

7 Diagonalization and Quadratic Forms

Diagonalization

Recall the definition of a **diagonal** matrix from Section 1.6.

Definition 7.1. A square matrix A is **diagonalizable** if there exists an invertible matrix P such that $P^{-1}AP$ is diagonal. We say that P **diagonalizes** A .

Remark. Why is this interesting? For many applications we need to compute **powers** of matrices, for example

$$A^7 = AAAAAAA.$$

To do this by direct calculation is a lot of work, but if A is diagonalizable, say $P^{-1}AP = D$ diagonal, then $A = PDP^{-1}$ so

$$A^7 = (PDP^{-1})(PDP^{-1})(PDP^{-1})(PDP^{-1})(PDP^{-1})(PDP^{-1})(PDP^{-1}) = PD^7P^{-1}.$$

and more generally, $A^k = PD^kP^{-1}$ for all k . We have seen in Exercise Sheet 5 that D^k is easy to compute, so this gives a much easier way to work out A^k for large k .

Examples 7.2. Consider

$$A = \begin{pmatrix} 0 & 0 & -2 \\ 1 & 2 & 1 \\ 1 & 0 & 3 \end{pmatrix}, P = \begin{pmatrix} -1 & 0 & -2 \\ 0 & 1 & 1 \\ 1 & 0 & 1 \end{pmatrix}, P^{-1} = \begin{pmatrix} 1 & 0 & 2 \\ 1 & 1 & 1 \\ -1 & 0 & -1 \end{pmatrix}.$$

Then we can check that

$$P^{-1}AP = \begin{pmatrix} 2 & 0 & 0 \\ 0 & 2 & 0 \\ 0 & 0 & 1 \end{pmatrix} =: D,$$

so A is diagonalizable. Now for any m we have

$$A^m = PD^mP^{-1} = P \begin{pmatrix} 2^m & 0 & 0 \\ 0 & 2^m & 0 \\ 0 & 0 & 1^m \end{pmatrix} P^{-1}$$

so to calculate A^m we need only calculate the scalar power 2^m and then perform two matrix multiplications.

Exercise. With A as above, work out A^{16} . Then try and do it directly without the “diagonalization”!

Given that diagonalizing a matrix is so useful, it is natural to ask which matrices can be diagonalized. To answer this question we will need a lemma giving yet another characterisation of invertible matrices.

Lemma 7.3. *Let P be an $n \times n$ square matrix. Then P is invertible if and only if its columns (viewed as column n -vectors) form a set of n linearly independent vectors.*

Proof. See Section 14. □

Theorem 7.4. *Let A be an $n \times n$ matrix. Then A is diagonalizable if and only if A has n linearly independent eigenvectors. A matrix P diagonalizes A if and only if P 's columns form a set of n linearly independent eigenvectors for A . If it does, then the main diagonal entries of the diagonal matrix $P^{-1}AP$ are the eigenvalues of A (in the order corresponding to the columns of P).*

Proof. Suppose $P^{-1}AP = D$ is diagonal. Let $c_1, \dots, c_n$ be the columns of P . By Lemma 7.3, the columns are linearly independent. Now $P^{-1}AP = D$ implies

$$AP = PD.$$

It follows from the definition of matrix multiplication that (i) the i th column of PD is $D_{ii}c_i$ and (ii) the i th column of $AP = Ac_i$. Thus we have $Ac_i = D_{ii}c_i$, so each column c_i is an eigenvector of A corresponding to the eigenvalue D_{ii} .

Conversely, if A has n linearly independent eigenvectors $c_1, \dots, c_n$ then let P be the matrix with these as columns, and D the diagonal matrix with the corresponding eigenvalues on the main diagonal. By Lemma 7.3, P is invertible. Now reversing the argument above, the i th column of AP is Ac_i and the i th column of PD is $D_{ii}c_i$ so $AP = PD$, so $P^{-1}AP = D$. □

Example 7.5. Let

$$A = \begin{pmatrix} 3 & 0 \\ 8 & -1 \end{pmatrix}, u = \begin{pmatrix} 1 \\ 2 \end{pmatrix} \text{ and } v = \begin{pmatrix} 0 \\ 1 \end{pmatrix}.$$

Then A has eigenvalues 3 and -1 , with corresponding eigenvectors u and v respectively (**exercise: check this**). It is easy to check that $\{u, v\}$ is linearly independent. If we let P be the matrix whose columns are u and v ,

$$P = \begin{pmatrix} 1 & 0 \\ 2 & 1 \end{pmatrix}, \text{ then } P^{-1} = \begin{pmatrix} 1 & 0 \\ -2 & 1 \end{pmatrix}$$

and one can check (**exercise**) that

$$P^{-1}AP = \begin{pmatrix} 3 & 0 \\ 0 & -1 \end{pmatrix}.$$

Definition 7.6. An $n \times n$ matrix A is called **orthogonally diagonalizable** if there is an **orthogonal** matrix P such that $P^{-1}AP = P^TAP$ is diagonal.

Theorem 7.7. Let A be an $n \times n$ matrix. Then the following are equivalent:

- (i) A is orthogonally diagonalizable.
- (ii) A has an orthonormal set of n eigenvectors;
- (iii) A is symmetric.

Proof. (i) $\Leftrightarrow$ (ii) This follows from Theorems 6.6, 6.8 and 7.4 (**exercise: write down exactly how**).

(i) $\Rightarrow$ (iii) If (i) holds, say $P^{-1}AP = D$ is diagonal with P orthogonal, then we have $A = PDP^{-1} = PDP^T$. Clearly D is symmetric, so

$$A^T = (PDP^T)^T = (P^T)^T D^T P^T = PDP^T = A$$

which means that A is symmetric.

(iii) $\Rightarrow$ (ii) Omitted (see for example the textbook of Anton). □

Quadratic Forms

Definition 7.8. A quadratic form in n variables is a function $f : \mathbb{R}^n \rightarrow \mathbb{R}$ of the form

$$f(x) = f(x_1, \dots, x_n) = \sum_{1 \leq i \leq j \leq n} c_{ij} x_i x_j \quad (*)$$

where $x \in \mathbb{R}^n$ and $c_{ij} \in \mathbb{R}$ ($1 \leq i \leq j \leq n$). Alternatively, a quadratic form is a homogeneous polynomial of degree 2 in n variables $x_1, \dots, x_n$.

Examples 7.9. The following are quadratic forms:

1. $f(x_1) = x_1^2$
2. $f(x_1, x_2) = 2x_1^2 + 3x_2^2 - x_1x_2$
3. $f(x_1, x_2, x_3) = x_1^2 + x_2^2 + x_3^2 - 2x_1x_2 - 2x_1x_3 - 2x_2x_3$

4. $f(x_1, \dots, x_n) = x_1^2 + x_2^2 + \dots + x_n^2 = \langle v|v \rangle$, where $v = (x_1, \dots, x_n)$. So the Euclidean inner product (see Chapter 6) gives rise to a quadratic form.

If we set $a_{ii} = c_{ii}$ for $i = 1, \dots, n$ and $a_{ij} = \frac{1}{2}c_{ij}$ for $1 \leq i < j \leq n$, then (*) becomes

$$f(x) = \sum_{i=1}^n a_{ii}x_i^2 + \sum_{1 \leq i < j \leq n} 2a_{ij}x_i x_j$$

and we can write this as

$$f(x) = x^T A x$$

where A is the symmetric $n \times n$ matrix with (i, j) -th entry equal to a_{ij} . Then A is called the matrix of the quadratic form f .

Example 7.10. Let $f(x_1, x_2) = 2x_1^2 - 3x_2^2 - x_1x_2$. Then

$$f(x_1, x_2) = \begin{pmatrix} x_1 & x_2 \end{pmatrix} \begin{pmatrix} 2 & -1/2 \\ -1/2 & -3 \end{pmatrix} \begin{pmatrix} x_1 \\ x_2 \end{pmatrix}.$$

Now that a symmetric matrix is involved, we can take advantage of Theorem 7.7.

ie. there exists an orthogonal matrix Q such that

$$Q^T A Q = D = \begin{pmatrix} \lambda_1 & \dots & 0 \\ \vdots & \ddots & \vdots \\ 0 & \dots & \lambda_n \end{pmatrix}$$

where D is a diagonal matrix and $\lambda_1, \dots, \lambda_n$ are the eigenvalues of A .

Now let $y = Q^{-1}x = Q^T x$. Then $x = Qy$ and

$$f(x) = (Qy)^T A (Qy) = y^T Q^T A Q y = y^T D y$$

and if $y = \begin{pmatrix} y_1 \\ \vdots \\ y_n \end{pmatrix}$ then

$$y^T D y = \lambda_1 y_1^2 + \dots + \lambda_n y_n^2,$$

a quadratic form in variables $y_1, \dots, y_n$ with no cross terms. This process is called **diagonalization** of the quadratic form f . We have just proved a famous theorem, namely

Theorem 7.11. (*The Principal Axes Theorem*) Every quadratic form f can be diagonalized. More specifically, if $f(x) = x^T A x$ is a quadratic form in $x = \begin{pmatrix} x_1 \\ \vdots \\ x_n \end{pmatrix}$, then there exists an orthogonal matrix Q such that

$$f(x) = x^T A x = \lambda_1 y_1^2 + \dots + \lambda_n y_n^2$$

where $\begin{pmatrix} y_1 \\ \vdots \\ y_n \end{pmatrix} = Q^T \begin{pmatrix} x_1 \\ \vdots \\ x_n \end{pmatrix}$ and $\lambda_1, \dots, \lambda_n$ are the eigenvalues of the matrix A .

From the first part of the course we know that Q is the matrix whose columns are the **unit** eigenvectors of the matrix A of f .

Example 7.12. Let $f(x_1, x_2, x_3) = 2x_1x_2 + 2x_1x_3 + 2x_2x_3$. The matrix of f is

$$A = \begin{pmatrix} 0 & 1 & 1 \\ 1 & 0 & 1 \\ 1 & 1 & 0 \end{pmatrix}.$$

The eigenvalues of A are $2, -1, -1$ with corresponding unit eigenvectors

$$\begin{pmatrix} 1/\sqrt{3} \\ 1/\sqrt{3} \\ 1/\sqrt{3} \end{pmatrix}, \begin{pmatrix} -2/\sqrt{6} \\ 1/\sqrt{6} \\ 1/\sqrt{6} \end{pmatrix}, \begin{pmatrix} 0 \\ 1/\sqrt{2} \\ -1/\sqrt{2} \end{pmatrix}$$

and so we have

$$Q = \begin{pmatrix} 1/\sqrt{3} & -2/\sqrt{6} & 0 \\ 1/\sqrt{3} & 1/\sqrt{6} & 1/\sqrt{2} \\ 1/\sqrt{3} & 1/\sqrt{6} & -1/\sqrt{2} \end{pmatrix}.$$

If we set $y = Q^T x$, we get

$$y_1 = \frac{1}{\sqrt{3}}(x_1 + x_2 + x_3), y_2 = \frac{1}{\sqrt{6}}(-2x_1 + x_2 + x_3), y_3 = \frac{1}{\sqrt{2}}(x_2 - x_3).$$

Then, expressed in terms of the variables y_1, y_2 and y_3 , the quadratic form becomes $2y_1^2 - y_2^2 - y_3^2$.

Definition 7.13. A quadratic form $f : \mathbb{R}^n \rightarrow \mathbb{R}$ is **positive definite** if $f(x) > 0$ for all $x \neq \underline{0}$.

An immediate consequence of the Principal Axes Theorem is the following:

Theorem 7.14. *Let $f(x) = x^T Ax$ be a quadratic form with matrix A . Then f is positive definite if and only if all the eigenvalues of A are positive.*

Proof. By the Principal Axes Theorem, there exists an orthogonal matrix Q such that

$$f(x) = \lambda_1 y_1^2 + \dots + \lambda_n y_n^2$$

where $y = \begin{pmatrix} y_1 \\ \vdots \\ y_n \end{pmatrix} = Q^T x$ and $\lambda_1, \dots, \lambda_n$ are the eigenvalues of A . If all the λ_i are positive then $f(x) > 0$ except when $y = \underline{0}$. But this happens if and only if $x = \underline{0}$ because Q^T is invertible. Therefore f is positive definite.

On the other hand if one of the eigenvalues $\lambda_i \leq 0$, letting $y = e_i$ and $x = Qy$ we get $f(x) = \lambda_i \leq 0$ and so f is not positive definite. $\square$

We say that a symmetric matrix A is **positive definite** if the associated quadratic form

$$f(x) = x^T Ax$$

is positive definite.

The Principal Axes Theorem has important applications in geometry.