

Maximal Inequalities for Reflected Brownian Motion with Drift

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Let $\beta = (\beta_t)_{t \geq 0}$ denote the unique strong solution of the equation

$$d\beta_t = -\mu \operatorname{sign}(\beta_t) dt + dB_t$$

satisfying $\beta_0 = 0$, where $\mu > 0$ and $B = (B_t)_{t \geq 0}$ is a standard Brownian motion. Then $|\beta| = (|\beta_t|)_{t \geq 0}$ is known to be a realisation of the reflected Brownian motion with drift $-\mu$. Using this representation we show that there exist universal constants $c_1 > 0$ and $c_2 > 0$ such that

$$c_1 E(H_\mu(\tau)) \leq E\left(\max_{0 \leq t \leq \tau} |\beta_t|\right) \leq c_2 E(H_\mu(\tau))$$

for all stopping times τ of β , where $H_\mu(x) = F_\mu^{-1}(x)$ denotes the inverse of the map $F_\mu(x) = (e^{2\mu x} - 2\mu x - 1)/2\mu^2$. In addition, we show that

$$E\left(\max_{0 \leq t \leq \tau} |\beta_t|\right) \leq G_\mu(E(\tau))$$

for all stopping times τ of β , where $G_\mu(x) = \inf_{c > 0} (cx + (1/2\mu) \log(1 + \mu/c))$. Both inequalities have their well-known analogues for Brownian motion (obtained by letting $\mu \downarrow 0$). The method of proof relies upon Lenglart's domination principle, Itô calculus, and optimal stopping techniques.

1. Introduction

A classic definition in the theory of Markov processes states that the process $X = (X_t)_{t \geq 0}$ is a *reflected Brownian motion with drift* $\lambda \in \mathbb{R}$, if X is a non-negative diffusion Markov process associated with the infinitesimal operator \mathbb{L}_X acting on a space of C^2 -functions $f : [0, \infty) \rightarrow \mathbb{R}$ satisfying $f'(0+) = 0$ according to the rule:

$$(1.1) \quad (\mathbb{L}_X f)(x) = \lambda f'(x) + \frac{1}{2} f''(x)$$

(see e.g. [4]). If such a process X also satisfies $X_0 = x$ for some $x \in \mathbb{R}$ given and fixed, then it is customary to write $X \sim RBM_x(\lambda)$.

In the case $\lambda = 0$ it is well-known that such a process can be realised as

$$(1.2) \quad X_t = |x + B_t|$$

where $B = (B_t)_{t \geq 0}$ is a standard Brownian motion (see e.g. [4] or [7]).

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In the case of general $\lambda \in \mathbb{R}$ it was shown only recently (see [3]) that the corresponding analogue of (1.2) takes the following form:

$$(1.3) \quad X_t = |\beta_t|$$

where $\beta = (\beta_t)_{t \geq 0}$ is the unique strong solution of the "bang-bang" equation:

$$(1.4) \quad d\beta_t = \lambda \operatorname{sign}(\beta_t) dt + dB_t$$

with $\beta_0 = x$. Then again $X \sim RBM_x(\lambda)$ and thus each reflected Brownian motion with drift can be realised as the modulus of the "bang-bang" process β . This representation is useful in many ways as it enables one to employ the well-known methods and techniques from the theory of stochastic differential equations and stochastic calculus (e.g. Itô-Tanaka formula).

In this note we shall demonstrate this fact by establishing two inequalities for reflected Brownian motion *with drift* as a counterpart of the well-known inequalities for Brownian motion *without drift*. The first inequality we have in mind is the *Burkholder-Gundy inequality* [1] stating that

$$(1.5) \quad c_1 E(\sqrt{\tau}) \leq E\left(\max_{0 \leq t \leq \tau} |B_t|\right) \leq c_2 E(\sqrt{\tau})$$

for all stopping times τ of B (see Theorem 2.1). The second inequality is the well-known Doob-type inequality for Brownian motion stating that

$$(1.6) \quad E\left(\max_{0 \leq t \leq \tau} |B_t|\right) \leq \sqrt{2} \sqrt{E(\tau)}$$

for all stopping times τ of B (see Theorem 2.4). This inequality was established independently by several authors, and the constant $\sqrt{2}$ is known to be best possible (see [2]).

2. The results and proof

1. We first establish an analogue of the Burkholder-Gundy inequality (1.5). For this we shall define a function F_μ on \mathbb{R}_+ by setting

$$(2.1) \quad F_\mu(x) = \frac{e^{2\mu x} - 2\mu x - 1}{2\mu^2}$$

for $x \geq 0$. Then $x \mapsto F_\mu(x)$ is strictly increasing on \mathbb{R}_+ , and we shall set

$$(2.2) \quad H_\mu(x) = F_\mu^{-1}(x)$$

to denote its inverse for $x \geq 0$ (see Remarks 2.3 below).

Theorem 2.1

Let $X = (X_t)_{t \geq 0}$ be a reflected Brownian motion with drift $-\mu$ such that $X_0 = 0$ where $\mu > 0$ is given and fixed. Then the following inequality is satisfied:

$$(2.3) \quad c_1 E(H_\mu(\tau)) \leq E\left(\max_{0 \leq t \leq \tau} X_t\right) \leq c_2 E(H_\mu(\tau))$$

for all stopping times τ of X , where $c_1 > 0$ and $c_2 > 0$ are some universal constants.

Proof. We shall present a proof which is based upon the following domination principle established by Lenglart [5] (see [7] p.155-156).

Lemma 2.2

Let $(\Omega, \mathcal{F}, (\mathcal{F}_t)_{t \geq 0}, P)$ be a filtered probability space, let $Z = (Z_t)_{t \geq 0}$ be an (\mathcal{F}_t) -adapted non-negative continuous process, let $A = (A_t)_{t \geq 0}$ be an (\mathcal{F}_t) -adapted increasing continuous process satisfying $A_0 = 0$, and let $H : \mathbf{R}_+ \rightarrow \mathbf{R}_+$ be an increasing continuous function satisfying $H(0) = 0$. Suppose that it is known that

$$(2.4) \quad E(Z_\tau) \leq E(A_\tau)$$

for all bounded (\mathcal{F}_t) -stopping times τ such that $(Z_{t \wedge \tau})_{t \geq 0}$ is bounded. Then we have:

$$(2.5) \quad E\left(\sup_{0 \leq t \leq \tau} H(Z_t)\right) \leq E\left(\tilde{H}(A_\tau)\right)$$

for all (\mathcal{F}_t) -stopping times τ , where

$$(2.6) \quad \tilde{H}(x) = x \int_x^\infty \frac{1}{s} dH(s) + 2H(x)$$

for all $x \geq 0$.

Proof. By Fubini's theorem we find:

$$(2.7) \quad \begin{aligned} E\left(\sup_{0 \leq t \leq \tau} H(Z_t)\right) &= E\left(H\left(\sup_{0 \leq t \leq \tau} Z_t\right)\right) = E\left(\int_0^\infty 1_{\{\sup_{0 \leq t \leq \tau} Z_t \geq s\}} dH(s)\right) \\ &\leq \int_0^\infty \left(P\left\{\sup_{0 \leq t \leq \tau} Z_t \geq s, A_\tau \leq s\right\} + P\{A_\tau > s\}\right) dH(s) \end{aligned}$$

since $s \mapsto H(s)$ is increasing and continuous. Consider the stopping times

$$(2.8) \quad \begin{aligned} \tau_1 &= \inf \{ t \geq 0 \mid Z_t \geq s \} \\ \tau_2 &= \inf \{ t \geq 0 \mid A_t \geq s \} . \end{aligned}$$

Then Markov's inequality and (2.4) imply:

$$(2.9) \quad \begin{aligned} P\left\{\sup_{0 \leq t \leq \tau} Z_t \geq s, A_\tau \leq s\right\} &\leq P\left\{\tau_1 \leq \tau, \tau_2 \geq \tau\right\} \leq P\left\{Z_{\tau_1 \wedge \tau_2 \wedge \tau} \geq s\right\} \\ &\leq \frac{1}{s} E(A_{\tau_1 \wedge \tau_2 \wedge \tau}) \end{aligned}$$

whenever τ is bounded. From (2.7) and (2.9) we conclude:

$$(2.10) \quad \begin{aligned} E\left(\sup_{0 \leq t \leq \tau} H(Z_t)\right) &\leq \int_0^\infty \left(\frac{1}{s} E\left(A_\tau 1_{\{A_\tau \leq s\}}\right) + 2P\{A_\tau > s\}\right) dH(s) \\ &= E\left(A_\tau \int_{A_\tau}^\infty \frac{1}{s} dH(s)\right) + 2E\left(H(A_\tau)\right) = E\left(\tilde{H}(A_\tau)\right) \end{aligned}$$

for all bounded τ . Finally, observe that $x \mapsto \tilde{H}(x)$ is increasing, and pass to the limit when $k \rightarrow \infty$ to reach any τ through bounded ones $\tau \wedge k$. This completes the proof of the lemma. \square

From (1.3) and (1.4) above we know that the process X can be realised as $X_t = |\beta_t|$ where $\beta = (\beta_t)_{t \geq 0}$ solves the equation:

$$(2.11) \quad d\beta_t = -\mu \operatorname{sign}(\beta_t) dt + dB_t$$

with $\beta_0 = 0$. The infinitesimal operator \mathbb{L}_X of X is given by (1.1) with $\lambda = -\mu$.

Extend the map F_μ from (2.1) to \mathbb{R}_- by setting $F_\mu(x) = F_\mu(-x)$ for $x < 0$. Note that $x \mapsto F_\mu(x)$ is even and satisfies $\mathbb{L}_X(F_\mu) = 1$ on \mathbb{R} with $F_\mu(0) = 0$. Moreover, since $x \mapsto F_\mu(x)$ is C^2 , Itô formula can be applied to $F_\mu(\beta_t)$ and this yields:

$$(2.12) \quad F_\mu(X_t) = F_\mu(|\beta_t|) = F_\mu(\beta_t) = \int_0^t \left(\mathbb{L}_X(F_\mu) \right)(\beta_s) ds + \int_0^t F'_\mu(\beta_s) dB_s = t + M_t$$

where $M = (M_t)_{t \geq 0}$ is a continuous local martingale given by $M_t = \int_0^t F'_\mu(\beta_s) dB_s$.

Let τ be a bounded stopping time such that $(F_\mu(X_{t \wedge \tau}))_{t \geq 0}$ is bounded. Passing to a localising sequence of stopping times for M if needed, we find from (2.12) that

$$(2.13) \quad E\left(F_\mu(X_\tau)\right) = E(\tau)$$

by means of the optional sampling theorem (see e.g. [7]).

Elementary calculations based on the L'Hospital rule show that

$$(2.14) \quad \sup_{x > 0} \left(\frac{x}{H_\mu(x)} \int_x^\infty \frac{dH_\mu(s)}{s} \right) = 1$$

for all $\mu > 0$. By definition (2.6) this fact implies that

$$(2.15) \quad \tilde{H}_\mu(x) \leq 3 H_\mu(x)$$

for all $x \geq 0$. It enables us to conclude the proof in two steps as follows.

Setting $Z_t = F_\mu(X_t)$ and $A_t = t$ we easily see by (2.13) that all hypotheses in Lemma 2.2 are satisfied, and thus by (2.5) and (2.15) we find:

$$(2.16) \quad E\left(\max_{0 \leq t \leq \tau} X_t\right) = E\left(\max_{0 \leq t \leq \tau} H_\mu(Z_t)\right) \leq E\left(\tilde{H}_\mu(A_\tau)\right) \leq 3 E\left(H_\mu(A_\tau)\right) = 3 E\left(H_\mu(\tau)\right)$$

for all stopping times τ of X . This establishes the right-hand side inequality in (2.3).

On the other hand, setting $Z_t = t$ and $A_t = \max_{0 \leq s \leq t} F_\mu(X_s)$ we again see easily by (2.13) that all hypotheses in Lemma 2.2 are satisfied, and thus by (2.5) and (2.15) we find:

$$(2.17) \quad E\left(H_\mu(\tau)\right) = E\left(\max_{0 \leq t \leq \tau} H_\mu(Z_t)\right) \leq E\left(\tilde{H}_\mu(A_\tau)\right) \leq 3 E\left(H_\mu(A_\tau)\right) = 3 E\left(\max_{0 \leq t \leq \tau} X_t\right)$$

for all stopping times τ of X . This establishes the left-hand side inequality in (2.3), and the proof of the theorem is complete. \square

Remarks 2.3

1. It is easily seen that $x \mapsto F_\mu(x)$ is convex on \mathbb{R}_+ , and thus $x \mapsto H_\mu(x)$ is concave on \mathbb{R}_+ . Hence applying Jensen's inequality in (2.3) we obtain:

$$(2.18) \quad E\left(\max_{0 \leq t \leq \tau} X_t\right) \leq c_2 H_\mu\left(E(\tau)\right)$$

for all stopping times τ of X .

2. Recalling further (2.13) we see that (2.18) implies the following Doob-type bound:

$$(2.19) \quad E\left(\max_{0 \leq t \leq \tau} X_t\right) \leq c_2 H_\mu\left(E(F_\mu(X_\tau))\right)$$

which is valid for all stopping times τ of X such that $E(\tau) < \infty$.

3. It is easily verified that $F_\mu(x) \rightarrow x^2$ as $\mu \downarrow 0$, and thus

$$(2.20) \quad \lim_{\mu \downarrow 0} H_\mu(x) = \sqrt{x}$$

for all $x \geq 0$. Passing to the limit in (2.3) when $\mu \downarrow 0$ we thus recover (1.5). In exactly the same way we see that (2.18) implies (1.6) with the constant $c_2 = 3$ on the right-hand side.

4. Using that $(2\mu x)^k / (2\mu^2 k!) \leq F_\mu(x) \leq (e^{2\mu x} - 1) / (2\mu^2)$ we find easily that

$$(2.21) \quad \frac{1}{2\mu} \log(1 + 2\mu^2 x) \leq H_\mu(x) \leq \frac{k/2}{(2\mu)^{1-2/k}} x^{1/k}$$

for all $x \geq 0$ and all $k \geq 2$. The left-hand side estimate in (2.21) is more accurate for large x , and the right-hand side estimate in (2.21) is more accurate for small x .

2. We turn to establishing an analogue of the Doob-type inequality (1.6). Note that although (2.18) above provides such a bound, it fails to capture (1.6) with the best constant $\sqrt{2}$ in the limit when $\mu \downarrow 0$. In the following theorem we present a result which repairs this deficiency.

Theorem 2.4

1. Let $X = (X_t)_{t \geq 0}$ be a reflected Brownian motion with drift $-\mu$ such that $X_0 = 0$ where $\mu > 0$ is given and fixed. Then the following inequality is satisfied:

$$(2.22) \quad E\left(\max_{0 \leq t \leq \tau} X_t\right) \leq \inf_{c > 0} \left(c E(\tau) + \frac{1}{2\mu} \log\left(1 + \frac{\mu}{c}\right) \right)$$

for all stopping times τ of X .

Moreover, the following inequalities are satisfied:

$$(2.23) \quad E\left(\max_{0 \leq t \leq \tau} X_t\right) \leq \sqrt{\frac{1}{2} E(\tau)} + \frac{1}{2\mu} \log\left(1 + \mu \sqrt{2E(\tau)}\right)$$

$$(2.24) \quad E\left(\max_{0 \leq t \leq \tau} X_t\right) \leq \frac{1}{2\mu} \left(1 + \log\left(1 + 2\mu^2 E(\tau)\right) \right)$$

for all stopping times τ of X . The inequality (2.23) is more accurate for small μ (letting $\mu \downarrow 0$ in (2.23) we obtain (1.6)), and the inequality (2.24) is more accurate for large μ (letting $\mu \downarrow 0$ in (2.24) the right-hand side tends to zero).

Proof. We shall only sketch the main points in the proof, and for remaining details and more information we shall refer to [2] (Theorem 3) and [6] (Corollary 3.2)

From (1.3) and (1.4) above we know that the process X can be realised as $X_t = |\beta_t|$ where $\beta = (\beta_t)_{t \geq 0}$ solves (2.11) with $\beta_0 = x \geq 0$. Set $S_t = (\max_{0 \leq r \leq t} X_r) \vee s$ for $s \geq x$ and consider the optimal stopping problem:

$$(2.25) \quad V_*(x, s) = \sup_{\tau} E_{x,s} (S_{\tau} - c\tau)$$

where $X_0 = x$ and $S_0 = 0$ under $P_{x,s}$. The supremum in (2.25) is taken over all stopping times τ of X satisfying $E_{x,s}(\tau) < \infty$, and the constant $c > 0$ is given and fixed.

This problem belongs to the general theory of optimal stopping for Markov processes that leads to the following *free-boundary* problem:

$$(2.26) \quad (\mathbb{L}_X V_*)(x, s) = c \quad (g_*(s) < x < s)$$

$$(2.27) \quad \left. \frac{\partial V_*}{\partial s}(x, s) \right|_{x=s-} = 0 \quad (\text{normal reflection})$$

$$(2.28) \quad V_*(x, s) \Big|_{x=g_*(s)+} = s \quad (\text{instantaneous stopping})$$

$$(2.29) \quad \left. \frac{\partial V_*}{\partial x}(x, s) \right|_{x=g_*(s)+} = 0 \quad (\text{smooth fit})$$

where $s \mapsto g_*(s)$ is an optimal stopping boundary (to be found). Since X is a non-negative diffusion and 0 is an instantaneously-reflecting (regular) boundary point for X , the following stopping time is to be optimal in (2.25):

$$(2.30) \quad \tau_* = \inf \{ t > 0 \mid S_t \geq s_*, X_t \leq g_*(S_t) \}$$

where $s_* \geq 0$ satisfies $g_*(s_*) = 0$.

The solution of (2.26)-(2.29) is given by

$$(2.31) \quad V_*(x, s) = s + c \int_{g_*(s)}^x (L(x) - L(y)) m(dy)$$

for $0 \leq g_*(s) \leq x \leq s$, where the optimal boundary $s \mapsto g_*(s)$ is the *maximal* solution of the first-order (nonlinear) differential equation:

$$(2.32) \quad g'(s) = \frac{L'(g(s))}{2c(L(s) - L(g(s)))}$$

staying strictly below the diagonal in \mathbb{R}_+^2 . In (2.31) and (2.32) we set $L = L(x)$ denote the *scale function* of X , and $m = m(dx)$ denotes the *speed measure* of X . From (2.11) we read that

$$(2.33) \quad L(x) = \frac{e^{2\mu x} - 1}{2\mu} \quad (x \geq 0)$$

$$(2.34) \quad m(dx) = 2 e^{-2\mu x} dx .$$

A strong Markov property implies that $V_*(x, s) = V_*(s_*, s_*) - c E_{x,s}(\tau_{s_*})$ for $0 \leq x \leq s \leq s_*$, where $\tau_{s_*} = \inf \{ t > 0 \mid X_t = s_* \}$, and this leads to the following explicit expression:

$$(2.35) \quad V_*(x, s) = s_* + c \int_0^x (L(x) - L(y)) m(dy)$$

for $0 \leq x \leq s \leq s_*$.

Inserting (2.33) into (2.32) we easily see that the linear function $g_*(s) = s - s_*$ is the maximal solution of (2.32), where $s_* > 0$ is explicitly given by

$$(2.36) \quad s_* = \frac{1}{2\mu} \log \left(1 + \frac{\mu}{c} \right).$$

Thus $g_*(s) = s - s_*$ is the optimal stopping boundary i.e. the stopping time (2.30) is optimal in (2.25), and from (2.35) we see that

$$(2.37) \quad V_*(0, 0) = s_*.$$

By means of (2.36) this fact establishes (2.22), and the first part of the proof is complete.

In order to derive the remaining statements, note first that for each stopping time τ of X such that $E(\tau) < \infty$, the infimum in (2.22) is attained at

$$(2.38) \quad c_* = c_*(\mu, E(\tau)) = -\frac{\mu}{2} + \sqrt{\frac{1}{2E(\tau)} + \mu^2}.$$

Inserting this expression into the right-hand side of (2.22) we obtain a sharp inequality (where equality is attained at the stopping time (2.30) for each $\mu > 0$ given and fixed). Moreover, letting $\mu \downarrow 0$ in this inequality we obtain (1.6) with $\sqrt{2}$ on the right-hand side.

Unfortunately, the right-hand side of the inequality obtained by inserting (2.37) into (2.22) defines a complicated function of $E(\tau)$. Its simplification can be achieved upon observing that

$$(2.39) \quad c_*(\mu, E(\tau)) \rightarrow \frac{1}{\sqrt{2E(\tau)}} \quad (\mu \downarrow 0)$$

$$(2.40) \quad \mu c_*(\mu, E(\tau)) \rightarrow \frac{1}{2E(\tau)} \quad (\mu \uparrow \infty).$$

These facts indicate that letting $c = 1/\sqrt{2E(\tau)}$ in (2.22) we get an inequality precise for small μ , and letting $c = 1/(2\mu E(\tau))$ in (2.22) we obtain an inequality precise for large μ . As these two inequalities are just those written in (2.23) and (2.24) respectively, the proof is complete. \square

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