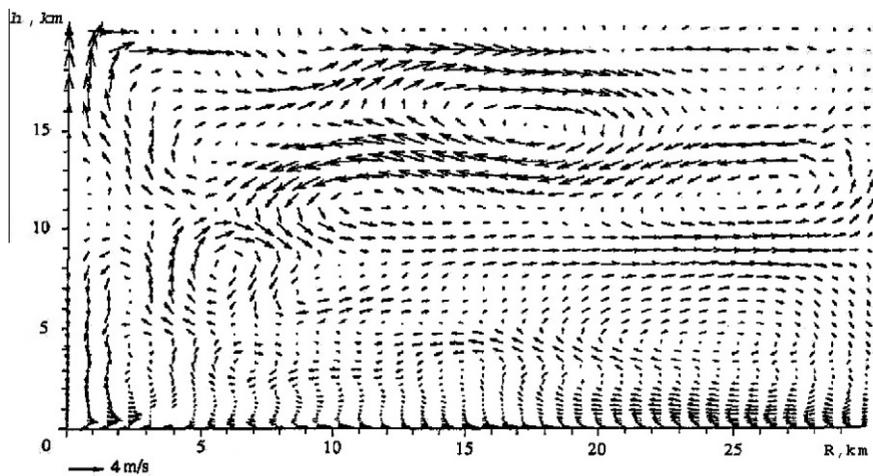


Fig. 5. Velocity field over a fire with  $R = 11$  km at  $t = 90$  min.

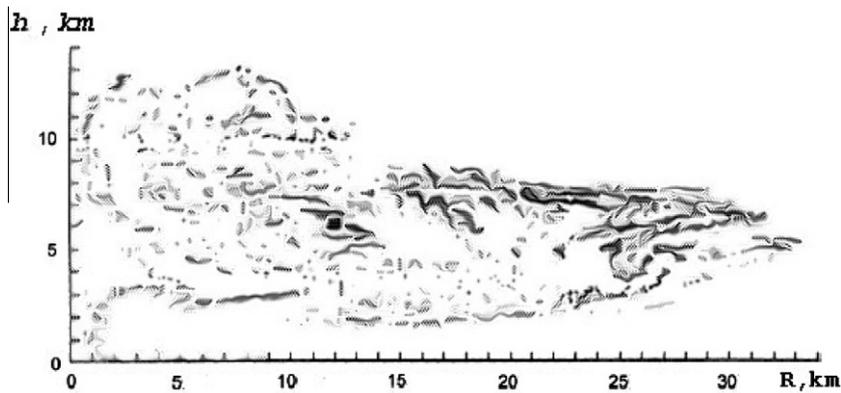


Fig. 6. Distribution of passive contaminant over a fire with  $R = 22$  km after 80 min.

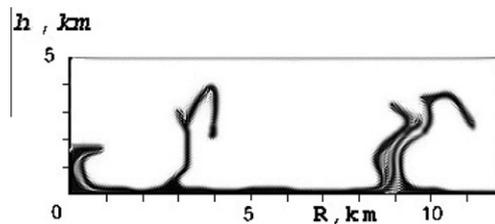


Fig. 7. Distribution of passive contaminant over a fire with  $R = 11$  km after 20 min.

The smoke distribution after 90 min is shown in Fig. 3. It can be seen that although the maximum altitude remains the same as before, the concentration of the contaminant drops and the aerosol mostly spreads at the height of neutral buoyancy,  $h_b$ , of about 7 km, which is situated in the tropopause.

One can expect that the increase of the radius of the fire,  $R$ , can lead to the increase of the maximum height of neutral buoyancy. However, it appears that this is so only up to  $R \approx 11$  km. After that the maximum altitude gradually decreases and reaches the ultimate value below 15 km. For example, the change of the radius from 22 km to 33 km leads to a slight drop of the maximum height from 16 km to 15 km.

Next, the dependence of the smoke plume height on time for the fire of  $R = 11$  km ( $q_f = 1.9 \times 10^7$  MW) is shown in Fig. 4. One can see that after  $t = 50$  min, the average maximum altitude of plume rise is about 17 km and remains constant as long as the fire source continues to operate. The field of velocities over the fire at time 90 min is presented in Fig. 5. One can see a set vortices mostly generated in the atmosphere during the plume oscillations around the height of neutral buoyancy  $h_b$ .

Finally, in Fig. 6, the distribution of aerosol over the fire with  $R = 22$  km after 80 min is shown. One can see that the plume height,  $h_t$ , is about 15 km, which is less than that of the fire of  $R = 11$  km. In turn, the computational results for the fire of  $R = 33$  km confirmed the altitude  $h_t$  is not much sensitive to the fire radius anymore.

The results discussed above suggest that if  $R$  is greater than 8 km, the fire breaks into local sources which tend to operate independently. Eventually, the fire breaks up into coherent structures represented by the Benard cells. This is shown in Fig. 7 which corresponds to the case of  $R = 11$  km after 20 min. The described effect was first obtained in Muzafarov and Utyuzhnikov [18].

Thus, one can see that the area of the fire is an important parameter with regards to the maximum altitude of the smoke plume. For large scale fires up to  $R \approx 11$  km, it may well be a more important factor than the total heat release. Once the size of the fire exceeds  $R = 11$  km, the maximum altitude of the smoke declines slightly, while the area of the smoke cloud eventually increases. Overall, one can conclude that the fire area does not affect the maximum altitude of the smoke plume if the typical size of the fire is significantly greater the atmospheric scale height  $H_0$ . In this case, the fire source is broken up into a series of local coherent structures operating independently.

In general, the predicted plume height is consistent with the altitude smoke injection of 13 km in the case of the Red Lake 7 wildfire in Canada in 1986, provided by Lavoué [33]. The area of the fire was about  $130 \text{ km}^2$  that corresponds to the radius of 7 km. It is interesting to note that approximately the same maximum altitude of the smoke plume is predicted by [13] for the Chisholm fire, which had much less area of the fire: as less as one order of magnitude. However, in the case of the Chisholm fire the typical fire size was 25 km. Thus, for the prediction of plume rise, the typical size of the fire source seems a more crucial parameter than the total area of the fire.

In all computations the altitude of the neutral buoyancy,  $h_b$ , is approximately half the total height of injection. This conclusion approximately agrees with the results obtained in [12]:  $h_t = 11$  km and  $h_b = 6$  km. It is to be noted that in the case of

**Table 1**  
Maximum plume height. Comparison against formula (3).

R, km	$h_t, A = 0.255$	$h_t, A = 0.31$	$h_{t,min}$	$h_{t,max}$
5	11.3	13.4	11.3	13
8	14.4	17.5	11.9	15
11	16.8	20.5	12.9	16.2

a small-area source  $h_b \approx 0.7h_t$  as shown in [21]. Here, the small-area source means the typical size of the fire is much less the atmospheric scale height  $H_0$ .

Our analysis demonstrates that the overshooting process of plume rise is followed by a significant fall of aerosol to the height of neutral buoyancy  $h_b$ . Meanwhile, some quantity of soot retains on the upper level due to the mixing mechanism. Thus, most aerosol appears in the tropopause. As noted before, the aerosol can eventually be heated by the sun and lofted into the stratosphere. The simulation of such a process is beyond the scope of the current paper.

### 3. Self-similar analytical solution for a point source

If the area of the fire source can be neglected, then the maximum plume height can be predicted via the self-similar solution for a point source [36]:

$$z_t = Aq_f^{1/4}, \quad A = \text{constant}, \tag{3}$$

where  $q_f$  is the total rate of heat release in MW,  $z_t$  is to be measured in km.

It is interesting to compare the computational prediction for  $h_t$  obtained by Muzafarov and Utyuzhnikov [18] against the self-similar solution (3). There are at least two values for the constant  $A$  available in the literature:  $A = 0.255$  according to [34] and  $A = 0.31$  used in [27]. Table 1 gives the prediction of  $h_t$  corresponding to the both values of constant  $A$  in formula (3) as well as the results of numerical simulation. It is accidental that these two constants provide good enough estimates for the range of  $h_t$  in the oscillations around the level of neutral buoyancy:  $h_{t,min} < h_t < h_{t,max}$  if  $R < 8$  km.

It is easy to see that starting from  $R = 11$  km, the formula (3) is considerably violated. One can expect this because, as soon as the radius becomes comparable with the atmospheric scale height (about 10 km),  $H_0$ , the physical problem is not self-similar anymore. In fact, since formula (3) is only obtained for a uniform atmosphere, it is not applicable even for a point source if the altitude of plume is high enough. As noted in [35], it should be modified with the account of variable stratification in the atmosphere above the tropopause.

For this purpose, introduce the parameter of stratification  $\Pi_s$  as follows [36]:

$$\Pi_s = H_0 \frac{d}{dz} \left[ \ln \left\{ \frac{\theta_{atm}(z)}{\theta_{atm}(0)} \right\} \right],$$

where  $\theta_{atm}$  is the potential atmospheric temperature.

Then, the modification suggested in [35] is given by

$$z_t = \left[ 1 + (\Pi_s^0 / \Pi_s)^{3/8} * \left( \frac{A}{H_0} q_f^{1/4} - 1 \right) \right] H_0, \tag{4}$$

here  $\Pi_s^0$  is the value of  $\Pi_s$  in the tropopause. It is clear that if the altitude is not higher the tropopause, then formula (4) coincides with the standard formula (3). The degree of 3/8 is chosen to fit available results for a point source in the case of  $z_t > H_0$ .

The effect of modification (4) is shown in Fig. 8. The computational results by Muzafarov and Utyuzhnikov [18] correspond to the curves marked by triangles and diamonds. One can see that the modified self-similar solution (solid line) gives better prediction as the plume is above the tropopause. The comparison of analytical predictions (3) and (4) against some experimental results is shown in the next section.

In the literature, there exists another analytical formula for the plume height, which is empirical in nature. Having analyzed many forest fires, Lavoué et al. [33] suggested a linear relationship between the frontal fire intensity and height of the smoke injection. Meanwhile, from formula (3) it follows that the injection height of the smoke is proportional to the square root of the radius:  $h_t \sim \sqrt{R}$ . Thus, for small enough fires (with the radius up to 5 km), the relationship between the smoke height and frontal intensity is not linear provided that the frontal intensity is proportional to the perimeter of the fire. This conclusion is also confirmed by the observation data for forest fires given in [6]. Meanwhile, Trentmann et al. [13] and Luderer et al. [12] suggest that the linear relationship breaks down near the tropopause. Indeed, as noted above the smoke plume height reaches its maximum value at about  $R = 11$  km and then decreases if the fire radius increases.

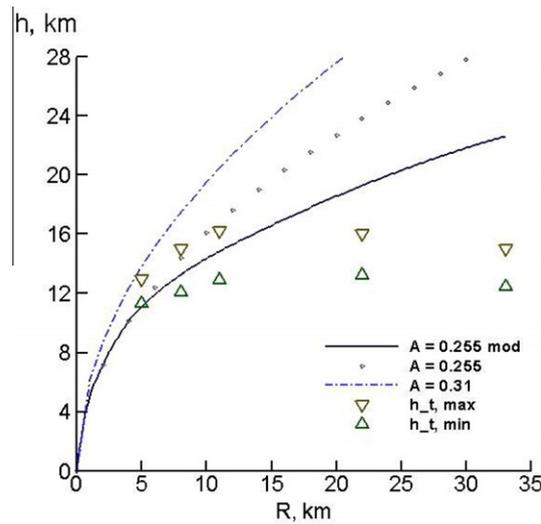


Fig. 8. Total plume height vs radius of fire  $R, Q_m = 0.05 \text{ MW/m}^2$ .  $\Delta$  and  $\nabla$  correspond to computational results. Solid, dotted and dash-dotted lines represent analytical predictions for the energy-equivalent point source.

### 4. Laboratory modeling

#### 4.1. Approximate self-similarity

It appears that the problem is determined by 11 dimensional or 8 dimensionless parameters. Although the rigorous self-similarity cannot be obtained in the laboratory conditions, it can be reached for 6 key dimensionless parameters [36].

Following Morton et al. [36], to apply the theory of similarity, determine all independent key parameters. The flow essentially depends on 11 dimensional values such as the density  $\rho_a(0)$ , its gradient  $\frac{d\rho}{dz}$ , atmospheric pressure  $p_a(0)$ , the fire diameter  $D$ , the gravity acceleration  $g$ , kinematic viscosity  $\nu$ , the density of the injected gas  $\rho_g(0)$ , the coordinates  $\{r, z\}$  of cylindrical coordinate system, and the time  $t$ . Since there are only three independent dimensions, from the  $\pi$ -theorem it immediately follows that the number of independent dimensionless parameters is equal to 8. The laboratory experiments were carried out in a cylindrical chamber with a specific atmosphere [35,37], whereas the following key parameters retaining:

$$\begin{aligned} \Pi_1 \equiv \Pi_s &= h_0 \frac{d}{dz} \left[ \ln \left\{ \frac{\rho_c(0)}{\rho_c(z)} \right\} \right], & \Pi_2 &= \frac{\rho_c(0)}{\rho_a(0)}, \\ \Pi_3 \equiv \frac{d_0}{h_0} &= \frac{D}{H_0}, & \Pi_4 \equiv \frac{\hat{z}}{h_0} &= \frac{z}{H_0}, \\ \Pi_5 \equiv \frac{\hat{r}}{h_0} &= \frac{r}{H_0}, & \Pi_6 \equiv \frac{\hat{t}}{(gh_0)^{1/2}} &= \frac{t}{(gH_0)^{1/2}}, \end{aligned}$$

where  $\rho_c$  is the density of air in the chamber;  $\rho_g$  the density of air at the source;  $d_0$  the diameter of the “fire” source in the chamber;  $h_0$  the height of the “tropopause” in the chamber;  $\hat{r}, \hat{z}, \hat{t}$  are the self-similar space and time variables, respectively.

The Grashof number  $Gr = gD_0^3/\nu$  was not exactly simulated. However, its value, calculated with respect to the turbulent viscosity, was approximately retained. Finally, the Froude number  $Fr = \rho_a(0)gh_0/p_a(0)$  was neglected in the experiments.

From the theory of similarity it follows that all lengths in experimental results are to be scaled as much as  $D/d_0$  while the time must be multiplied by  $\sqrt{D/d_0}$ .

It was supposed that  $H_0 = 11 \text{ km}$  while  $h_0 = 20 \div 25 \text{ cm}$ . The height  $h_0$  was determined as the altitude at which  $\rho_c(h_0) = 0.87\rho_c(0)$ . Thus, in the experiments the typical size of the problem was reduced as much as 200 times.

#### 4.2. Experimental setup

The experiments were carried out in a cylinder chamber 7 m in radius and 1.5 m in height. Freon mixed with air was injected from the bottom and top to the chamber and gradually taken away from the side. The gas injected through the bottom was heavier the gas coming through the top as much as 5.9. The total rate of the injection,  $q$ , was 15 g/s. Thereby, a local stratified atmosphere was maintained in the experiments in such a way that

$$\frac{\rho_c(z)}{\rho_c(0)} = \frac{\theta_{atm}(0)}{\theta_{atm}(z)}$$

The fire source was modeled by injected light gas with smoke. The velocity of injection  $w(0)$  satisfied the similarity conditions:

$$w(0) = W(0) \left( \frac{h_0}{H_0} \right)^{1/2},$$

where  $W(0)$  is the typical velocity in the real conditions which was estimated as a function of the intensity of the fire source  $Q_m$  per unit area [36]:

$$W(0) = \frac{Q_m}{C_p(T - T_{atm})},$$

where  $C_p$  is the heat capacity,  $T$  the temperature,  $T_{atm} = 300$  K. Thus, the equivalent total source power is equal to  $w(0)\pi d^2/4$ .

The injected gas was delivered through a grid to cause its turbulence. The radius of the source upon a scaling procedure varied between 5 km and 22 km. The effects of moisture and radiation were not simulated in the experiments.

### 5. Comparison between laboratory, computational and analytical results

Test cases with  $d_0/h_0 < 1$  showed a good correspondence between the experimental results and the point-source solution (4) with respect to the maximum height of a convective column  $h_t$ .

There is a reasonably good correspondence between the experimental results [35] and computational results obtained in [25]. Two types of fire sources were considered distinguished by their intensity. The results are shown in Figs. 9 and 10 respectively for  $Q_m = 0.073$  MW/m<sup>2</sup> and  $Q_m = 0.24$  MW/m<sup>2</sup>. Such values of energy release rate represent wildfire and urban fire [1]. The experimental results, marked by squares, were recalculated for real scales via multiplication of all space sizes by  $H_0/h_0 = D/d_0$ . The total plume height,  $h_t$ , and altitude of neutral buoyancy,  $h_b$ , are represented by the solid and dash-dotted lines, respectively. In turn, the appropriate computational results are marked by squares. The difference between the computational and laboratory results is mostly within 10%.

In Figs. 9 and 10, the crosses correspond to the point source with the equivalent power. As can be seen, the plume altitude is significantly higher in this case. This result demonstrates that the point-source model is not applicable if  $R$  is greater 5 km. One can see that the modified analytical approximation given by formula (4) with  $A = 0.255$  (dashed line) provides an accurate enough prediction for the energy-equivalent point source. In turn, the original formula (3) (dotted line) is basically applicable only if  $h_t$  does not exceed the tropopause height.

In [25] the algebraic turbulence model was similar to that used in Muzafarov and Utyuzhnikov [18] but one free parameter of the model was modified. Breaking up the fire into multiple convective cells around  $R = 11$  km is observed in all regimes. As can be seen, the smoke column altitude significantly increases as the heat rate,  $Q_m$ , increases.

Analyzing the results obtained in Muzafarov and Utyuzhnikov [18] and [25], one can conclude that the maximum height of the plume is proved to be quite sensitive to the turbulence model used. On the one hand, the model suggested by Gostintsev

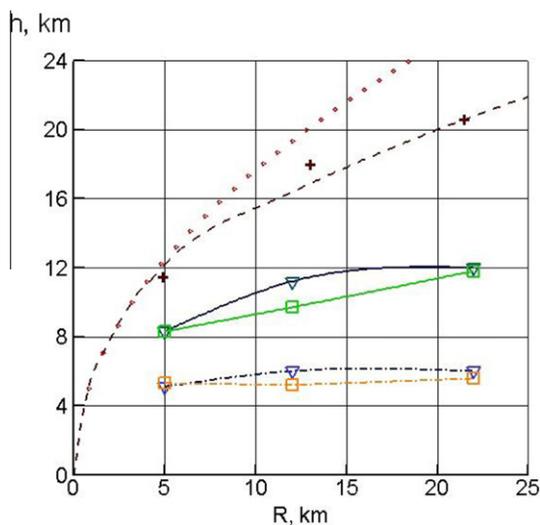
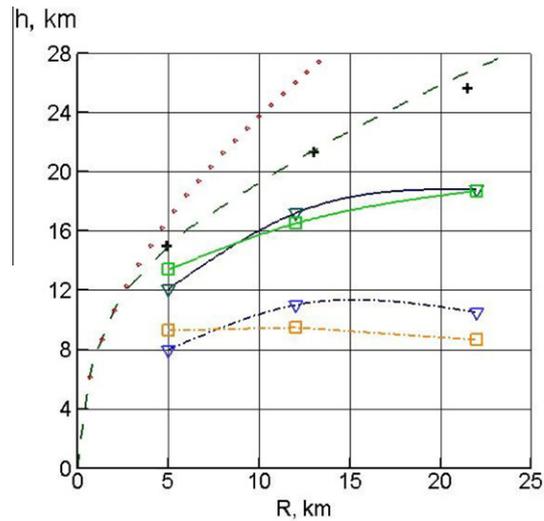


Fig. 9. Total plume height (solid line) and level of neutral buoyancy (dashed line) vs radius of fire  $R$ ,  $Q_m = 0.073$  MW/m<sup>2</sup>.  $\nabla$  corresponds to computational results,  $\square$ , experimental results. Crosses, dashed and dotted lines represent experimental and analytical predictions (3) and (4), respectively, for the energy-equivalent point source.



**Fig. 10.** Maximum plume height (solid line) and level of neutral buoyancy (dashed line) vs radius of fire  $R$ ,  $Q_m = 0.24 \text{ MW/m}^2$ .  $\nabla$  corresponds to computational results,  $\square$ , experimental results. Crosses, dashed and dotted lines represent experimental and analytical predictions (3) and (4), respectively, for the energy-equivalent point source.

et al. [27] provides a good correspondence with the self-similar solution for a point source (3) whereas the model by Penner et al. [16] gives a good enough prediction of the experimental data by Balabanov et al. [35]. On the other hand, there is a difference within a few kilometers between those two predictions.

Finally, in [38], 3D simulations were carried out for the fire with  $R = 10 \text{ km}$  and the velocity of the wind  $10 \text{ m/s}$ . It appeared that the maximum height as well as the altitude and total area of the smoke cloud are not strongly affected by the wind although the region of the smoke cloud is significantly displaced and deformed.

## 6. Summary

The prediction of smoke column height over a large-scale fire has been considered. Some computational, analytical and experimental approaches have been analyzed and compared to each other. The self-similar analytical solution for a point source should be modified if the altitude of the smoke column reaches the tropopause. In turn, the point-source solution gives good enough prediction only if the typical size of the fire is less the atmospheric scale height.

The laboratory modeling based on an approximate theory of similarity provides a reasonably good prediction for the evolution of smoke columns. According to laboratory and computational simulation, the aerosol over a large scale fire sequentially rises in the atmosphere, overshoots the equilibrium height, falls down and mostly spreads at some altitude. It appears that the altitude of neutral buoyancy is approximately half the maximum one. The plume oscillates in the atmosphere around some height of equilibrium with the frequency of natural atmospheric oscillations. The area of a fire can significantly affect the maximum height of the convective columns. In the case of large scale fires, the fire area may be more important than the intensity of heat release.

If the diameter of the fire exceeds twice the atmospheric scale height, then the fire breaks up into coherent structures represented by the Benard cells. The deactivating of the energy source results in some drop of the maximum height. If the typical size of the fire further increases, the height of the smoke column does not increase in contrast to the case of an energy-equivalent point source. It appears that for very large-scale fires the total column height reaches some ultimate level above the tropopause.

In all considered possible cases, the altitude of neutral buoyancy remains below the stratosphere. Hence, most smoke appears in the tropopause and does not penetrate into the stratosphere. However, the long-term effect of the cross-tropopause transport of smoke can be reinforced by the self-lofting that leads to the subsequent injection of some quantity of aerosol into the stratosphere. For the analysis of climate consequences, which is beyond the scope of the current paper, coupling a low-scale simulation of the initial (pyrocumulus) stage of the fire with global-scale climate models is required.

The effects of moisture, radiation and latent heat release should be taken into account in further experiments.

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