

Two hours

**THE UNIVERSITY OF MANCHESTER**

ELASTICITY

20 January 2015

14:00 – 16:00

Answer **ALL FIVE** questions.

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Electronic calculators may be used, provided that they cannot store text.

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1. An undeformed three-dimensional elastic body is a circular cylinder of radius 1 and length 2, whose axis is aligned with the  $x_3$ -axis of a Cartesian coordinate system. The base of the cylinder lies in the plane  $x_3 = 0$ . The body is subjected to the displacement field  $(u_1, u_2, u_3)$  where

$$u_1 = \epsilon 2x_1x_3, \quad u_2 = \epsilon 2x_2x_3, \quad u_3 = -\epsilon (x_1^2 + x_2^2),$$

and  $\epsilon$  is a small positive constant.

- (i) Write down the expression for the deformed position  $X_i$  and hence sketch the undeformed and deformed configurations in the plane  $x_2 = 0$ . Is the deformation axisymmetric?
- (ii) Determine the strain tensor  $e_{ij}$  and rotation tensor  $\omega_{ij}$  corresponding to this displacement field.
- (iii) Find the principal strains and principal axes of strain and hence describe the deformation.

[16 marks]

2.

- (i) Show that

$$\Phi(x, y) = -Fxy^2(3 - 2y),$$

is a valid Airy stress function, where  $F$  is a positive constant and  $x$  and  $y$  are Cartesian coordinates.

- (ii) If  $\Phi$  describes the stress field within an elastic body occupying the domain  $y \in [0, 1]$  and  $x \in [0, 1]$ , find the corresponding tractions on boundaries of the domain.
- (iii) Sketch the loads on each boundary and give a physical interpretation of the loading.

[12 marks]

3. A three-dimensional elastic body in a state of plane stress has

$$\tau_{11} = ax_1, \quad \tau_{12} = \tau_{21} = b, \quad \tau_{22} = c \sin x_2,$$

where  $a$ ,  $b$  and  $c$  are constants and all other components of the stress tensor,  $\tau_{ij}$ , are zero.

- (i) Assuming that the body is in equilibrium, use Cauchy's equation

$$\tau_{ij,j} + F_i = 0,$$

to find components of the body force per unit volume,  $\mathbf{F}$ .

- (ii) The constitutive law for a homogeneous, linearly elastic material is

$$\tau_{ij} = \lambda \delta_{ij} e_{kk} + 2\mu e_{ij},$$

where  $\lambda$  and  $\mu$  are the Lamé coefficients. Use the constitutive law to find all components of the strain tensor  $e_{ij}$  corresponding to the given stress field.

- (iii) Explain why the body is not in a state of plane strain.

[12 marks]

4. A uniform elastic cylinder of elliptical cross-section has its axis aligned with the  $z$ -axis of a Cartesian coordinate system  $(x, y, z)$ . The displacement vector in the Cartesian coordinate system is given by the components  $(u, v, w)$  and the cylinder is twisted such that

$$u = -\theta zy, \quad v = \theta zx, \quad w = \theta\psi(x, y),$$

where  $\theta$  is a given constant and  $\psi(x, y)$  is an unknown function. There are no body forces acting.

- (i) Find the strain tensor corresponding to the given deformation.  
(ii) Find the corresponding stress tensor, assuming that the body is linearly elastic:

$$\tau_{ij} = \lambda\delta_{ij}e_{kk} + 2\mu e_{ij},$$

where  $\mu$  and  $\lambda$  are the Lamé coefficients.

- (iii) Show that the equations of equilibrium,  $\tau_{ij,j} + F_i = 0$ , are satisfied by the introduction of a stress function,  $\phi(x, y)$ , where

$$\tau_{xz} = \frac{\partial\phi}{\partial y}, \quad \tau_{yz} = -\frac{\partial\phi}{\partial x};$$

and use the results from (ii) to show that

$$\nabla^2\phi = -2\mu\theta. \tag{1}$$

- (iv) Explain why a traction-free boundary condition on the side of the cylinder is given by

$$\frac{d\phi}{ds} = 0,$$

where  $s$  is an arclength coordinate around the perimeter of the cylinder's cross-section.

- (v) If the boundary of the elliptical cross-section is given by the equation  $(x/a)^2 + (y/b)^2 = 1$ , where  $a > b > 0$ , show that

$$\phi = C \left( \frac{x^2}{a^2} + \frac{y^2}{b^2} - 1 \right),$$

satisfies the traction-free boundary condition and the equation (1) for a particular value of  $C$ , which is to be found.

- (vi) Find the location and value of the maximum absolute stress exerted on the cylinder.

[20 marks]

5. An infinite linear elastic body with Lamé coefficients  $\lambda$  and  $\mu$  contains a spherical hole of undeformed radius  $a$ . The hole has an internal pressure given by  $p = p_0$ .

(i) Explain why the displacement field may be assumed to be of the form

$$\mathbf{u} = u_\rho(\rho) \hat{\rho},$$

where  $\rho$  is the distance from the centre of the hole; and  $\hat{\rho}$  is a unit vector directed away from the centre of the hole.

(ii) Solve the Navier–Lamé equations, in the usual notation,

$$(\lambda + 2\mu)\nabla(\nabla \cdot \mathbf{u}) - \mu\nabla \times \nabla \times \mathbf{u} + \mathbf{F} = \mathbf{0},$$

stating any boundary conditions clearly, to find the solution for  $u_\rho(\rho)$  in terms of the Lamé constants  $\lambda$ ,  $\mu$  and the values  $p_0$  and  $a$ .

(iii) Another infinite body of the same material contains a cylindrical hole of infinite length that is also of radius  $a$  and loaded by internal pressure  $p_0$ . Determine whether the cylindrical or spherical hole has a greater deformed radius.

(iv) If instead the undeformed cylinder radius is  $\alpha a$ , find the value of  $\alpha$  such that the deformed cylinder and sphere have the same radius.

[20 marks]

You may use the results that in spherical polar coordinates  $(\rho, \vartheta, \phi)$

$$\begin{aligned} \text{grad } f &= \frac{\partial f}{\partial \rho} \hat{\rho} + \frac{1}{\rho} \frac{\partial f}{\partial \vartheta} \hat{\vartheta} + \frac{1}{\rho \sin \vartheta} \frac{\partial f}{\partial \phi} \hat{\phi}, \\ \text{div } \mathbf{u} &= \frac{1}{\rho^2 \sin \vartheta} \left\{ \frac{\partial}{\partial \rho} (\rho^2 \sin \vartheta u_\rho) + \frac{\partial}{\partial \vartheta} (\rho \sin \vartheta u_\vartheta) + \frac{\partial}{\partial \phi} (\rho u_\phi) \right\}, \\ \text{curl } \mathbf{u} &= \frac{1}{\rho \sin \vartheta} \left[ \frac{\partial}{\partial \vartheta} (u_\phi \sin \vartheta) - \frac{\partial u_\vartheta}{\partial \phi} \right] \hat{\mathbf{r}} + \frac{1}{\rho} \left[ \frac{1}{\sin \vartheta} \frac{\partial u_\rho}{\partial \phi} - \frac{\partial}{\partial \rho} (\rho u_\phi) \right] \hat{\vartheta} + \frac{1}{\rho} \left[ \frac{\partial}{\partial \rho} (\rho u_\vartheta) - \frac{\partial u_\rho}{\partial \vartheta} \right] \hat{\phi}. \\ \tau_{\rho\rho} &= \lambda \text{div } \mathbf{u} + 2\mu \frac{\partial u_\rho}{\partial \rho}. \end{aligned}$$

In cylindrical polar coordinates  $(r, \theta, z)$

$$\begin{aligned} \text{grad } f &= \frac{\partial f}{\partial r} \hat{\mathbf{r}} + \frac{1}{r} \frac{\partial f}{\partial \theta} \hat{\boldsymbol{\theta}} + \frac{\partial f}{\partial z} \hat{\mathbf{z}}, & \text{div } \mathbf{u} &= \frac{1}{r} \frac{\partial (ru_r)}{\partial r} + \frac{1}{r} \frac{\partial u_\theta}{\partial \theta} + \frac{\partial u_z}{\partial z}, \\ \text{curl } \mathbf{u} &= \left( \frac{1}{r} \frac{\partial u_z}{\partial \theta} - \frac{\partial u_\theta}{\partial z} \right) \hat{\mathbf{r}} + \left( \frac{\partial u_r}{\partial z} - \frac{\partial u_z}{\partial r} \right) \hat{\boldsymbol{\theta}} + \left( \frac{1}{r} \frac{\partial (ru_\theta)}{\partial r} - \frac{1}{r} \frac{\partial u_r}{\partial \theta} \right) \hat{\mathbf{z}}. \\ \tau_{rr} &= \lambda \text{div } \mathbf{u} + 2\mu \frac{\partial u_r}{\partial r}, & \tau_{\theta\theta} &= \lambda \text{div } \mathbf{u} + 2\mu \left( \frac{1}{r} \frac{\partial u_\theta}{\partial \theta} + \frac{u_r}{r} \right), & \tau_{zz} &= \lambda \text{div } \mathbf{u} + 2\mu \frac{\partial u_z}{\partial z}, \\ \frac{\tau_{r\theta}}{\mu} &= \frac{\tau_{\theta r}}{\mu} = \frac{\partial u_\theta}{\partial r} - \frac{u_\theta}{r} + \frac{1}{r} \frac{\partial u_r}{\partial \theta}, & \frac{\tau_{rz}}{\mu} &= \frac{\tau_{zr}}{\mu} = \frac{\partial u_z}{\partial r} + \frac{\partial u_r}{\partial z}, & \frac{\tau_{\theta z}}{\mu} &= \frac{\tau_{z\theta}}{\mu} = \frac{1}{r} \frac{\partial u_z}{\partial \theta} + \frac{\partial u_\theta}{\partial z}. \end{aligned}$$

**END OF EXAMINATION PAPER**